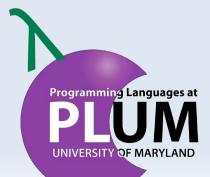
A Study of Dynamic Software Update Quiescence for Multithreaded Programs

Christopher M. Hayden, <u>Karla Saur</u>, Michael Hicks, Jeffrey S. Foster





Update Timing

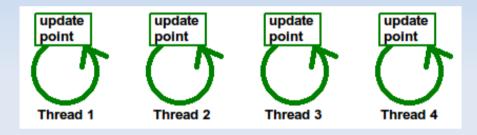
Well-defined update points make it easier to reason about update correctness

```
void *thread_entry(void *arg) {
    /* thread init code */
    while (1) {
        dsu_update(); /* update point */
        /* loop body: typically handles a single program event */
    }
```

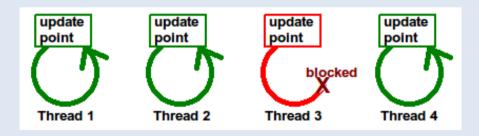
 Good candidates are *quiescent points* in loops which have little in-flight state

DSU and Threading

- *Timeliness* in multithreaded updates:
 - Full quiescence all threads hit update point



 Concern - Updating at only specific points has the risk of delaying an update for too long, even indefinitely



Goals & Approach:

- Questions:
 - Quick full quiescence in multithreaded programs?
 - What blocking calls impede quick quiescence?
- Created library: QBench
 - Interrupt blocking to facilitate quiescence with minimal delay
 - *Measures time* from update request to full quiescence
 - Idioms we develop in QBench we can roll into DSU systems

Update at Quiescent Points

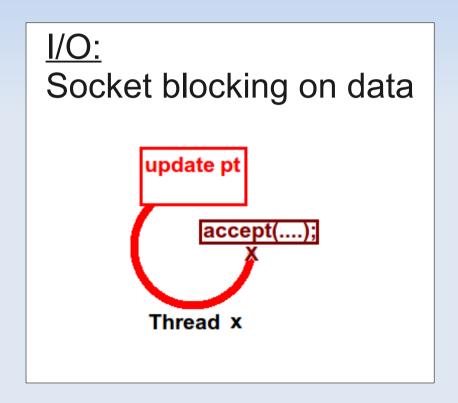
- Update point 'qbench_update':
 - No update requested: call is a no-op
 - Update requested: calling thread blocks

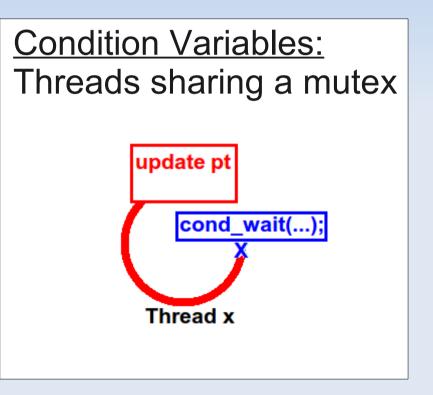
```
void *thread_entry(void *arg) {
/* thread init code */
while (1) {
    qbench_update(); /* update point */
    /* loop body: typically handles a single program event */
    }
```

- Request an update by sending a SIGUSR2 signal
 - QBench installs a signal handler indicating update requested.

Threats to Quiescence

Blocking calls in our experiments:





Under normal circumstances an accept call will block until a connection is accepted.

```
void *thread_entry(void *arg) {
/* thread init code */
while (1) {
res = accept(sockfd, addr, addrlen);
/* ... handle connection */
}
```

Under normal circumstances an accept call will block until a connection is accepted.

- void *thread_entry(void *arg) {
- 2 /* thread init code */

```
3 while (1) {
```

5

6

7

8

9

10

```
4 qbench_update();
```

```
res = accept(sockfd, addr, addrlen);
```

```
/* ... handle connection */
```

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4 qbench_update();

```
res = accept(sockfd, addr, addrlen);
```

/* ... handle connection */

```
if (res == -1 && errno == EINTR)
  continue;
```

A signal will interrupt *accept*, return -1, and set errno to EINTR.

7

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- void *thread_entry(void *arg) {
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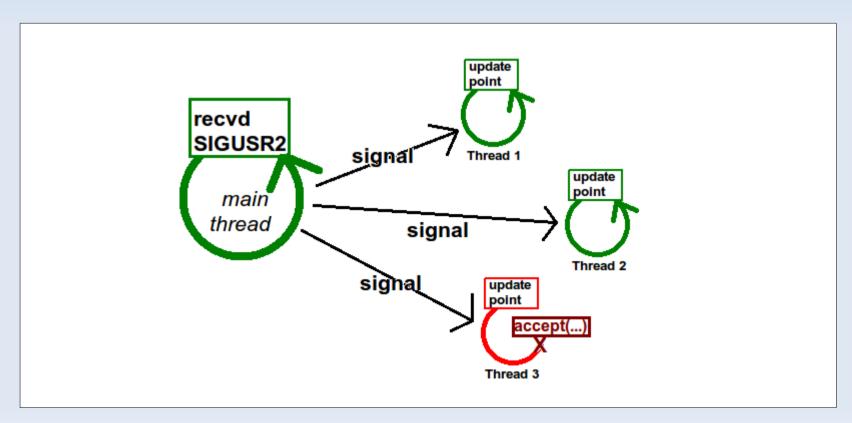
Returns to top of even loop to immediately hit update point

interrupt *accept*, return -1, and set errno to EINTR.

A signal will

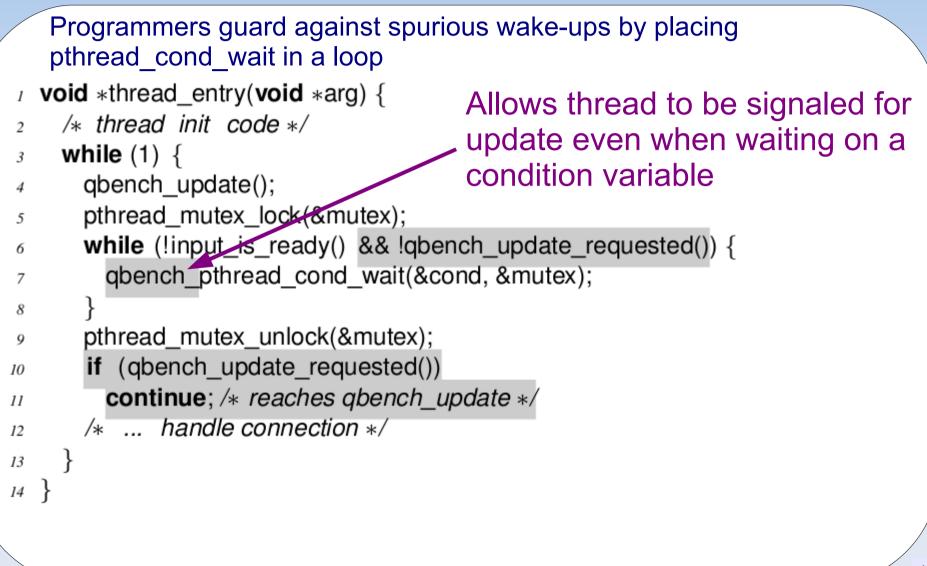
UNIX Signals

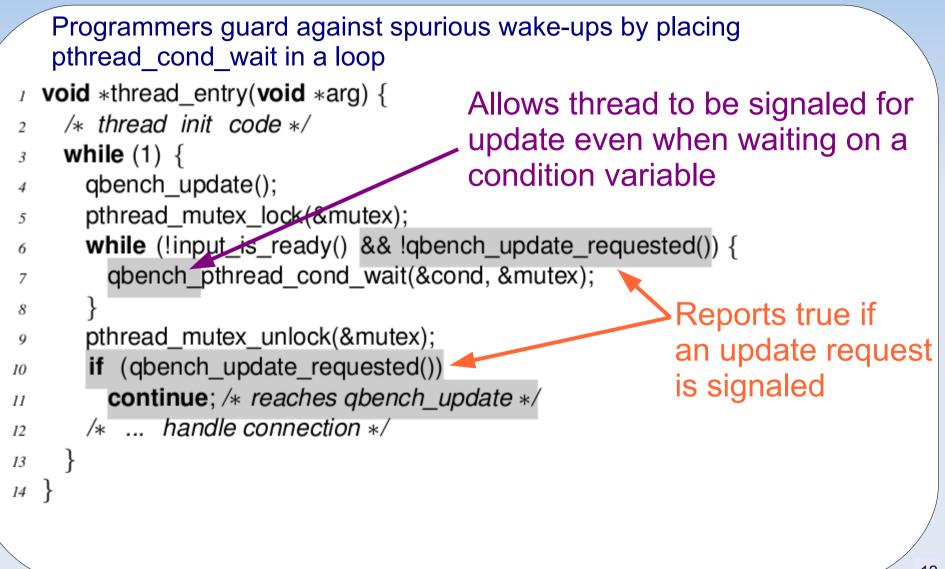
- Signals are usually handled by main thread
 - Main thread signals all threads not blocked by condition variables

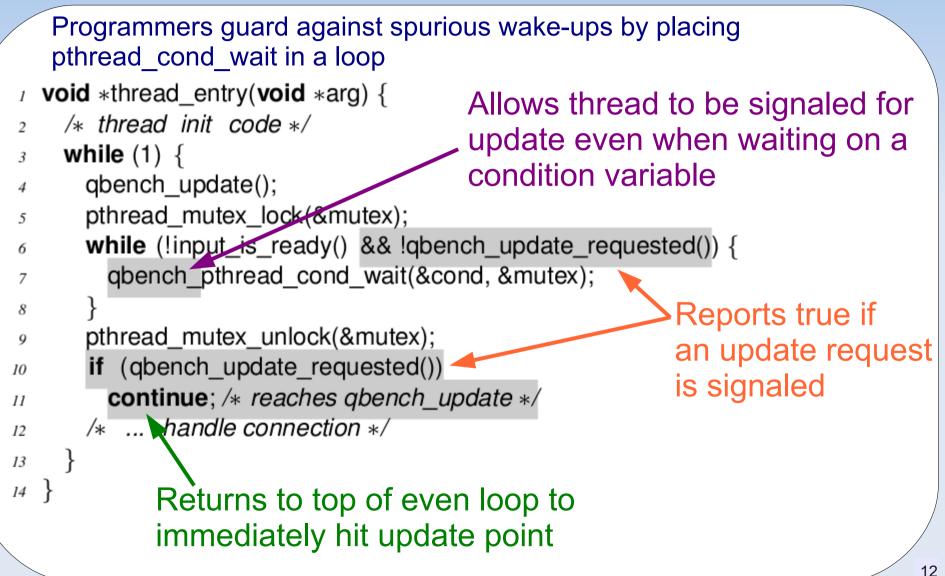


```
Programmers guard against spurious wake-ups by placing
   pthread cond wait in a loop
  void *thread_entry(void *arg) {
1
    /* thread init code */
2
    while (1) {
3
      qbench update();
4
      pthread_mutex_lock(&mutex);
5
      while (!input_is_ready()){
6
           pthread_cond_wait(&cond,&mutex);
7
8
      pthread_mutex_unlock(&mutex);
9
10
11
      /* ... handle connection */
12
13
14
```

```
Programmers guard against spurious wake-ups by placing
   pthread cond wait in a loop
void *thread_entry(void *arg) {
    /* thread init code */
2
    while (1) {
3
      qbench_update();
4
      pthread_mutex_lock(&mutex);
5
      while (!input_is_ready() && !qbench_update_requested()) {
6
        qbench pthread_cond_wait(&cond, &mutex);
7
8
      pthread_mutex_unlock(&mutex);
9
      if (qbench_update_requested())
10
        continue; /* reaches qbench_update */
11
      /* ... handle connection */
12
13
14
```

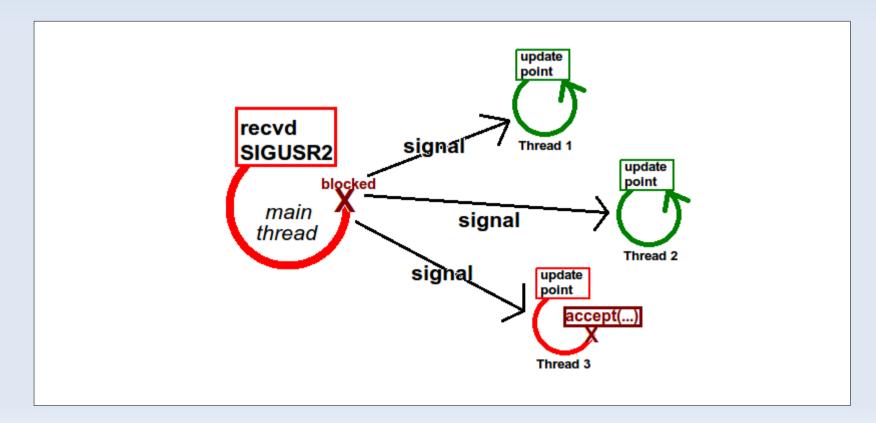






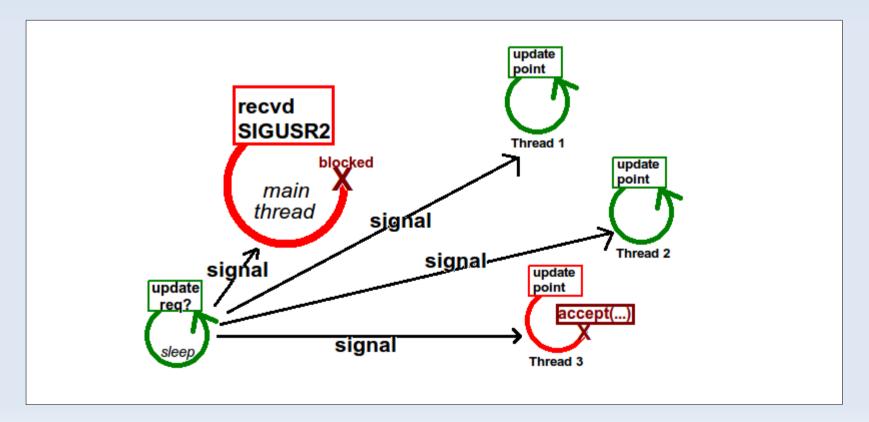
Waking a Blocked Thread

 Condition Variables: Another thread must be available to signal



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- We chose programs covering a wide range of domains.
- On average, 22 lines of code changed (including update points).
- Manual changes: changes beyond adding calls to QBench.

	LoC		Upd	Changed	Required
Program	Total	# of Threads	Points	LoC (†)	Manual Chgs
httpd-2.2.22	232651	$2 + c^*, \ c = 3$	5	7 (5)	3 (Cond. Var. Loop)
icecast-2.3.2	17038	6	12	3 (3)	1 (Thread Sleeps)
iperf-2.0.5	3996	$3 + n^{\circ}, \ n = 1$	5	8 (3)	1 (Cond. Var. Loop)
memcached-1.4.13	9404	$2 + c^*, \ c = 4$	4	27 (4)	2 (libevent changes)
space-tyrant-0.354	8721	$3 + 2n^{\circ}, n = 5$	6	8 (6)	1 (Thread Sleeps)
suricata-1.2.1	260344	$8 + c^*, \ c = 3$	7	11 (6)	1 (libpcap break)

*Configurable: c workers °Varies by n connected clients [†]Calls to QBench excluding update

Results

- Two Workloads:
 - Server idle (i.e., no connected clients)
 - Performing program-dependent work
- Nearly all programs quiesced in under 1ms
- Some would not quiesce without changes

	w/Load (ms)		w/o Load (ms)	
Program	All Chgs	UpdPt only	All Chgs	UpdPt only
httpd-2.2.22	0.185	0.230	0.123	0.150
icecast-2.3.2	105.152	954.32	107.558	986.265
iperf-2.0.5	0.193	DNQ	0.169	DNQ
memcached-1.4.13	0.166	DNQ	0.155	DNQ
space-tyrant-0.354	0.426	20.583	0.078	20.304
suricata-1.2.1	0.503	68.098	0.378	DNQ

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Summary & Future Work

 Demonstrated multithreaded quiescence quickly and with little implementation complexity for many programs with fixed update points

 Time to quiescence ranged from 0.155 to 107.558 ms; most were below 1 ms

 We plan to integrate the multi-threaded quiescent functionality back into Kitsune