# New Upper and Lower bounds for Entanglement Testing

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Motivations Related Work Main Result

### **Entanglement Detection**

#### **Definition (Separable and Entangled States)**

A bi-partitie state  $\rho \in D(\mathcal{X} \otimes \mathcal{Y})$  is *separable* if  $\exists$  dist.  $\{p_i\}$ ,

$$\rho = \sum \boldsymbol{p}_{i} \sigma_{\boldsymbol{X}}^{i} \otimes \sigma_{\boldsymbol{Y}}^{i}, \text{ s.t. } \sigma_{\boldsymbol{X}}^{i} \in \mathrm{D}\left(\boldsymbol{\mathcal{X}}\right), \sigma_{\boldsymbol{Y}}^{i} \in \mathrm{D}\left(\boldsymbol{\mathcal{Y}}\right).$$

Otherwise,  $\rho$  is *entangled*. Let Sep  $\stackrel{\text{def}}{=} \{$  separable states  $\}$ .

#### Definition (Entanglement Detection)

A KEY problem: given the description of  $\rho \in D(\mathcal{X} \otimes \mathcal{Y})$ , decide

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Otherwise,  $\rho$  is *entangled*. Let Sep  $\stackrel{\text{def}}{=}$  { separable states }.

#### **Definition (Entanglement Detection)**

A KEY problem: given the description of  $\rho \in D(\mathcal{X} \otimes \mathcal{Y})$ , decide Either  $\rho \in$  Sep, or  $\rho$  is far away from Sep.

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# **Alternative Formulation**

#### **Definition (Weak Membership)**

 $WMem(\epsilon, \|\cdot\|)$ : for any  $\rho \in D(\mathcal{X} \otimes \mathcal{Y})$ , decide either  $\rho \in Sep$  or  $\|\rho - Sep\| \ge \epsilon$ .

Via standard techniques in convex optimization, equivalent to

**Definition (Weak Optimization)** 

WOpt( $M, \epsilon$ ) : for any  $M \in \text{Herm}(\mathcal{X} \otimes \mathcal{Y})$ , estimate the value of

 $\max_{\rho \in \mathsf{Sep}} \langle \boldsymbol{M}, \rho \rangle \,,$ 

with additive error  $\epsilon$ .

From now on, we focus on WOpt( $M, \epsilon$ ).

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### The Problem: alternative formulation

Recall that  $h_{\text{Sep}(d)}(M)$  refers to

$$\max \langle \mathbf{M}, \rho \rangle \text{ s.t. } \rho \in \text{Sep}(\mathcal{X} \otimes \mathcal{Y}).$$

For any  $M \in \mathbb{C}^{d \times d}$ , there exists  $M' \in \mathbb{C}^{2d \times 2d}$  s.t.

$$h_{\operatorname{ProdSym}(2d)}(M') = rac{1}{4}h_{\operatorname{Sep}(d)}(M),$$

where  $\operatorname{ProdSym}(d, k) := \operatorname{conv}\{(|\psi\rangle \langle \psi|)^{\otimes 2} : |\psi\rangle \in B(\mathbb{C}^d)\}.$ [HM]

REDUCE our problem to the mathematically simpler h<sub>ProdSym(d)</sub>.

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# Reduce *h*<sub>ProdSym(*d*)</sub> further

Let  $|\psi\rangle = \sum_{i=1}^{d} a_i |i\rangle$  such that  $\forall i, a_i \in \mathbb{C}$  and  $\sum_i |a_i|^2 = 1$ . It is easy to see that  $h_{\text{ProdSym}(d)}$  is equivalent to

$$\max_{a \in \mathbb{C}^d} \sum_{i_1, i_2, j_1, j_2} M_{(i_1, i_2), (j_1, j_2)} a_{i_1}^* a_{i_2}^* a_{j_1} a_{j_2}$$
(1) subject to  $||a||^2 = 1.$ 

Now reduce from  $\mathbb{C}$  to  $\mathbb{R}$  by observing:

- *M* is a Hermitian so the objective function is real.
- Decomposing the complex number into real and imaginary parts.

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# *h*ProdSym(*n*) with real variables

By renaming, we arrive at the  $h_{ProdSym(n)}$  with real variables:

$$\max_{x \in \mathbb{R}^n} f_0(x) = \sum_{i_1, i_2, j_1, j_2} M_{(i_1, i_2), (j_1, j_2)} x_{i_1} x_{i_2} x_{j_1} x_{j_2}$$
subject to  $f_1(x) = ||x||^2 - 1 = 0.$ 
(2)

**REMARK**: this is an instance of *polynomial optimization* problems with a homogenous degree 4 objective polynomial and a degree 2 constraint polynomial.

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# Connections

### **Quantum Information:**

- Ground energy that is achieved by *non-entangled* states.
- Mean-field approximation in statistical quantum mechanics.
- Positivity test of quantum channels.
- 17 more examples in quantum information in [HM10].

### **Quantum Complexity:**

• Quantum Merlin-Arthur Game with Two-Provers (QMA(2)).

### **Classical Complexity:**

• Unique Game Conjecture and Small-set Expansion.  $(\ell_2 \rightarrow \ell_4 \text{ norm})$ 

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# **Early Attempts**

### Separability Criterions:

- Positive Partial Transpose (PPT) :  $\rho^{T_{\mathcal{Y}}} = \rho$ ? [PH]
- Reduction Criterions:  $I_{\mathcal{X}} \otimes \rho_Y \ge \rho$ ? [HH]
- • • • •
- FAILURE: any such test has arbitrarily large error. [BS]

#### Doherty-Parrilo-Spedalieri (DPS) hierarchy:

- $\rho$  is *k*-extendible if  $\exists$  symmetric  $\sigma \in D(\mathcal{X} \otimes \mathcal{Y}_1 \otimes \cdots \otimes \mathcal{Y}_k)$ ,  $\forall i, \rho = \sigma_{XY_i}$ .
- $\phi \in \mathrm{Sep}$  if and only if  $\rho$  is to extend ble for any  $k \geq 0.1$

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### Hardness

Let  $h_{\text{Sep}(d)}(M)$  denote the value of

 $\max \langle \mathbf{M}, \rho \rangle$  s.t.  $\rho \in D(\mathcal{X} \otimes \mathcal{Y})$  is *separable*,

where *d* refers to the dimension of  $\mathcal{X} \otimes \mathcal{Y}$ .

#### Hardness

NP-hard to approximate h<sub>Sep(d)</sub>(M) with additive error ε = 1/poly(d). [Gur03,loa07,Gha10], [deK08, LONY09].
 Assuming Exponential Time Hypothesis (ETH), for constant ε, approximate h<sub>Sep(d)</sub>(M) needs d<sup>Ω(log(d))</sup> time. via the connection to QMA(2). [HM, AB+]

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# **Upper bounds**

#### When $\epsilon = 1/poly(d)$

• DPS to  $O(d/\sqrt{\epsilon})$  level: time  $(d/\sqrt{\epsilon})^{O(d)} \rightarrow d^{O(d)}$ . [NOP]

• Epsilon-net (brute-force): time  $(1/\epsilon)^{O(d)} 
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#### When $\epsilon = \text{const}$

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### Landscape

#### **Table:** Known results about approximating $h_{\text{Sep}(d)}$ to error $\epsilon$

Error $\epsilon$	Lower bounds	Upper b. (DPS)	Upper b. ( $\epsilon$ -net)
1/poly(d)	NP-hard	$(d/\sqrt{\epsilon})^{O(d)}$	$(1/\epsilon)^{O(d)}$
const	$d^{O(log(d))}$	$d^{O(log(d)/\epsilon^2)}$	similar to left
	(ETH)	(1-LOCC)	(1-LOCC)

**REMARK**: previous results focus on the *dependence on d*, which is sufficient for their purpose. However, the *dependence* on  $\epsilon$  could be bad.

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**Table:** Known results about approximating  $h_{\text{Sep}(d)}$  to error  $\epsilon$ 

Error $\epsilon$	Lower bounds	Upper b. (DPS)	Upper b. ( $\epsilon$ -net)
1/poly(d)	NP-hard	poly $(1/\epsilon)$	poly $(1/\epsilon)$
const	$d^{O(log(d))}$	$\exp(1/\epsilon)$	similar to left
	(ETH)	(1-LOCC)	(1-LOCC)

**REMARK**: previous results focus on the *dependence on d*, which is sufficient for their purpose. However, the *dependence on*  $\epsilon$  could be bad. Is such dependence necessary?

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Motivations Related Work Main Result

# Angle I: Error MATTERs!

### Complexity could grow with $1/\epsilon$

- Infinite translationally invariant Hamiltonian: the complexity grows rapidly with 1/ε even with fixed local dimension. [CPW]
- Quantum Interactive Proof: the complexity jumps from PSPACE to EXP with smaller *e*. [IKW]

### Will approximating $h_{\text{Sep}(d)}$ be such a case?

**REMARK**: It is not clear how to improve the error dependence for either DPS or epsilon-net approach.

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Motivations Related Work Main Result

## Main Result I:

## Error dependence about h<sub>Sep(d)</sub>

- NO error dependence except numerical errors.
- For analytical purposes, there is no error at all.
- Numerically, the dependence is polylog(1/ε), *exponential* improvement from best known poly(1/ε), exp(1/ε).

Moreover, the dependence on *d* remains the same.

#### Theorem (Main I)

There exist two algorithms that estimate  $h_{\text{Sep}(d)}(M)$  to error  $\epsilon$  in time  $\exp(\text{poly}(d))$  poly  $\log(1/\epsilon)$ . similar for the multi-partite case.

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Motivations Related Work Main Result

# **DPS+** hierarchy

## **DPS+** hierarchy level $\overline{k}$ for $h_{\text{Sep}(d)}(\overline{M})$

$\max_{ ho}$	$\left<  ho_{\boldsymbol{X} \mathcal{Y}_1}, \boldsymbol{M} \right>$	
such that	$ \rho \in \mathrm{D}\left(\mathcal{X}\otimes\mathcal{Y}_{1}\otimes\cdots\otimes\mathcal{Y}_{k}\right), $	(3)
	$ \rho $ is symmetric on $\mathcal{Y}_1 \otimes \cdots \otimes \mathcal{Y}_k$ ,	(-)
	$\langle \rho, \Gamma_i \rangle = 0, \forall i.$ KKT conditions	

#### Remarks

- The new hierarchy is exact when k = exp(poly(d)).
- KKT conditions Γ<sub>i</sub> depend on *M*.
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Motivations Related Work Main Result

# Result II: Hardness w/o ASSUMPTIONs?

## Will the hardness of $h_{\text{Sep}(d)}$ for const $\epsilon$ hold w/o ETH?

#### Theorem (Main II.1)

DPS hierarchies (or general Sum-of-Squares SDP) require  $\Omega(\log(d))$  levels to solve  $h_{Sep(d)}$  with constant precision.

#### Theorem (Main II.2)

Any SDP that estimate  $h_{\text{Sep}(d)}(M)$  with constant errors requires size  $d^{\Omega(\log(d))}$ .

#### Remark: Match $d^{\Omega(\log(d))}$ time bound when assuming ETH.

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Principle of Sum-of-Squares

One way to show that a polynomial f(x) is *nonnegative* could be

$$f(x)=\sum a_i(x)^2\geq 0.$$

#### Example

$$\begin{split} f(x) &= 2x^2 - 6x + 5 \\ &= (x^2 - 2x + 1) + (x^2 - 4x + 4) \\ &= (x - 1)^2 + (x - 2)^2 \geq 0. \end{split}$$

Such a decomposition is called a *sum of squares (SOS) certificate* for the non-negativity of *f*. The min degree,  $deg_{sos}$ .

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

## Principle of SoS : constrained domain

#### **Definition (Variety)**

A set  $V \subseteq \mathbb{C}^n$  is called an *algebraic variety* if  $V = \{x \in \mathbb{C}^n : g_1(x) = \cdots = g_k(x) = 0\}.$ 

Non-negativity of f(x) on V could be shown by

$$f(x) = \sum a_i(x)^2 + \sum b_j(x)g_j(x) \ge 0.$$

**Question**: whether all nonnegative polynomials on certain variety have a SOS certificate? Hilbert 17th problem!

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

## SoS in Optimization

$$\begin{array}{ll} \max & f(x) \\ \text{subject to} & g_i(x) = 0 \quad \forall i \end{array} \tag{4}$$

#### is equivalent to (justified by Positivstellensatz)

min 
$$\nu$$
  
such that  $\nu - f(x) = \sigma(x) + \sum_{i} b_i(x)g_i(x),$  (5)

where  $\sigma(x)$  is SOS and  $b_i(x)$  is any polynomial.

Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

## SoS relaxation: Lasserre/Parrilo Hierarchy

- If σ(x), b<sub>i</sub>(x) have any degrees (or deg<sub>sos</sub>(v f)), then problem (5) is equivalent to problem (4).
- By bounding the degrees, we get the Lasserre/Parrilo hierarchy.

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Why it is a SDP?

#### Observation

- Any p(x) (of degree 2D) =  $m^T Qm$ , where *m* is the vector of monomials of degree up to 2D and *Q* is the coefficients.
- p(x) is a SOS iff  $Q \ge 0$ .

$$\begin{array}{ll} \min_{\nu, b_{i\alpha} \in \mathbb{R}} & \nu \\ \text{such that} & \nu A_0 - F - \sum_{i\alpha} b_{i\alpha} G_{i\alpha} \ge 0. \end{array} (7)$$

Complexity: poly(m) poly log(1/ $\epsilon$ ), where  $m = \binom{n+D}{D}$ .

A. Harrow, A. Natarajan, and X. Wu New Upper and Lower bounds for Entanglement Testing

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

## Dual of the SDP: moment

#### Dual of the SOS cone

- Let Σ<sub>d,2D</sub> be the cone of all PSD matrices representing SOS polynomials with degree up to 2D.
- The dual cone  $\Sigma_{d,2D}^*$  is moment  $M_D(x) \ge 0$ , where entry  $(\alpha, \beta)$  of  $M_d(x)$  is  $\int x^{\alpha+\beta} \mu(dx), |\alpha|, |\beta| \le d$ .

#### **Pseudo-expectation**

- Expectation on moment  $M_D(x)$  gives rise to pseudo-expectation.
- Behave similar to expectation for low-degree polynomials.

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Full Symmetry $\implies$ DPS

#### Example

Now each entry is labelled with ((i, j), (k, l)) for degree 4 case, i.e.,  $M_d(x) = \rho \in D(\mathbb{C}^n \otimes \mathbb{C}^n)$ .

$$\rho = \sum_{(i,j),(k,l)} x_i x_j x_k x_l \ket{i} \ket{j} \langle k | \langle l |.$$

Note that entry ((i, j), (k, l)) and ((i, l), (k, j)) have the same value  $x_i x_j x_k x_l$ . This is **PPT** condition. Similar for **DPS**.

Remark: more symmetry because in ProdSym. Flexible in choosing more or less symmetry.

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Karush-Kuhn-Tucker Conditions

For any optimization problem

$$\max f(x) \text{ s.t. } g_i(x) \leq 0, h_j(x) = 0, \forall i, j,$$

if  $x^*$  is a *local* optimizer, then  $\exists \mu_i, \lambda_j$ ,

$$\begin{aligned} \nabla f(\boldsymbol{x}^*) &= \sum \mu_i \nabla g_i(\boldsymbol{x}^*) + \sum \lambda_j \nabla h_j(\boldsymbol{x}^*) \\ g_i(\boldsymbol{x}^*) &\leq 0, h_j(\boldsymbol{x}^*) = 0, \\ \mu_i &\geq 0, \mu_i g_i(\boldsymbol{x}^*) = 0. \end{aligned}$$

Remark: for convex optimization (our case), any global optimizer satisfies KKT.

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

### Our case

Recall our optimization problem is

 $\max f_0(x)$  s.t.  $f_1(x) = 0$ .

The KKT condition is  $\nabla f_0(x) = \lambda \nabla f_1(x)$ , which is equivalent to

$$\operatorname{rank}\begin{pmatrix} \frac{\partial f_0(x)}{\partial x_1} & \frac{\partial f_1(x)}{\partial x_1}\\ \vdots & \vdots\\ \frac{\partial f_0(x)}{\partial x_{2n}} & \frac{\partial f_1(x)}{\partial x_{2n}} \end{pmatrix} < 2.$$

 $g_{ij}(x) = \frac{\partial f_0(x)}{\partial x_i} \frac{\partial f_1(x)}{\partial x_j} - \frac{\partial f_0(x)}{\partial x_j} \frac{\partial f_1(x)}{\partial x_i}, \quad \forall i, j$ 

A. Harrow, A. Natarajan, and X. Wu New Upper and Lower bounds for Entanglement Testing

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$$\operatorname{rank}\begin{pmatrix} \frac{\partial f_0(x)}{\partial x_1} & \frac{\partial f_1(x)}{\partial x_1}\\ \vdots & \vdots\\ \frac{\partial f_0(x)}{\partial x_{2n}} & \frac{\partial f_1(x)}{\partial x_{2n}} \end{pmatrix} < 2.$$

$$g_{ij}(x) = \frac{\partial f_0(x)}{\partial x_i} \frac{\partial f_1(x)}{\partial x_j} - \frac{\partial f_0(x)}{\partial x_j} \frac{\partial f_1(x)}{\partial x_i}, \quad \forall i, j$$

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

## **Optimization Problem with KKT constraints**



#### • Apply the degree bound *D*, we get the SoS SDP hierarchy.

 Will show finite convergence when D = exp(poly(d)). Then m = (<sup>d+D</sup><sub>D</sub>) = exp(poly(d)). Thus the final time is exp(poly(d)) poly log(1/ϵ).

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# **Optimization Problem with KKT constraints**

$$\begin{array}{ll} \min & \nu \\ \text{such that} & \nu - f_0(x) \geq 0 \\ & f_1(x) = 0 \\ \\ \text{KKT} & g_{ij}(x) = 0 \quad \forall \, 1 \leq i \neq j \leq 2d \end{array}$$

- Apply the degree bound D, we get the SoS SDP hierarchy.
- Will show finite convergence when D = exp(poly(d)). Then m = (<sup>d+D</sup><sub>D</sub>) = exp(poly(d)). Thus the final time is exp(poly(d)) poly log(1/ϵ).

Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

### **Proof Overview**

#### • KKT conditions are necessary for *critical* points.

- KKT conditions imply finite convergence (tri-exponential or higher) for a generic optimization problem. [N, NR]
- Bring down the level for our problem to exponential.
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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Generic input M

### Theorem (Zero-dimensional of generic $I_K$ )

For a generic M,  $|V(I_K)| < \infty$  and  $I_K$  is zero-dimensional.

#### Theorem (Degree bound)

There exists  $m = O(\exp(poly(n)))$ , s.t. for a generic M,  $\epsilon > 0$ ,

 $v - f_0(x) + \epsilon = \sigma(x) + g(x),$ 

where  $\sigma(x)$  is SoS and deg $(\sigma(x)) \leq m, g(x) \in I_K^m$ .

#### Corollary (SDP solution)

Estimate  $h_{ProdSym(n)}(M)$  for a generic M to error  $\epsilon$  needs  $exp(poly(n))poly log(1/\epsilon)$ .

A. Harrow, A. Natarajan, and X. Wu New Upper and Lower bounds for Entanglement Testing

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Arbitrary input M

#### **Observations**

- Generic *M* is *dense*. The opt of SDP could be continuous.
- Issue: SOS SDP might be *infeasible* up to degree *m* for arbitrary input *M*.

#### Solutions

- Switch to the dual SDP (moment): satisfies Slater's condition, i.e, strictly feasible.
- For a generic M, by strong duality,  $P_{\text{TotS}}(M) = OPT_{\text{max}}(M)$ :

For any input M, use the continuity of the dual SOP then.

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# Result II: Hardness w/o ASSUMPTIONs!

#### Theorem (Main II.1)

DPS hierarchies (or general Sum-of-Squares SDP) require  $\Omega(\log(d))$  levels to solve  $h_{\text{Sep}(d)}$  with constant precision.

#### Theorem (Main II.2)

Any SDP that estimate  $h_{\text{Sep}(d)}(M)$  with constant errors requires size  $d^{\Omega(\log(d))}$ .

**Remark:** Theorem II.1  $\Rightarrow$  Theorem II.2 due to a recent result on psd rank (SDP) lower bound [LRS].

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

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### • LB: instance w/ true value small, SoS (or SDP) value large.

- Start w/ such an instance: random 3XOR w/ true value  $\sim 1/2 + \epsilon$ , SoS value= 1 for large sos degree.
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- Make use of a QMA(2) protocol (for 2-out-of-4 SAT) [AB+] to solve this 3XOR.
- Step 1: a random 3XOR  $\Rightarrow$  a 2-out-of-4 SAT instance.
- Step 2: QMA(2) protocol as a reduction!

Step 2.1: Embed it further as an instance to h<sub>ear(i)</sub>(M).
 (Theorem 1.1)

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Step 2.2: Apply LRS to the resultant problem. Then reduces

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- Make use of a QMA(2) protocol (for 2-out-of-4 SAT) [AB+] to solve this 3XOR.
- Step 1: a random 3XOR  $\Rightarrow$  a 2-out-of-4 SAT instance.
- Step 2: QMA(2) protocol as a reduction!
  - Step 2.1: Embed it further as an instance to h<sub>Sep(d)</sub>(M). (Theorem II.1)
  - Step 2.2: Apply LRS to the resultant problem. Then reduce it to h<sub>Sep(d)</sub>(M). (Theorem II.2)

Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Step 1: 3XOR $\Rightarrow$ 2-out-of-4 SAT

A random 3XOR on *n* vars with O(n) clauses: sos-deg  $\Omega(n)$ , true value  $\sim 1/2$ , pseudo-expectation value 1.

- A random 3XOR (each var appears in const clauses) has sos-deg Ω(n).
- Replace each clause  $x_1 \oplus x_2 \oplus x_3 = z_c$  with  $2o4(x_1, b, c, z)$ ,  $2o4(x_2, a, c, z)$ ,  $2o4(x_3, a, b, z)$ .
- Use 2*o*4 clauses to make all auxiliary  $z_c$  the same. Use expander graphs to force const appearances.
- Extending the pseudo-expectation:  $\tilde{E}[y_1(x)y_2(x)] = \sum_{\alpha \in y_1y_2} \tilde{E}[x^{\alpha}].$

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

# Step 2: DPS and SDP lower bounds

#### **DPS lower bound**

- Embed this pseudo-distribution on  $\{0, 1\}^n$  to  $\mathbb{R}^d$ .  $(d = n^{\sqrt{n} \text{polylog}(n)})$
- Thus h<sub>Sep(d)</sub>(M) has sos degree Ω(log(d)).

#### **SDP** lower bound

- Apply LRS to this function on {0,1}<sup>n</sup>. Obtain SDP size lower bound (d/loglog(d))<sup>Ω(log(d))</sup>.
- By soundness, a general h<sub>Sep(d)</sub>(M) can solve this problem, thus has the same lower bound.

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Sum-of-Squares Relaxation Finite Convergence at Exponential Level SoS, SDP Lower Bounds

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**Open Questions** 

## **Open Questions**

#### DPS+

- Analyze the low levels of DPS+.
- Advantages of adding KKT conditions other than presented here.
- Extension to the non-commutative case?

#### SoS, SDP lower bound

- Any hope for a better bound?
- Extension to general algorithms?
- Any other applications to quantum information?

**Open Questions** 

## **Question And Answer**

# Thank you! Q & A

A. Harrow, A. Natarajan, and X. Wu New Upper and Lower bounds for Entanglement Testing

**Open Questions** 

#### **Proof of Theorem 1**

## Let $\mathcal{U} = \{f_1(x) = 0\}, \mathcal{W} = \{\forall i, j, g_{ij} = 0\}$ . then $V(I_{\mathcal{K}}) \subseteq \mathcal{U} \cap \mathcal{W}$ .

It suffices to show  $|\mathcal{U} \cap \mathcal{W}| < \infty$ . Construct  $\mathcal{A} = \mathcal{X} \cap \mathcal{U}$  s.t.

 $\mathcal{A} \cap \mathcal{W} = \emptyset$  and dim $(\mathcal{X}) = n - 1$ . Note  $\mathcal{W} \cap \mathcal{A} = (\mathcal{W} \cap \mathcal{U}) \cap \mathcal{X}$ .

By Bézout's theorem, two varieties with dimension sum  $\geq n$  must intersect. Thus

 $\dim(\mathcal{W} \cap \mathcal{U}) + \dim(\mathcal{X}) = \dim(\mathcal{W} \cap \mathcal{U}) + n - 1 < n.$ 

This implies dim $(\mathcal{W} \cap \mathcal{U}) = 0$  and thus  $|V(I_{\mathcal{K}})| < \infty$ .

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## **Proof of Theorem 1: construct** X

Let  $\mathcal{X} = \{f_0(x) = \mu\}$  for generic  $(\mu, M)$ . dim $(\mathcal{X}) = n - 1$ .

By Bertini's theorem,  $\dim(\mathcal{A}) = \dim(\mathcal{U} \cap \mathcal{X}) = n - 2$ .

The Jacobian matrix 
$$J_{\mathcal{A}} = \begin{pmatrix} \frac{\partial f_0}{\partial x_1} & \frac{\partial f_1}{\partial x_1} \\ \vdots & \vdots \\ \frac{\partial f_0}{\partial x_n} & \frac{\partial f_1}{\partial x_n} \end{pmatrix}$$
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Subtly: genericity; projective space; homogenization!

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## **Proof of Theorem 2**

Let  $\{\gamma_i\}$  be a Grobner basis for  $I_K$ .

 $|V(I_{\mathcal{K}})| < \infty \implies \max \deg\{\gamma_i\} \le D = \exp(\operatorname{poly}(n)).$ 

Now, want to bound  $deg(\sigma(x)), deg(g(x))$  in

 $v - f_0(x) = \sigma(x) + g(x)$ . s.t.  $\sigma(x)$  SOS  $, g(x) \in I_K^m$ .

Let  $\sigma(x) = \sum s_a(x)^2$ . By property of Grobner basis

 $s_a(x) = g_a(x) + u_a(x)$ , s.t.  $g_a(x) \in I_K$ ,  $\deg(u_a(x)) \le nD$ .

Thus

 $v - f_0(x) = \sigma'(x) + g'(x), \deg(\sigma'(x)) \le \exp(\operatorname{poly}(n)), g' \in I_K.$ 

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Thus

$$\mathbf{v} - \mathbf{f}_0(\mathbf{x}) = \sigma'(\mathbf{x}) + \mathbf{g}'(\mathbf{x}), \deg(\sigma'(\mathbf{x})) \leq \exp(\operatorname{poly}(\mathbf{n})), \mathbf{g}' \in \mathbf{I}_K.$$

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**Open Questions** 

# Proof of Theorem 2: $g' \in I_K^m$

All we need is to show  $g' \in I_K^m$ ,  $m = \exp(\operatorname{poly}(n))$ .

- $\deg(g'(x)) = \deg(\sigma'(x)) = m$ .
- In Grobner basis,  $g'(x) = \sum t_k \gamma_k(x)$ ,  $\deg(t_k \gamma_k(x)) \le m$ . • (Omitted)  $x_k(x) = \sum u_k(x) g_k(x)$ ,  $\deg(u_k) \le m$ .

• (Omitted)  $\gamma_k(x) = \sum u_{ij}(x)g_{ij}(x), \deg(u_{ij}) \leq m.$ 

Thus,  $g'(x) = \sum t_k u_{ij} g_{ij}(x)$ ,  $\deg(t_k u_{ij}) \le m$ ,  $\implies g'(x) \in I_K^m$ .

 $\begin{array}{ll} f_{K}^{m} &=& \{v(x)f_{1}(x) + \sum h_{ij}(x)g_{ij}(x): \deg(v(x)f_{1}(x)) \leq m, \\ &\forall \, i,j, \deg(h_{ij}g_{ij}) \leq m\}. \end{array}$ 

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**Open Questions** 

# Proof of Theorem 2: $g' \in I_K^m$

All we need is to show  $g' \in I_{\mathcal{K}}^m, m = \exp(\operatorname{poly}(n))$ .

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• (Omitted)  $\gamma_k(x) = \sum u_{ij}(x)g_{ij}(x), \deg(u_{ij}) \leq m.$ 

Thus,  $g'(x) = \sum t_k u_{ij} g_{ij}(x), \deg(t_k u_{ij}) \le m, \implies g'(x) \in I_K^m$ .

 $\begin{array}{ll} f_{K}^{m} &= \{v(x)f_{1}(x) + \sum h_{ij}(x)g_{ij}(x) : \deg(v(x)f_{1}(x)) \leq m, \\ &\forall i,j, \deg(h_{ij}g_{ij}) \leq m\}. \end{array}$ 

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