

# Memory Offloading

Abhinav Bhatele, Daniel Nichols



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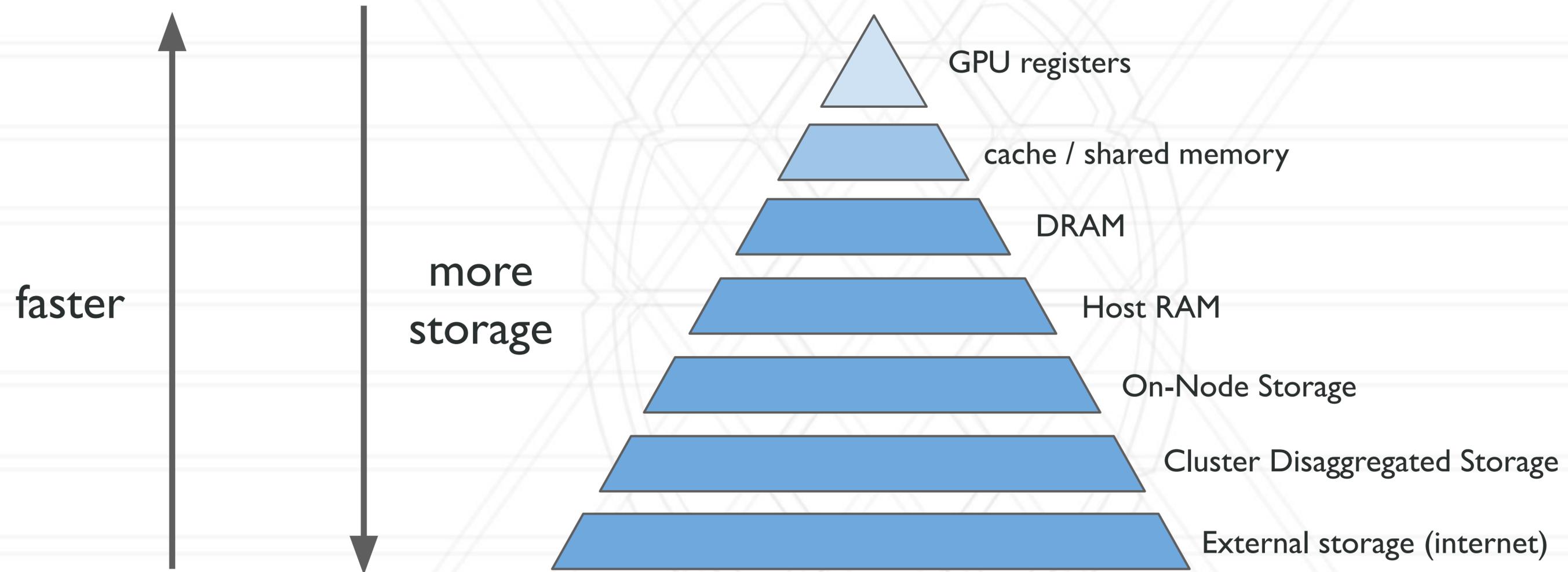
# Announcements

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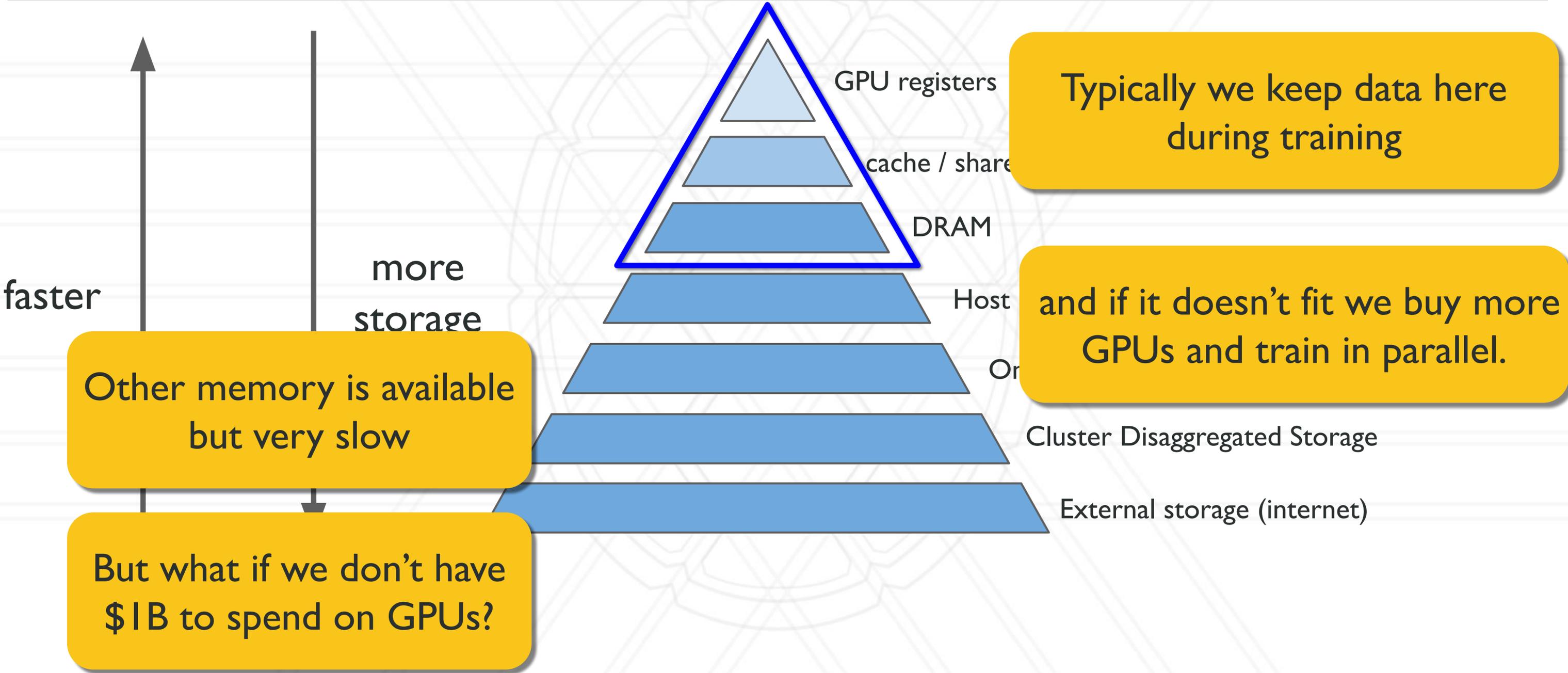
- Interim report for the project is due on April 17
- Midterm is on April 10
- Assignment 2 grades are out

# Memory Hierarchy

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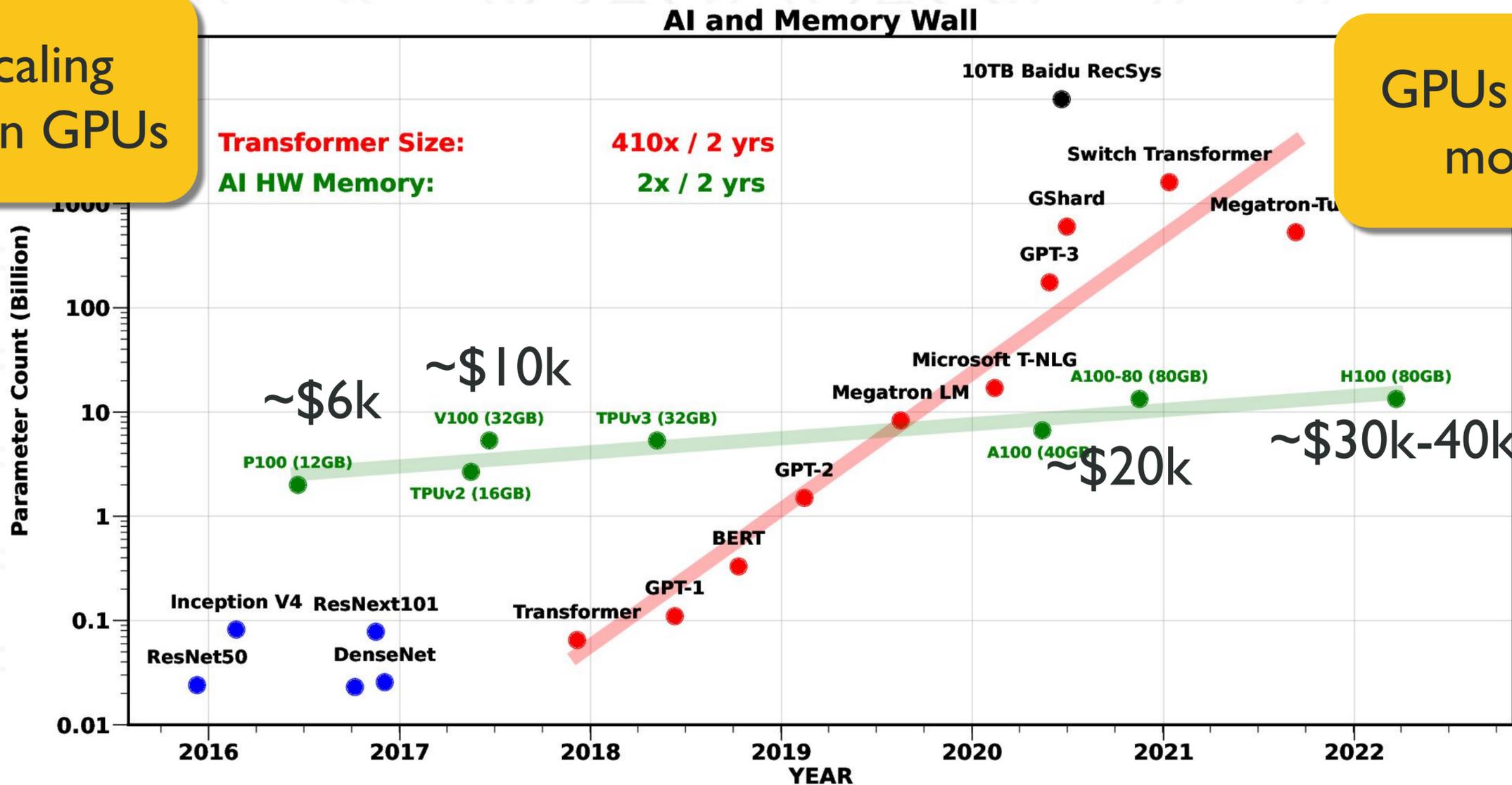
# Memory Hierarchy



# Problems with Memory Scaling

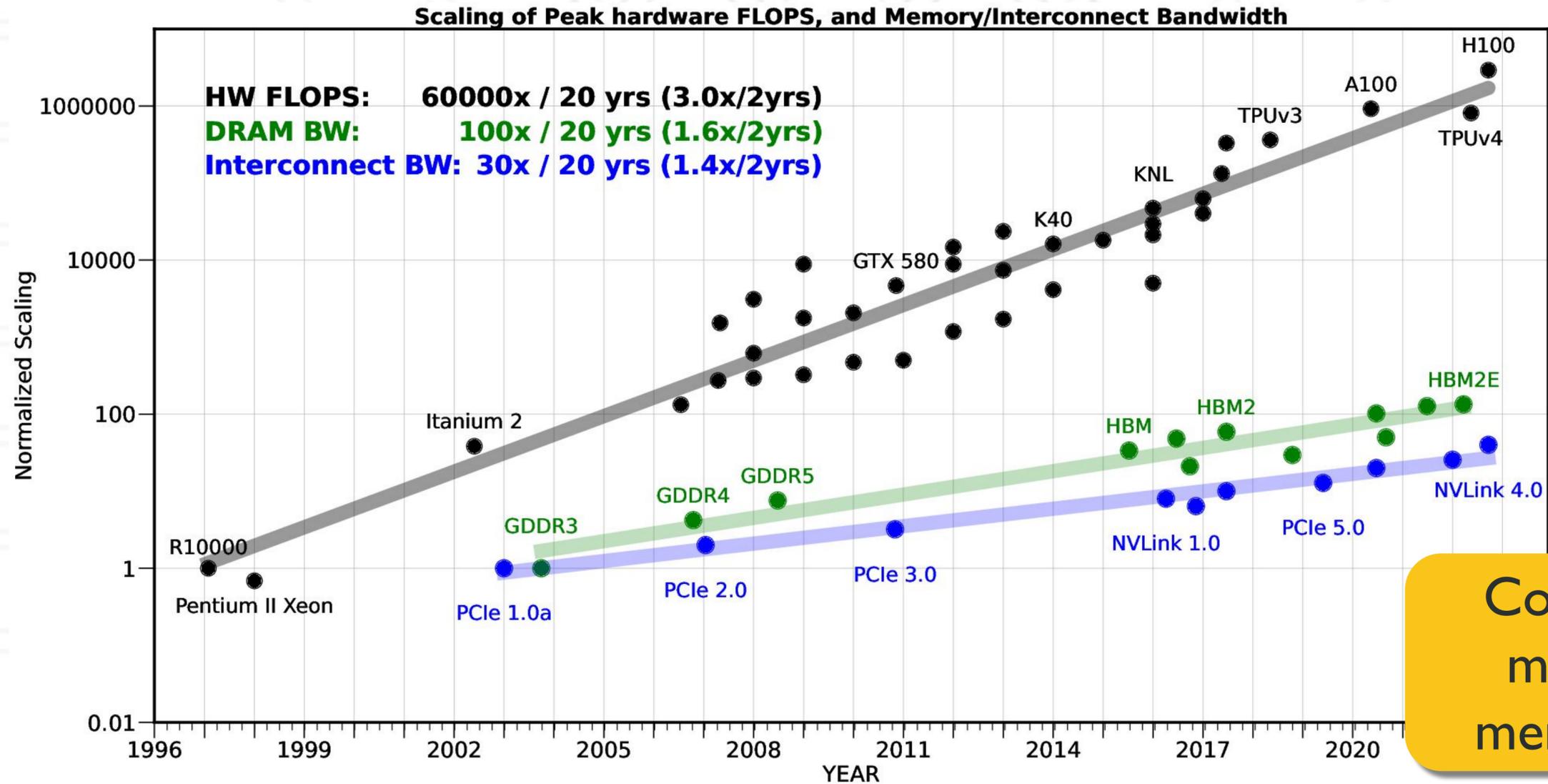
Models are scaling much faster than GPUs

GPUs are also getting more expensive



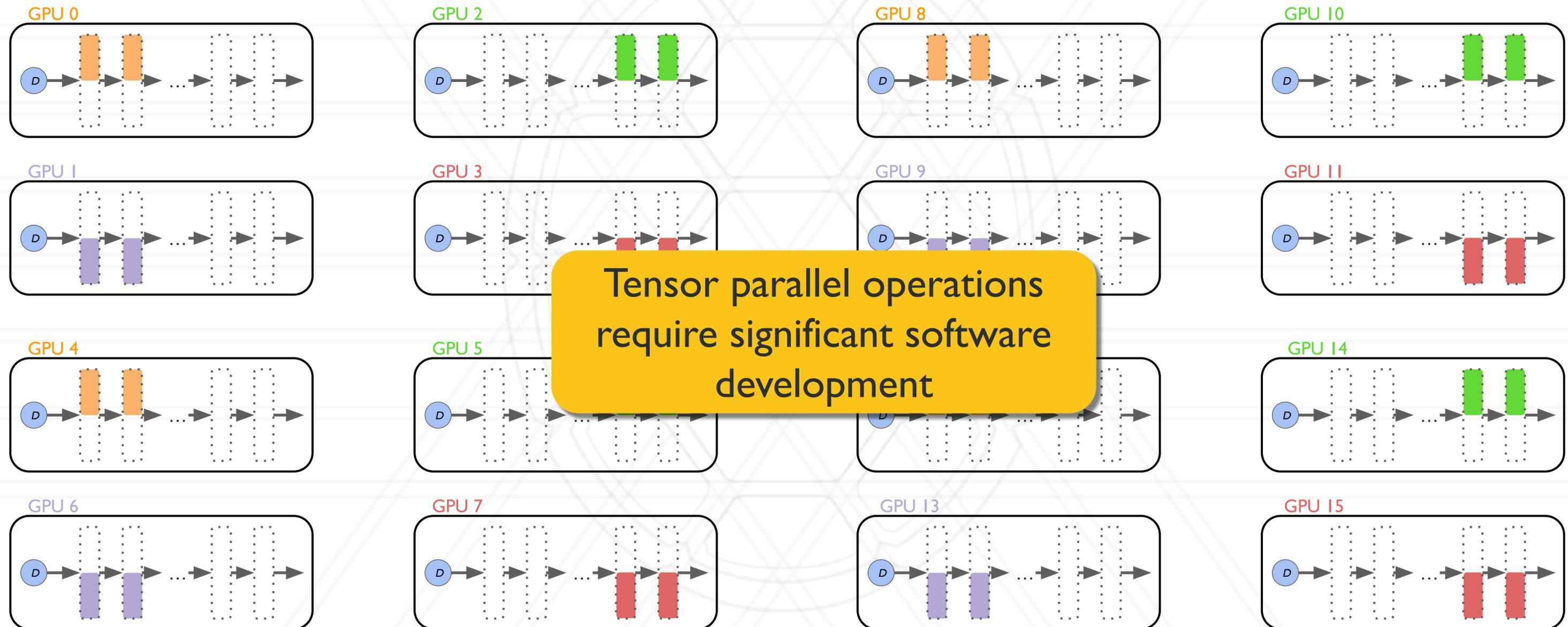
A. Gholami, et. al., "AI and Memory Wall"

# Problems with Memory Scaling



A. Gholami, et. al., "AI and Memory Wall"

# Other Problems with Using More GPUs



# Memory Offloading

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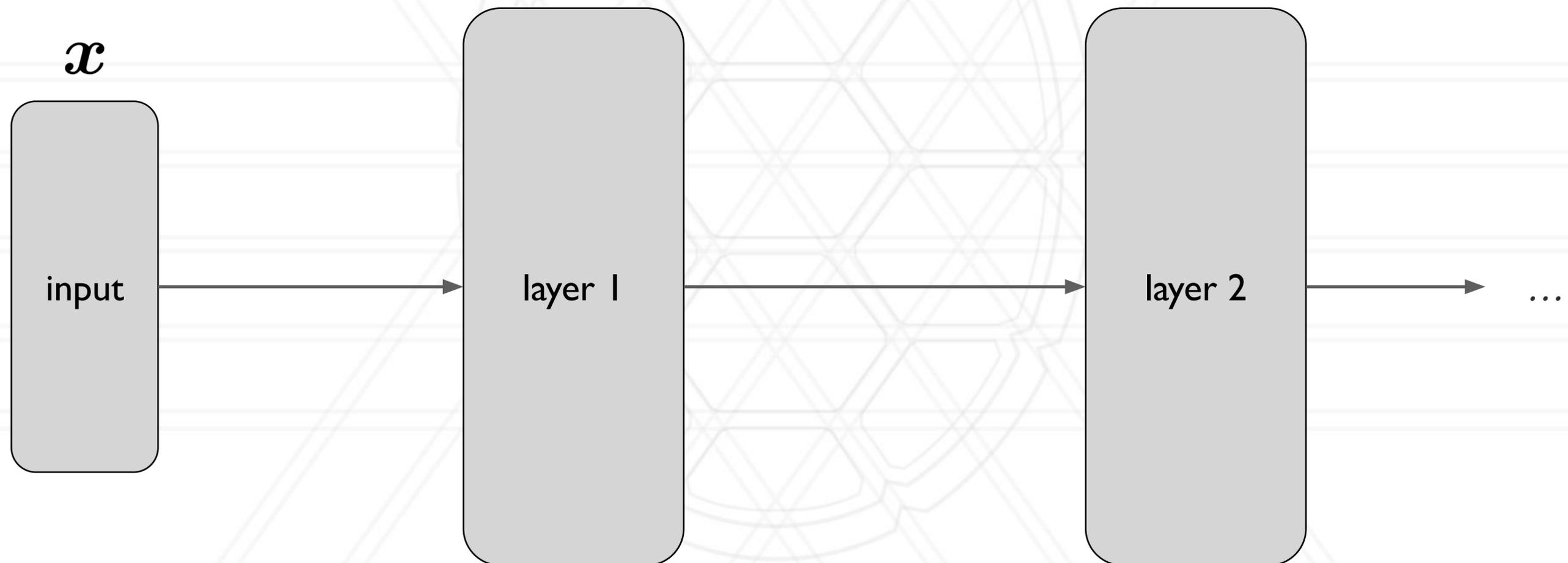
- Can we migrate memory to the CPU or disk to save on GPU memory?
- Will be slow, but provide previously unattainable functionality
- Sometimes this is ok
  - Fine-tuning on small datasets
  - Batched inference
  - Reads/writes can be completely masked

# What's using the memory?

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$$\mathbf{h}^{(1)} = \sigma \left( \Theta^{(1)T} \mathbf{x} \right)$$

$$\mathbf{h}^{(2)} = \sigma \left( \Theta^{(2)T} \mathbf{h}^{(1)} \right)$$

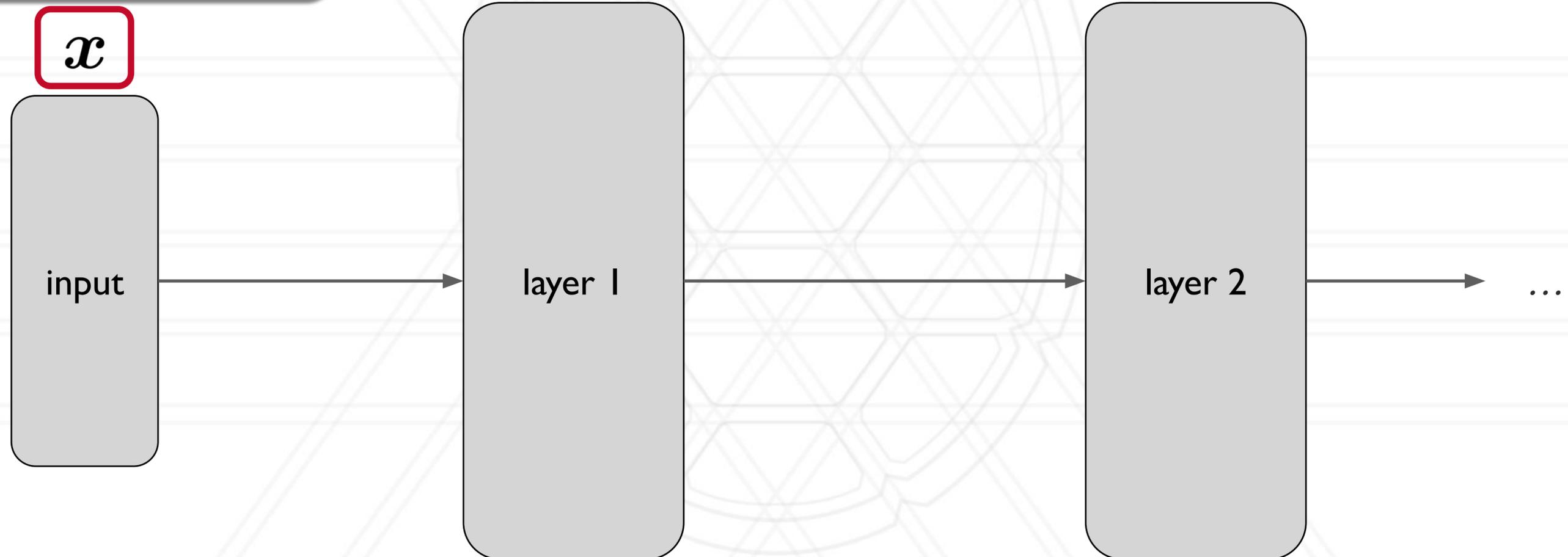


# What's using the memory?

input data – this is generally negligible

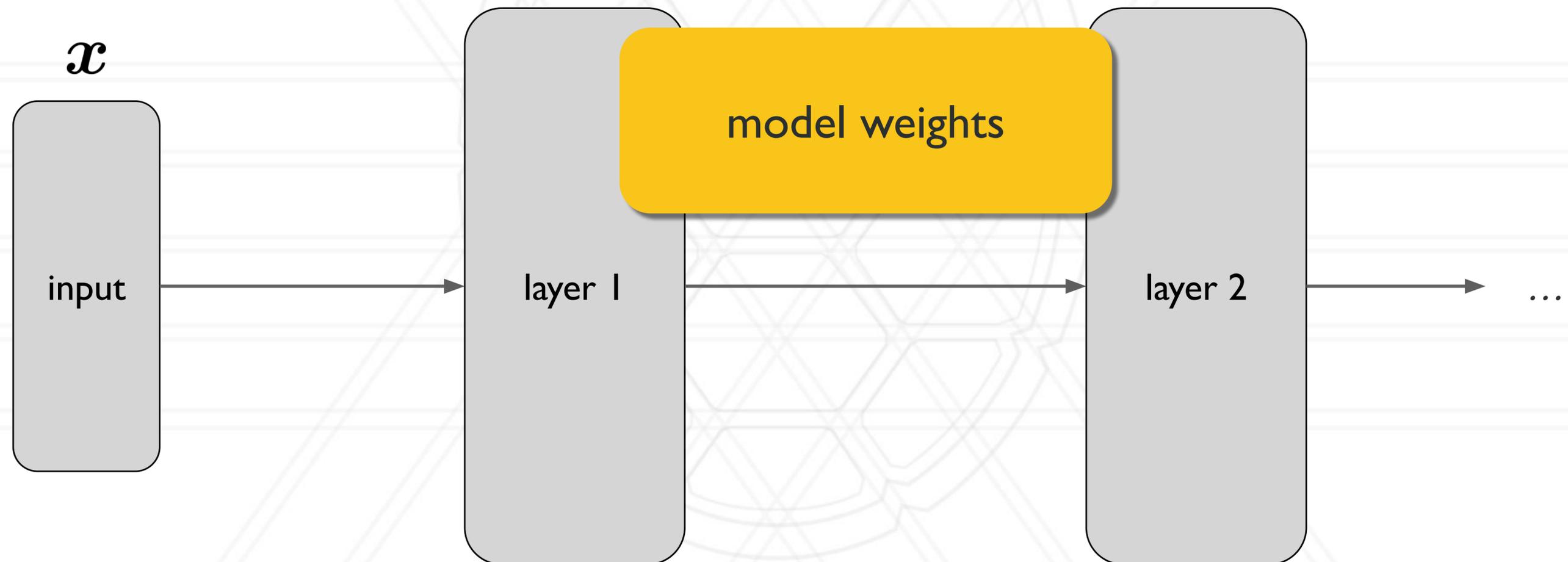
$$\mathbf{h}^{(1)} = \sigma \left( \Theta^{(1)T} \mathbf{x} \right)$$

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# What's using the memory?

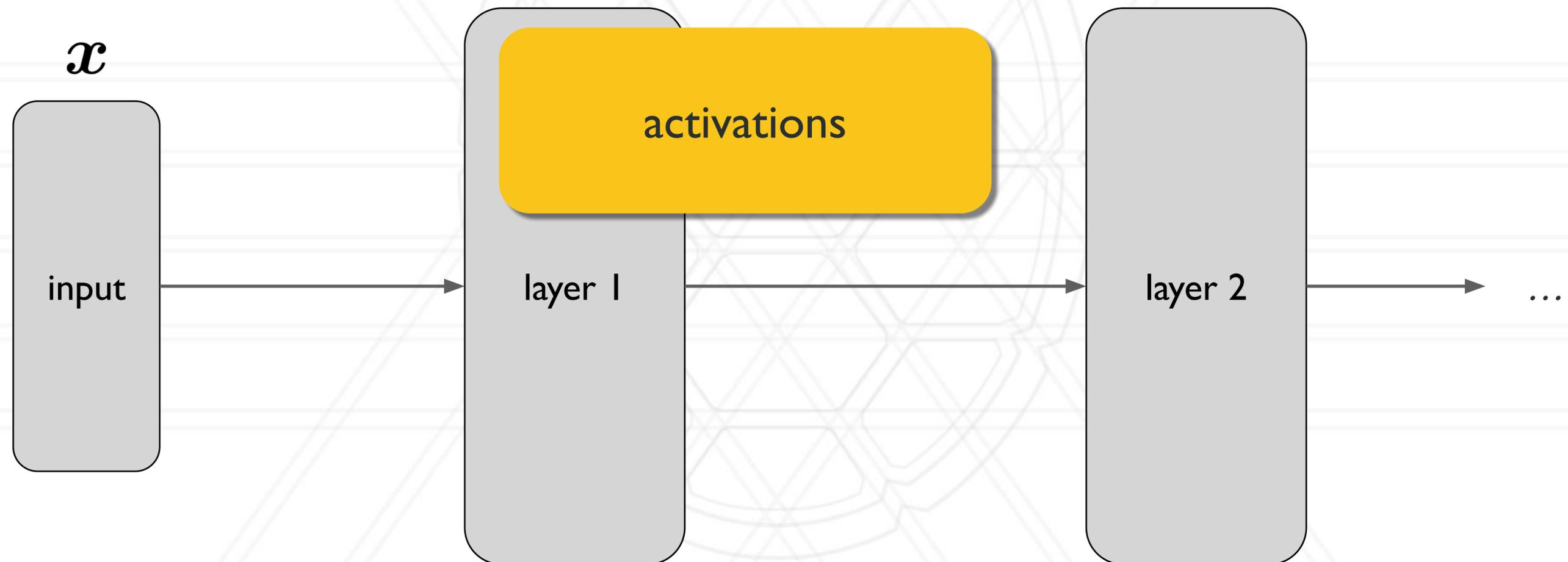
$$h^{(1)} = \sigma \left( \Theta^{(1)T} x \right) \qquad h^{(2)} = \sigma \left( \Theta^{(2)T} h^{(1)} \right)$$



# What's using the memory?

$$\mathbf{h}^{(1)} = \sigma \left( \Theta^{(1)T} \mathbf{x} \right)$$

$$\mathbf{h}^{(2)} = \sigma \left( \Theta^{(2)T} \mathbf{h}^{(1)} \right)$$



# What's using the memory?

- Activation checkpointing can save us some space
- Memory - performance tradeoff

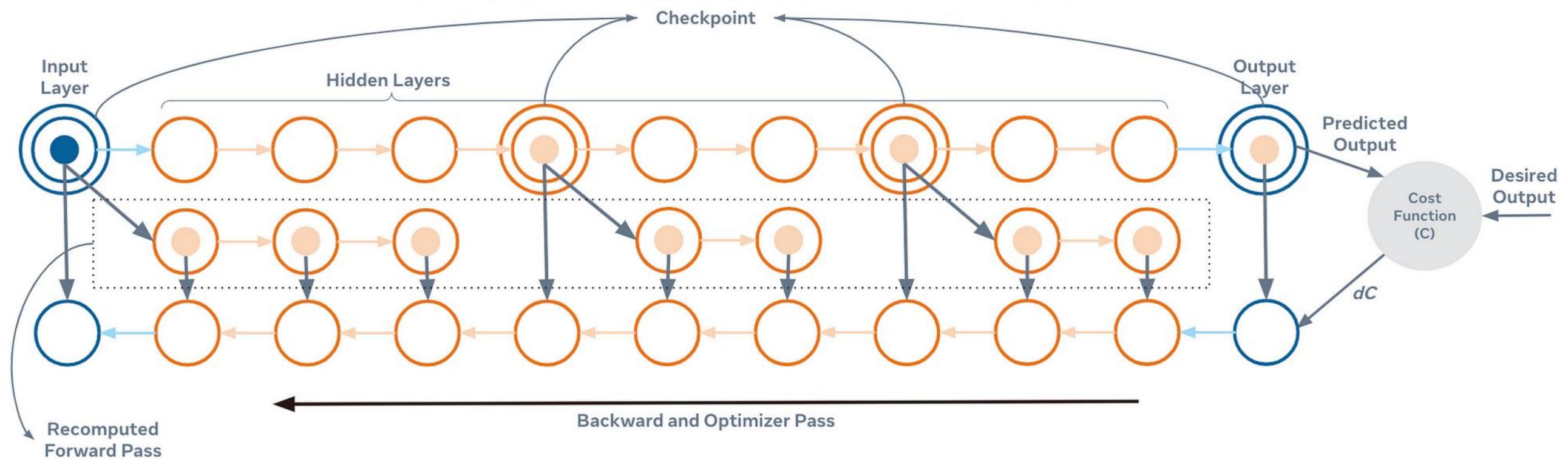
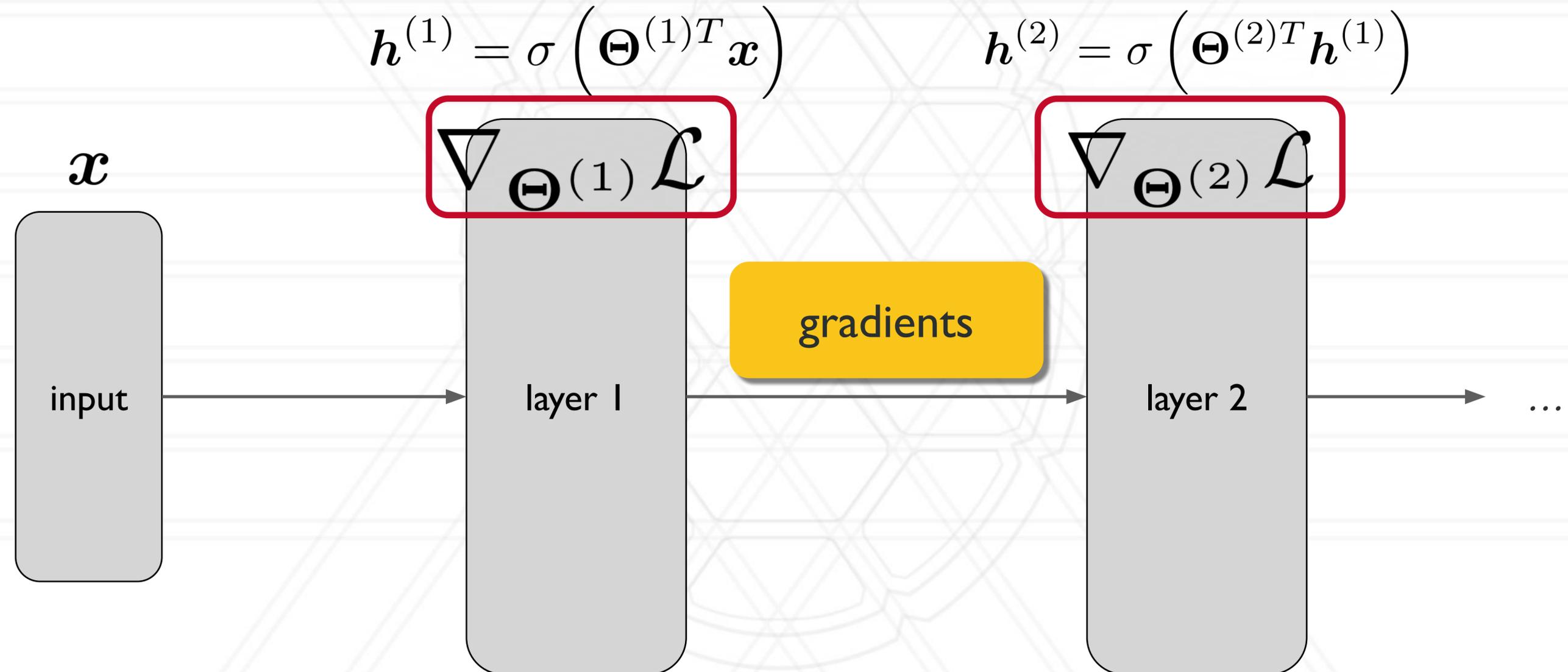
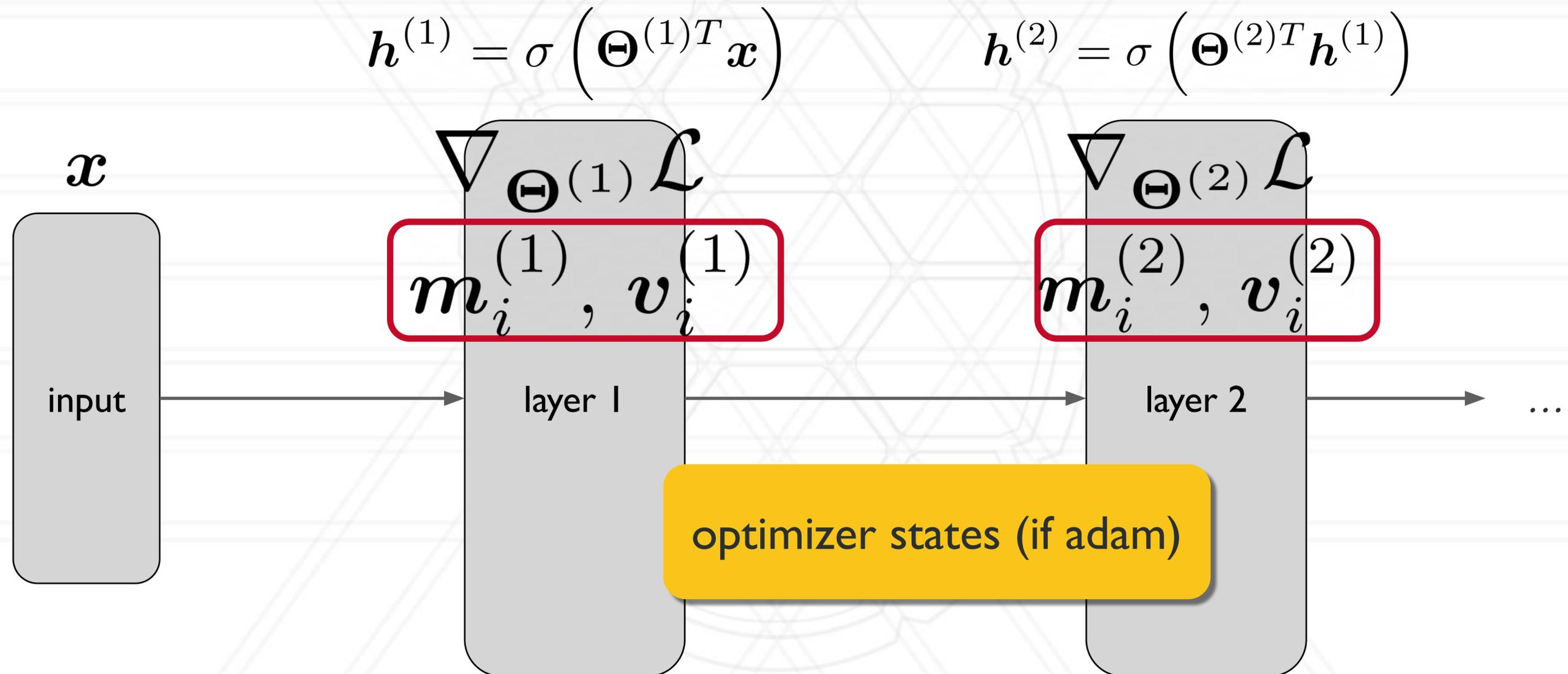


image: <https://shivambharuka.medium.com/deep-learning-a-primer-on-distributed-training-part-1-d0ae0054bb1c>

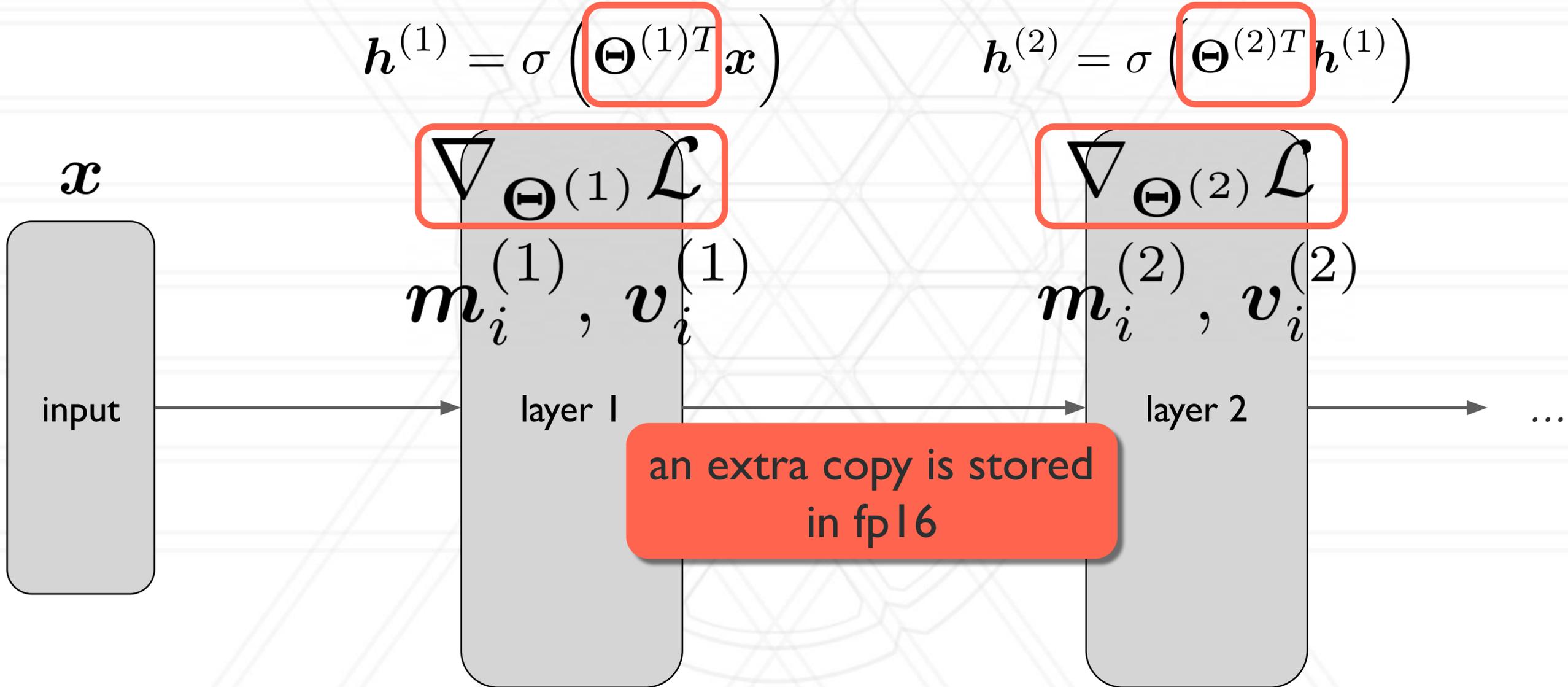
# What's using the memory?



# What's using the memory?



# Mixed Precision Training



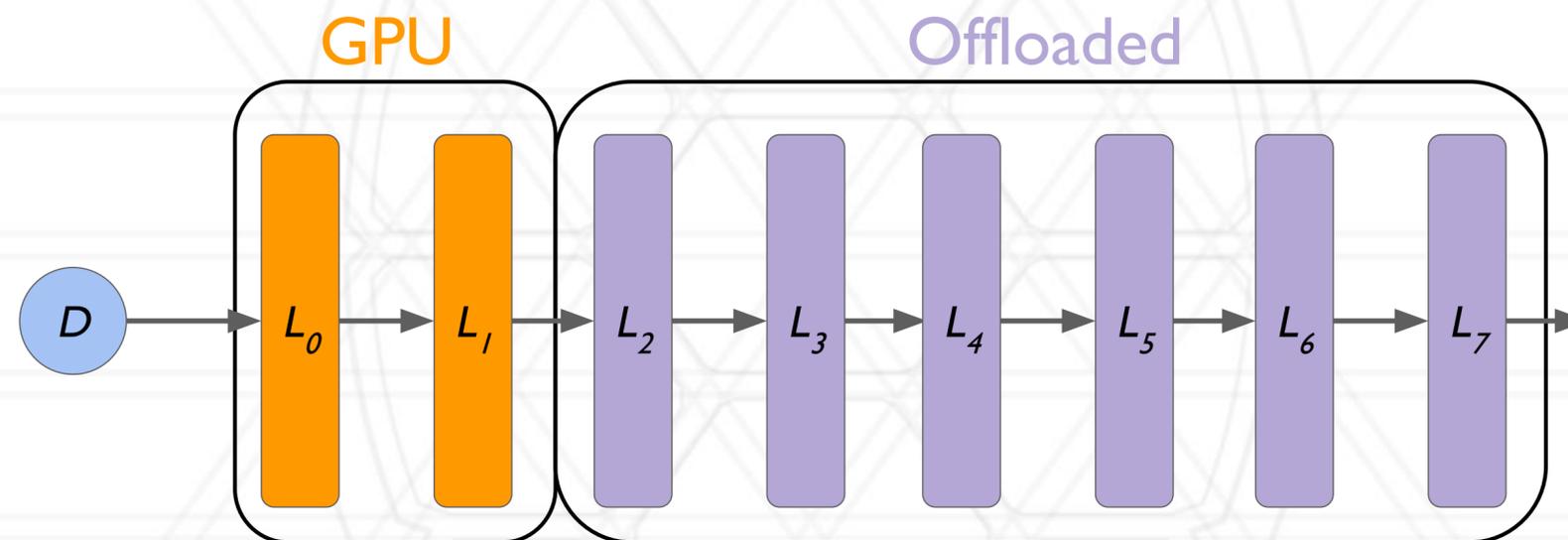
# What's using the memory?

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- Model state; not dependent on batch size, sequence length, etc.
  - Weights, gradients, optimizer states
- Residual state; dependent on input data
  - Activations
  - Can be reduced through activation checkpointing

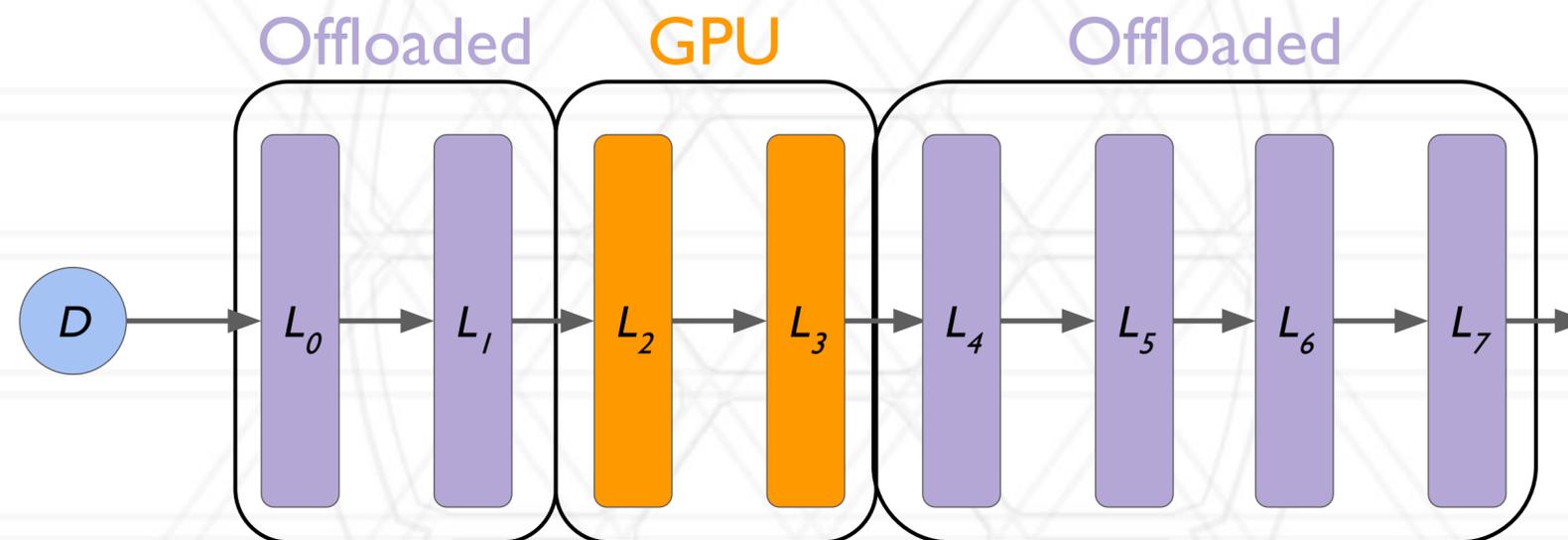
# Naive Offloading

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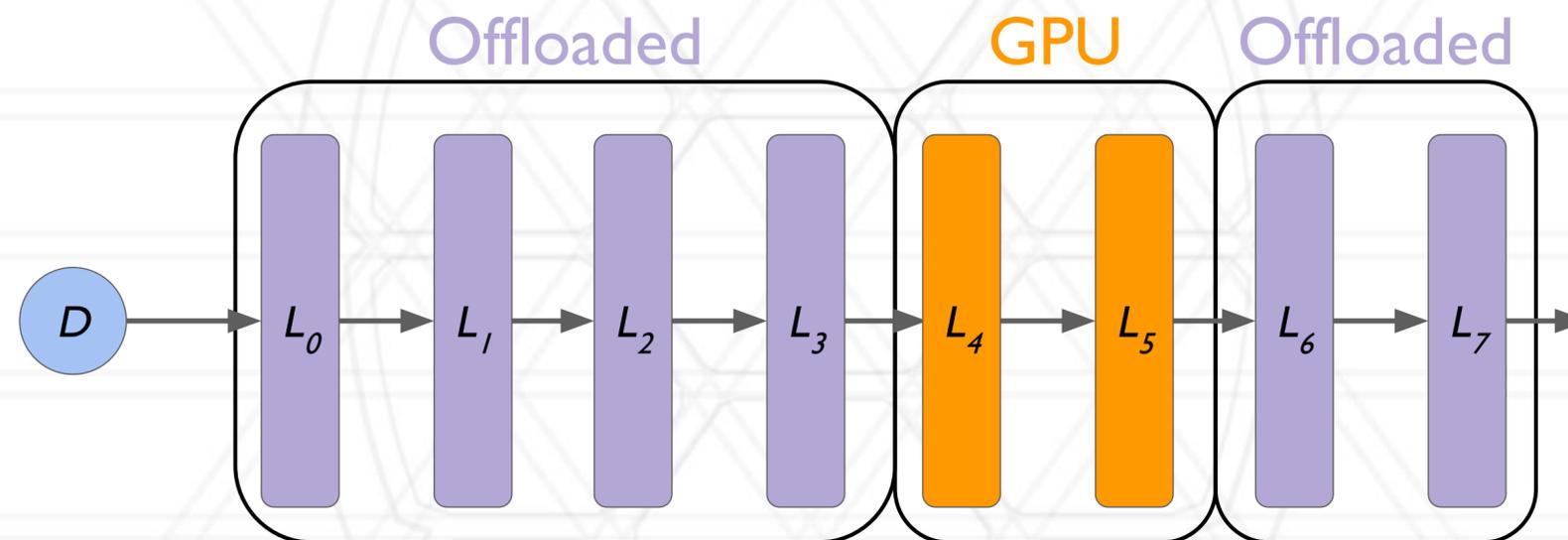
# Naive Offloading

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# Naive Offloading

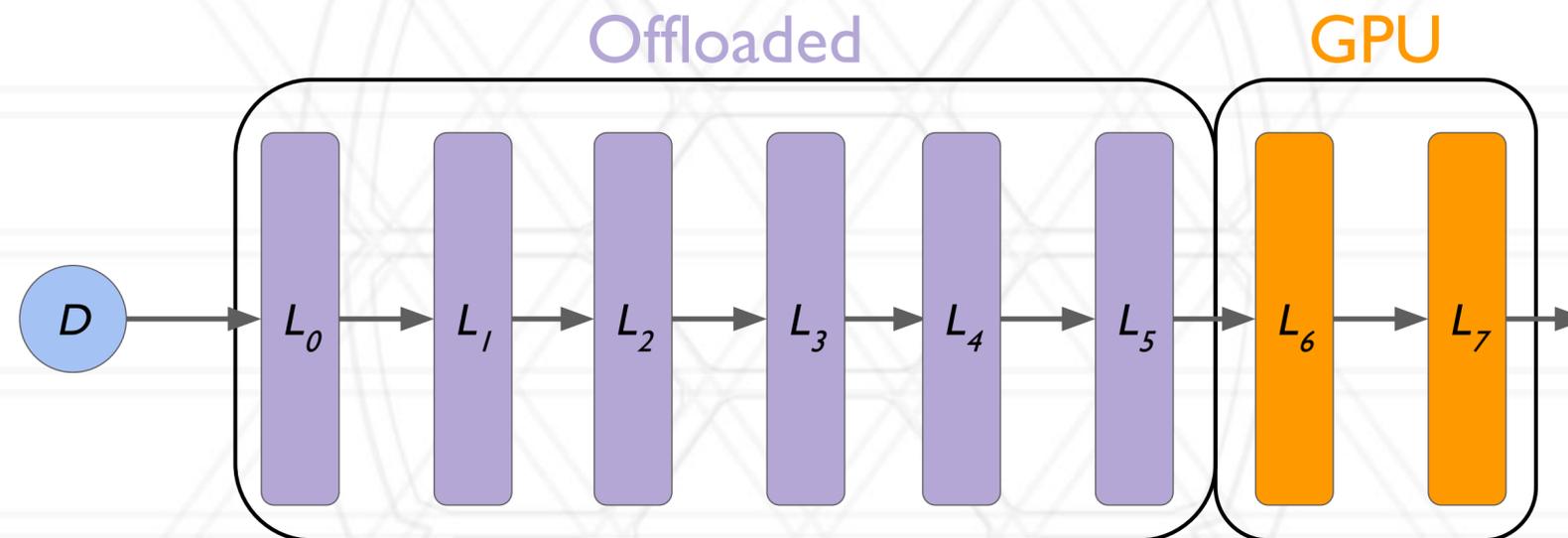
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# Naive Offloading

This is very slow...

How can we improve it?



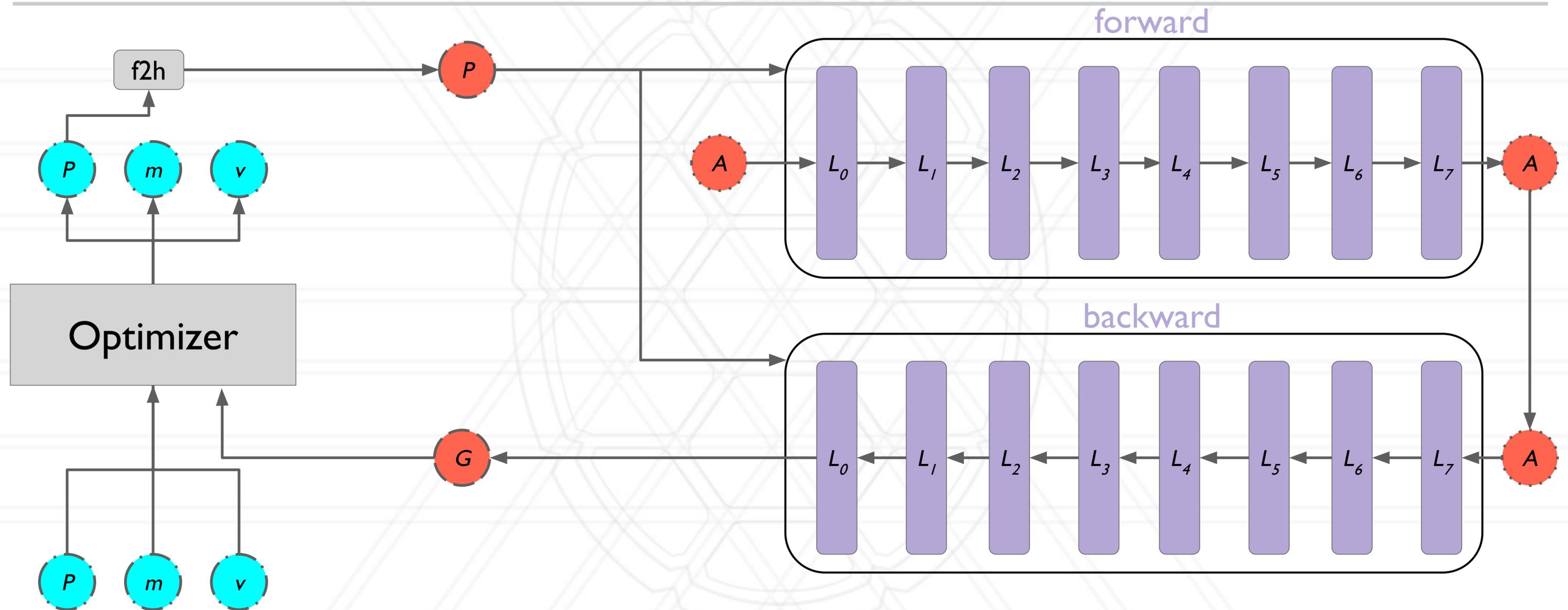
# ZeRO-Offload

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- An earlier work offloading to CPU memory
- Partition training dataflow graph
  - Put less intensive compute on CPU
  - Minimize CPU-GPU copying

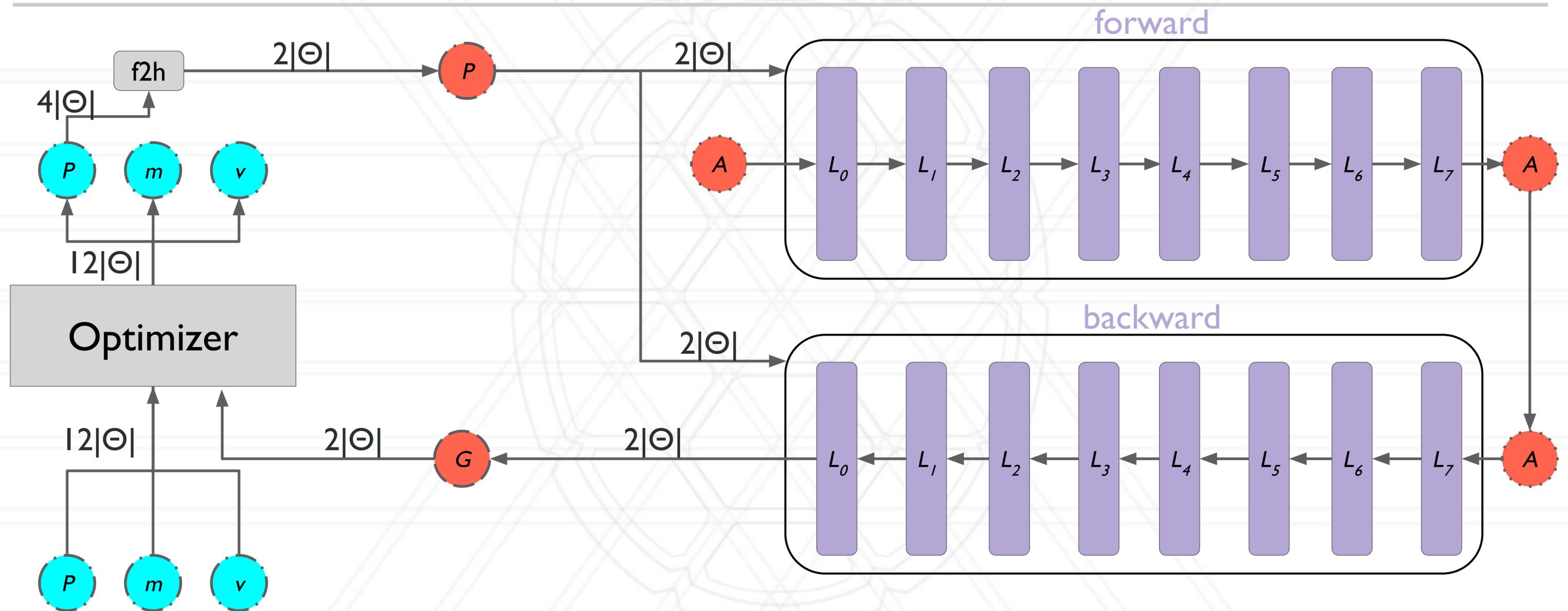
J. Ren, et. al., “ZeRO-Offload: Democratizing Billion-Scale Model Training” 2021

# ZeRO-Offload



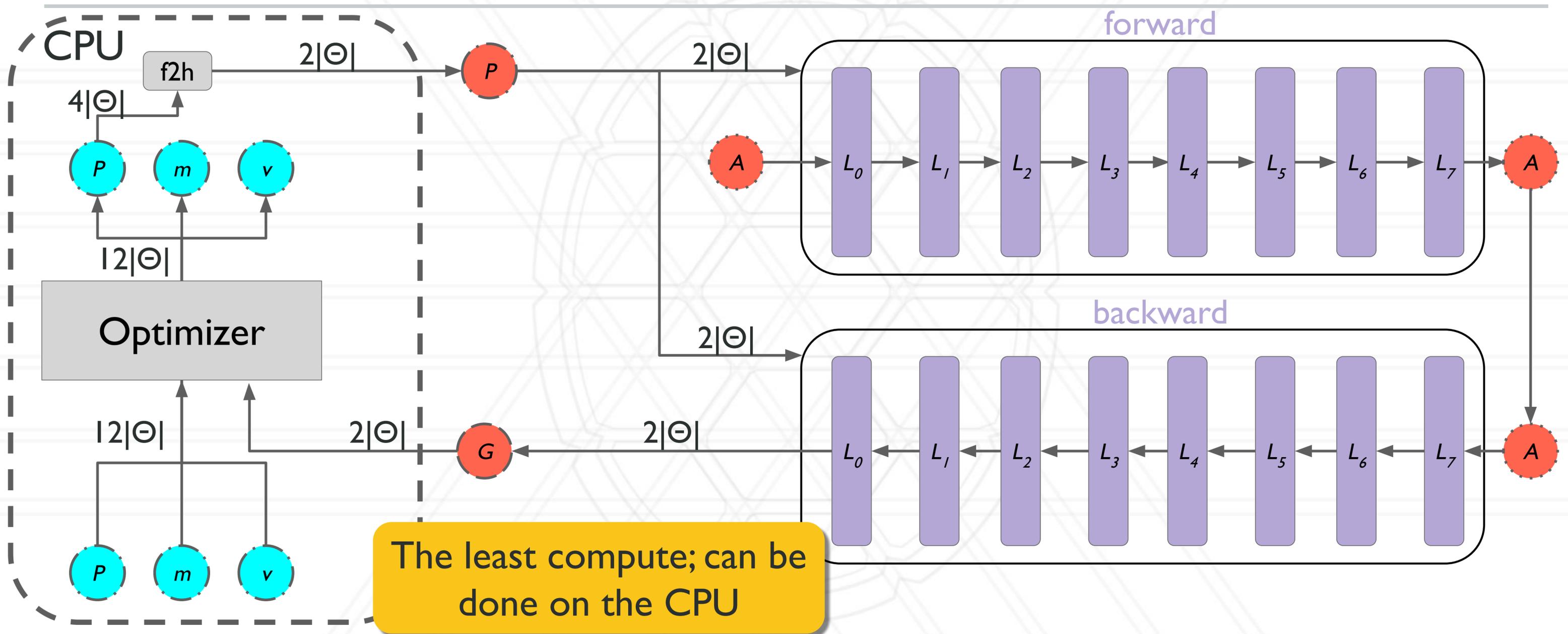
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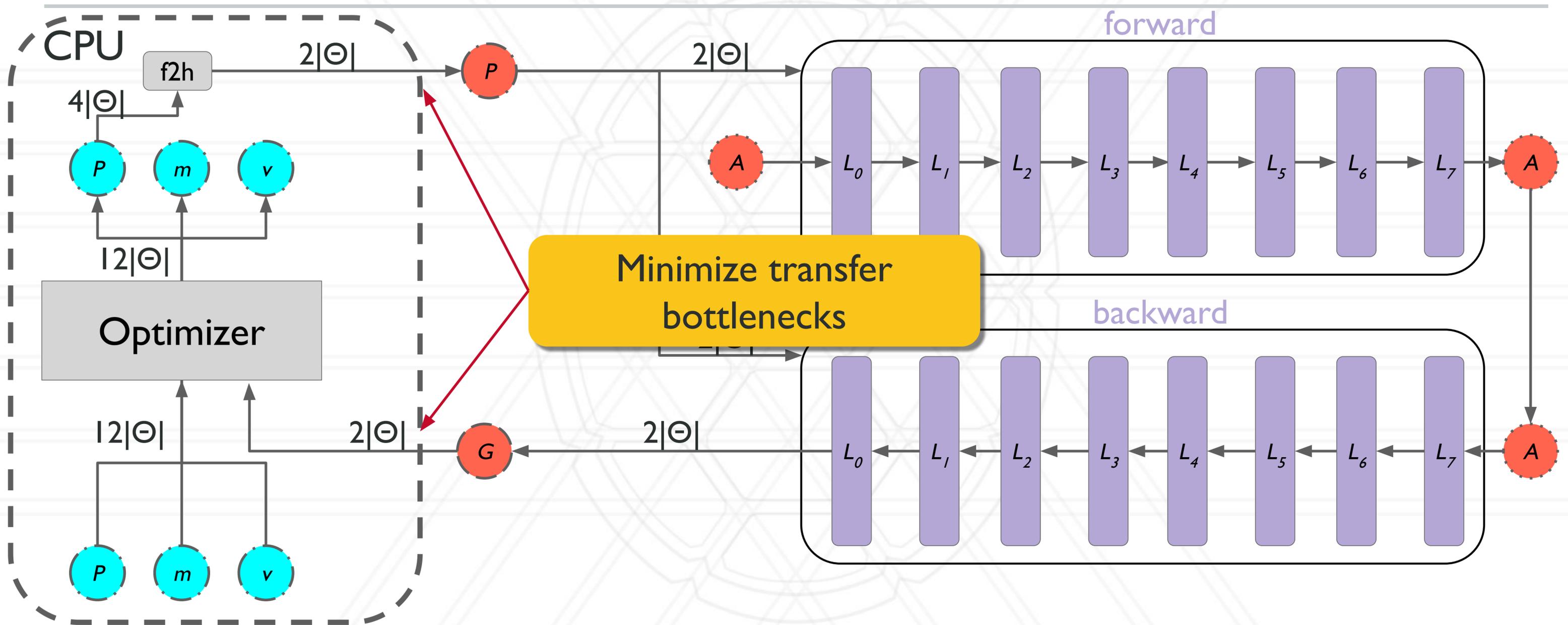
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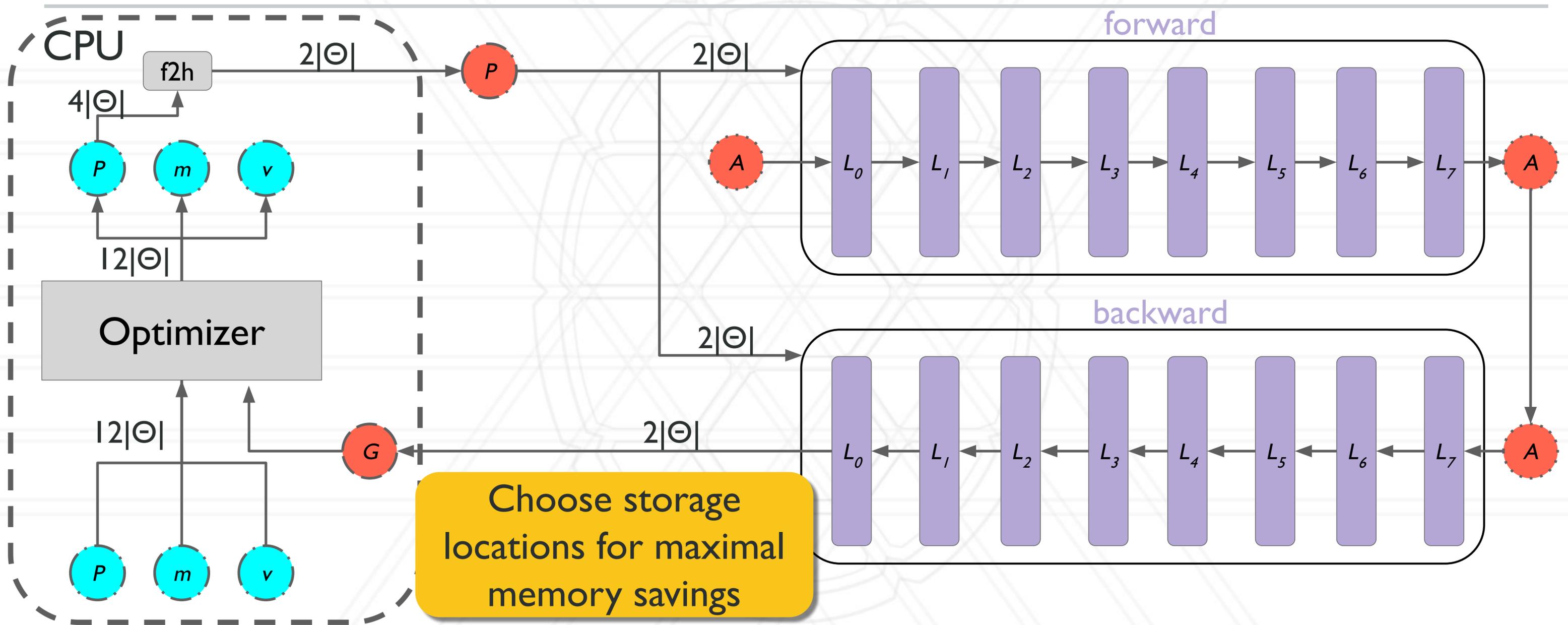
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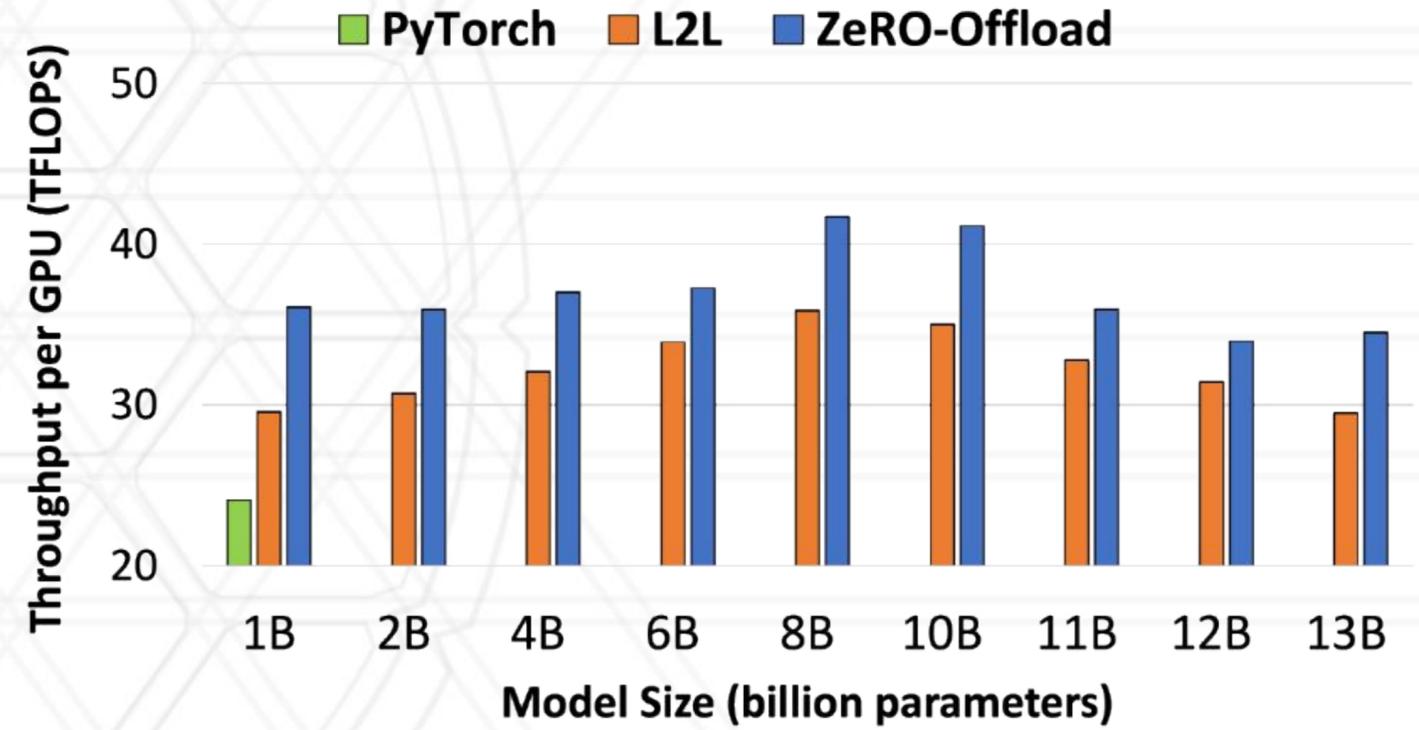
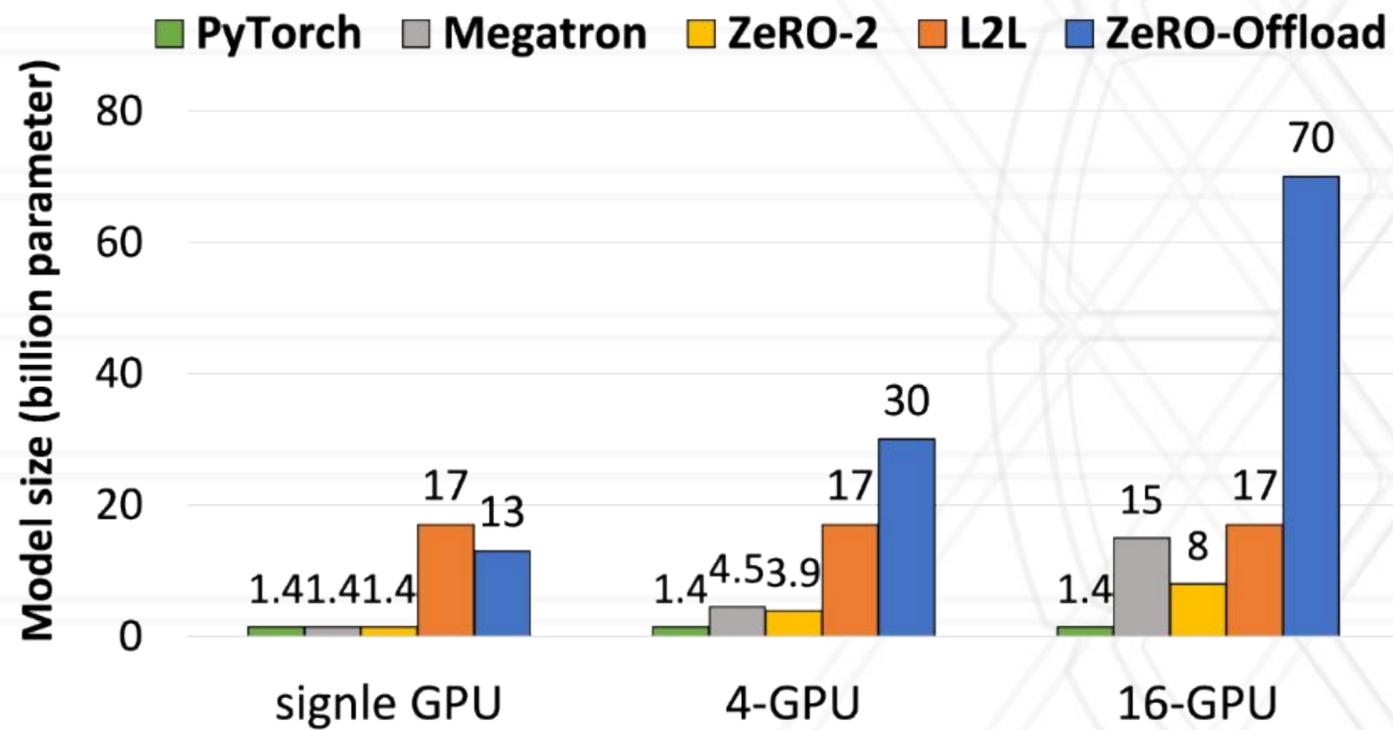
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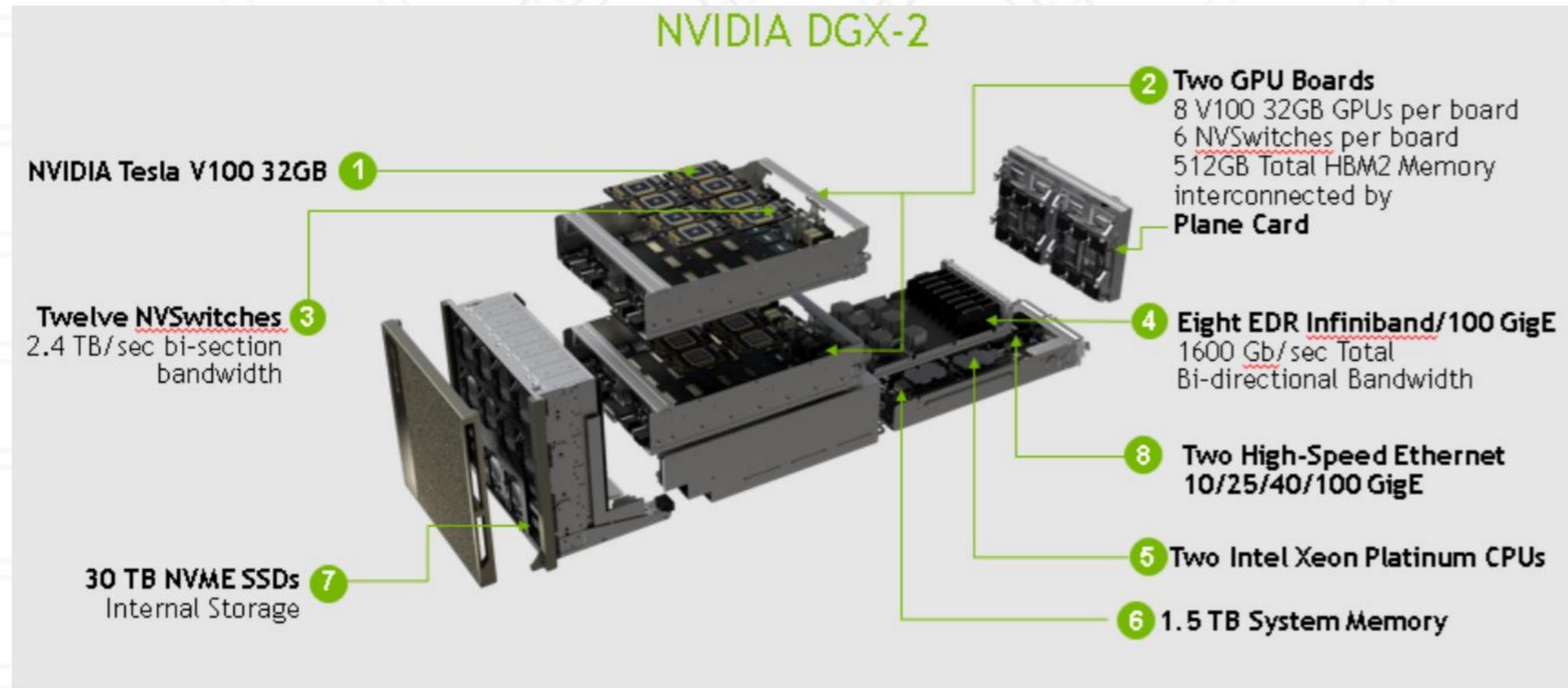
# Zero-Infinity

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- Modern HPC clusters have lots of memory per node
  - DGX-2
    - 512 GB GPU Memory
    - 1.5 TB CPU Memory
    - 30 TB NVMe Storage
- GPT-3 requires ~2-4 TB to fine-tune
  - Do we need multiple nodes?
  - Could we use all of the available memory to train larger models?

S. Rajbhandari, et. al., “ZeRO-Infinity: Breaking the GPU Memory Wall for Extreme Scale Deep Learning” SC ‘21

# DGX-2



S. Rajbhandari, et. al., “ZeRO-Infinity: Breaking the GPU Memory Wall for Extreme Scale Deep Learning” SC ‘21

# Built on Top of ZeRO

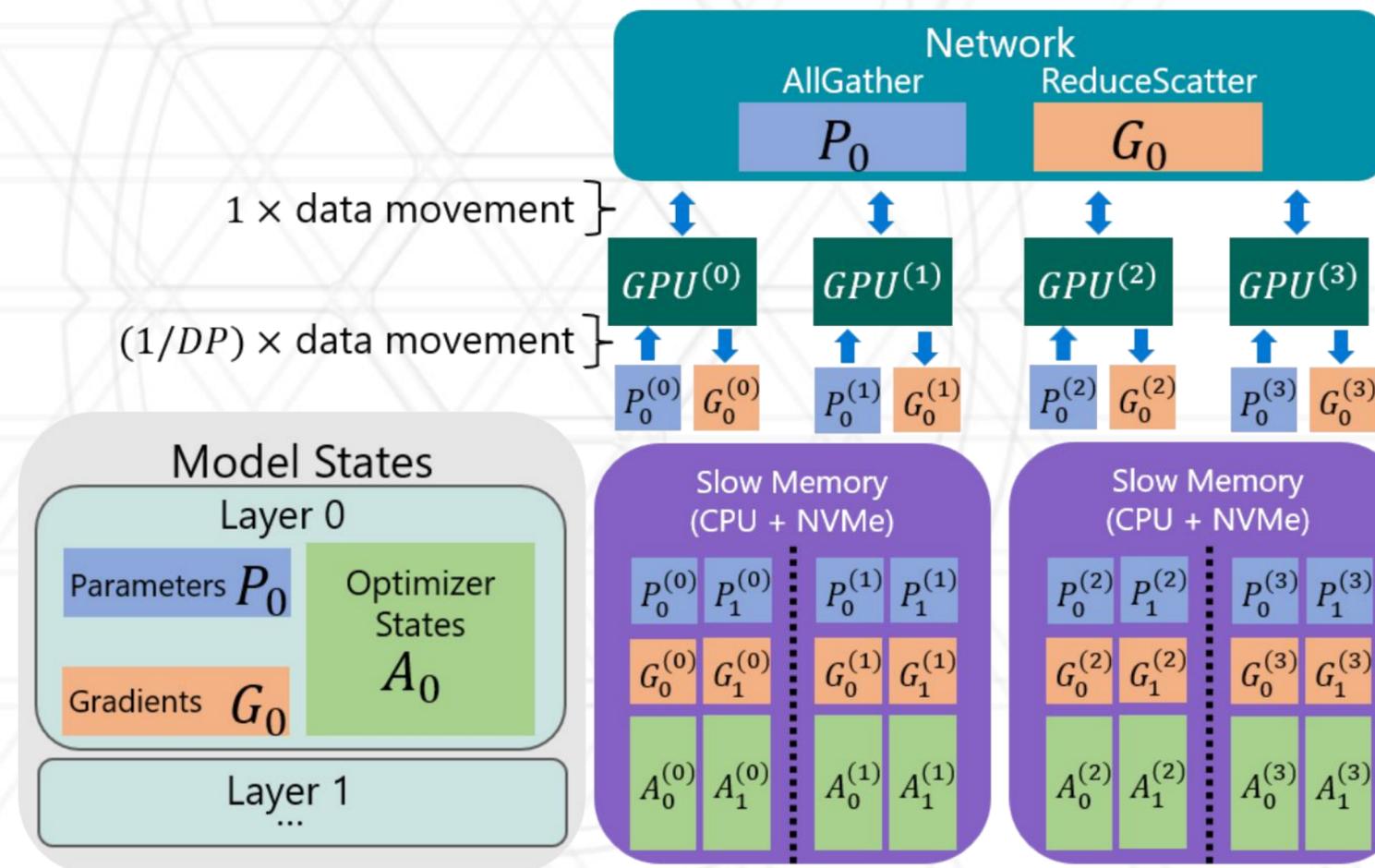
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- Deepspeed ZeRO is a precursor to FSDP with 3 stages
  - Stage 1: Split optimizer states
  - Stage 2: Split optimizer states + gradients
  - Stage 3: Split optimizer states + gradients + parameters
- No code refactoring!

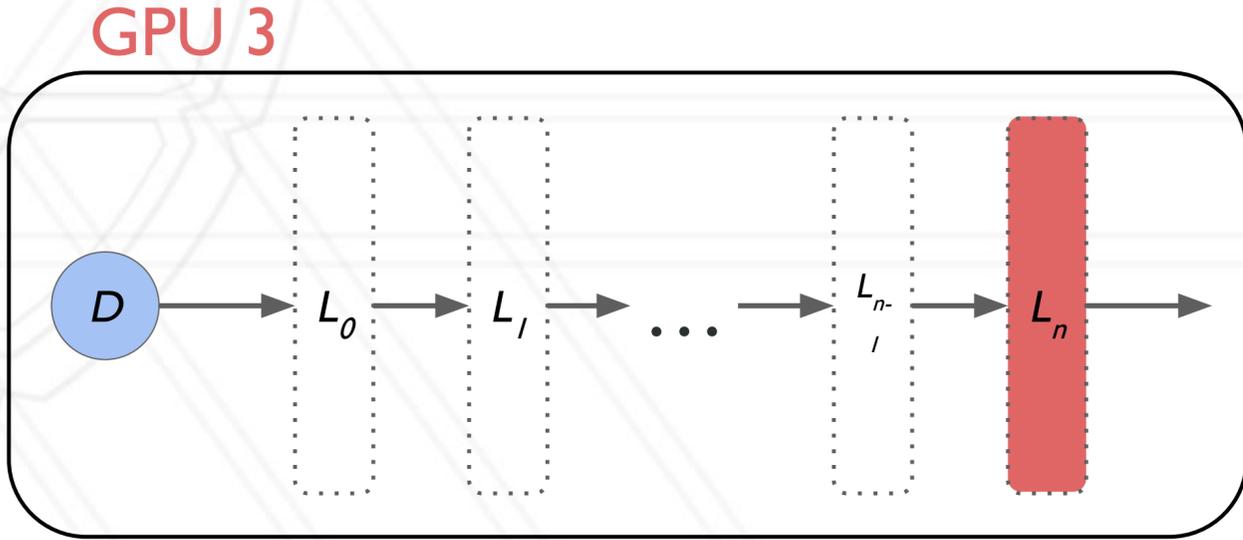
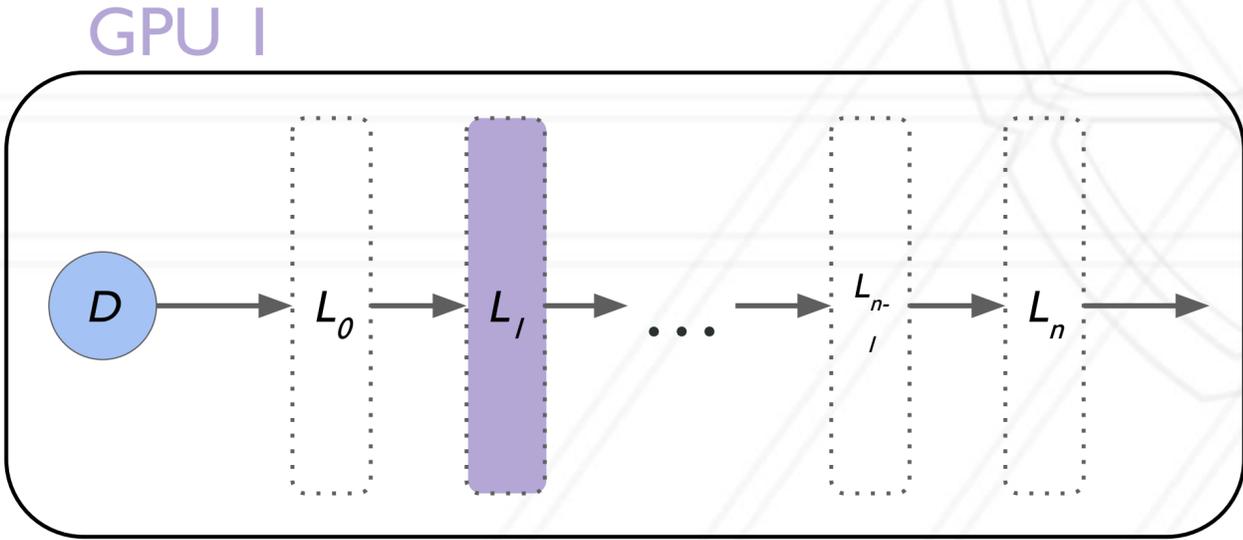
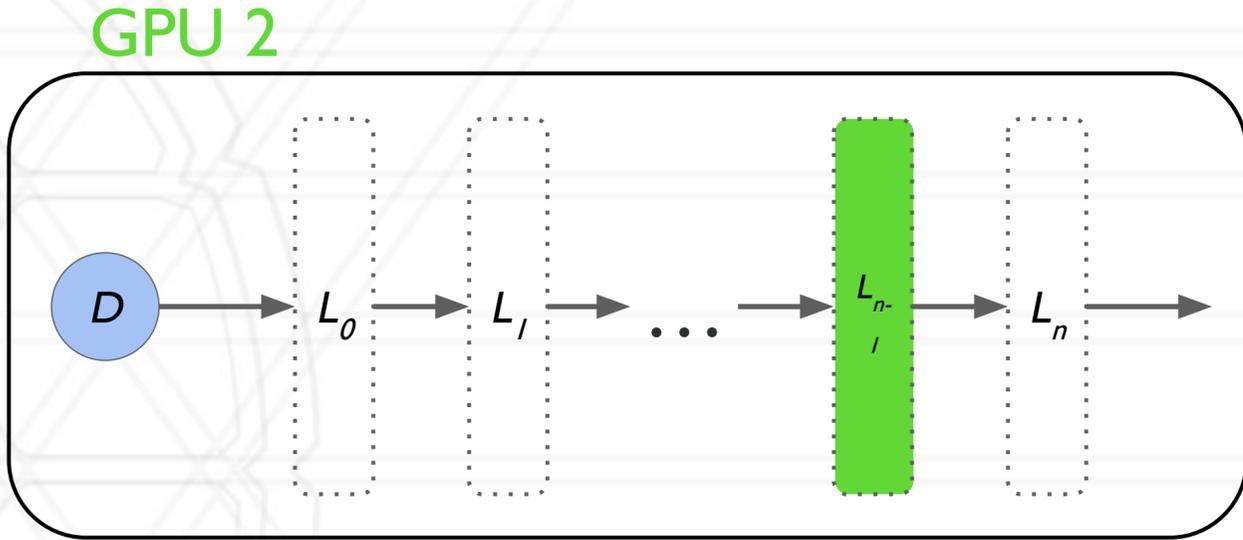
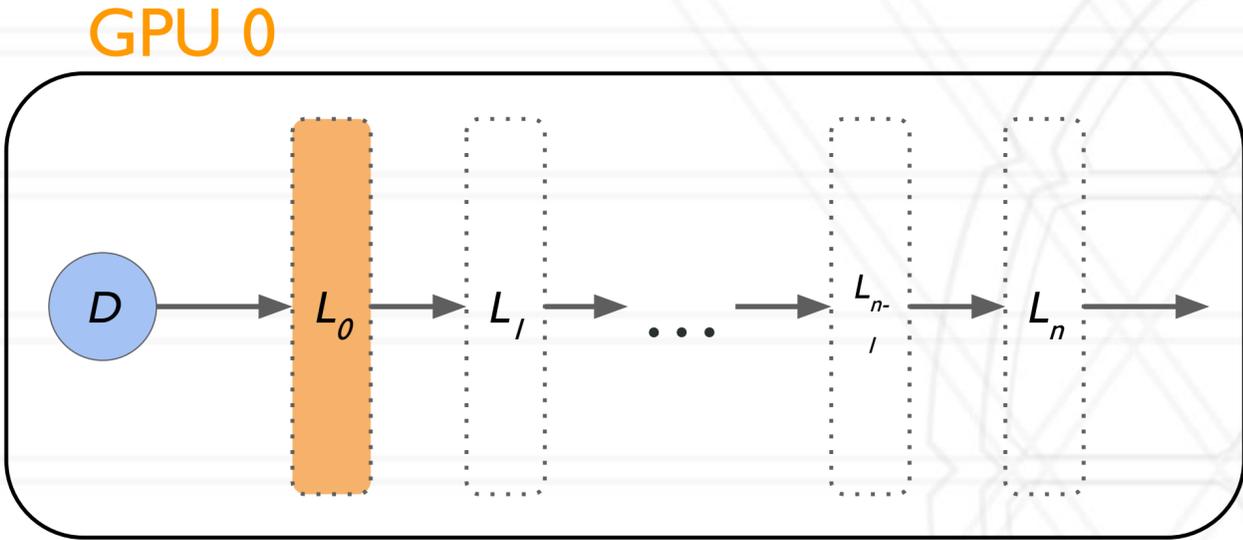
# Offloading Parameters in ZeRO

- So can we just offload ZeRO parameters to CPU/NVMe?

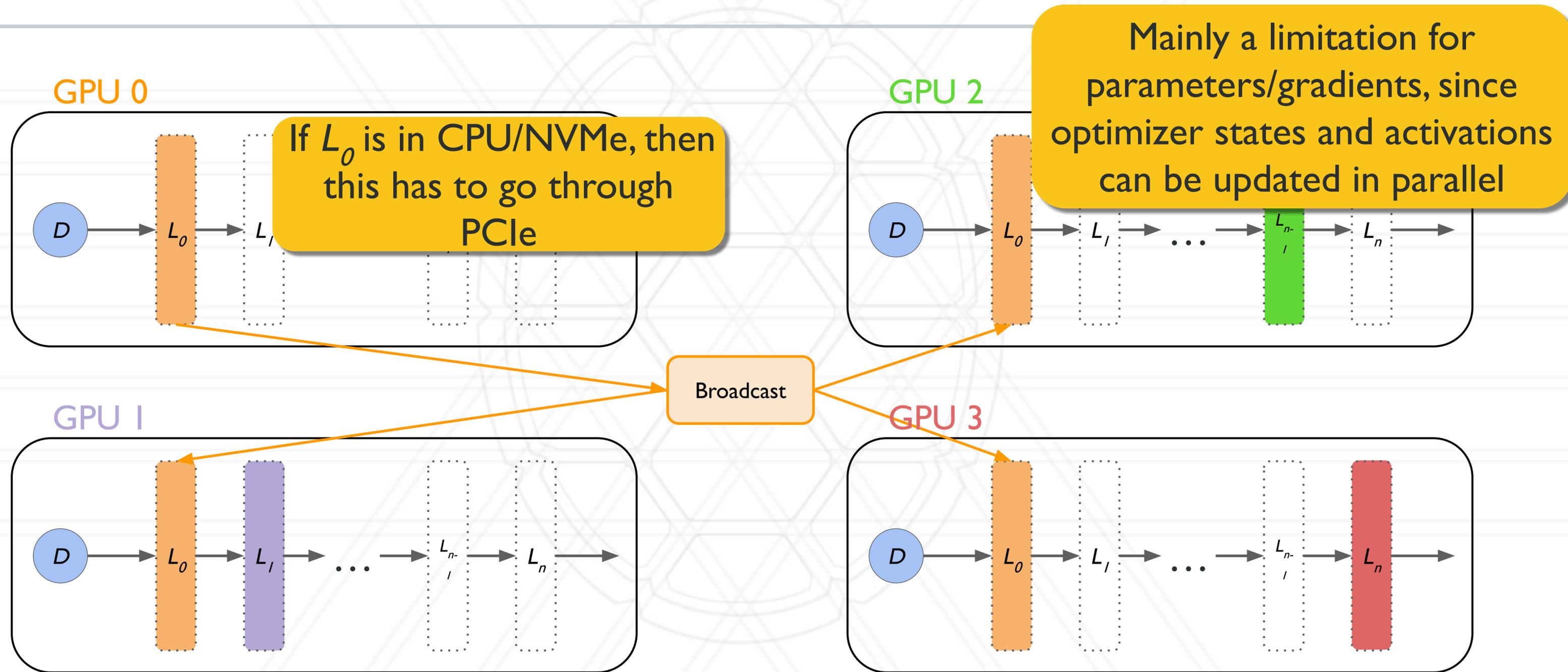
This will be very slow!



# Limited by PCI Bandwidth

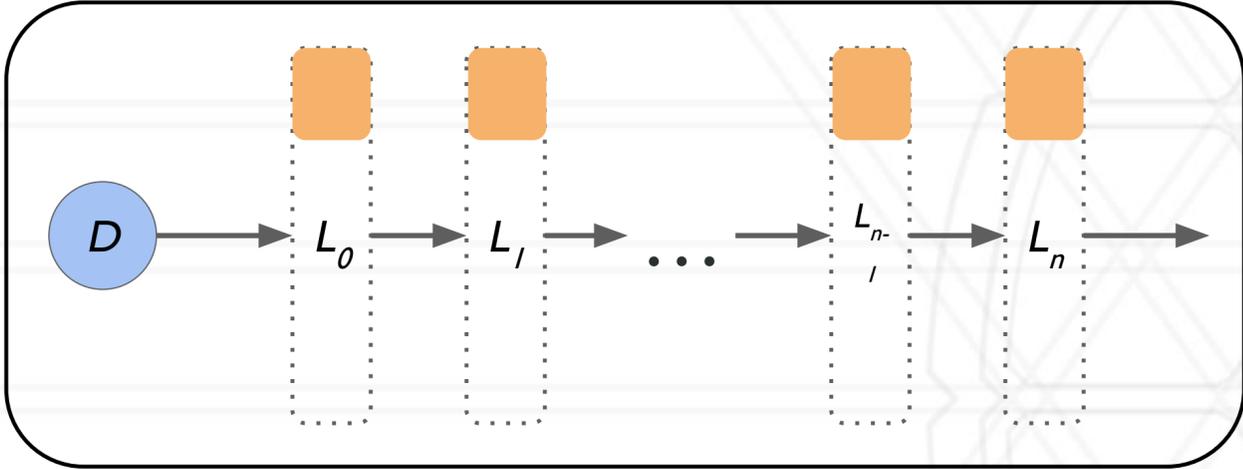


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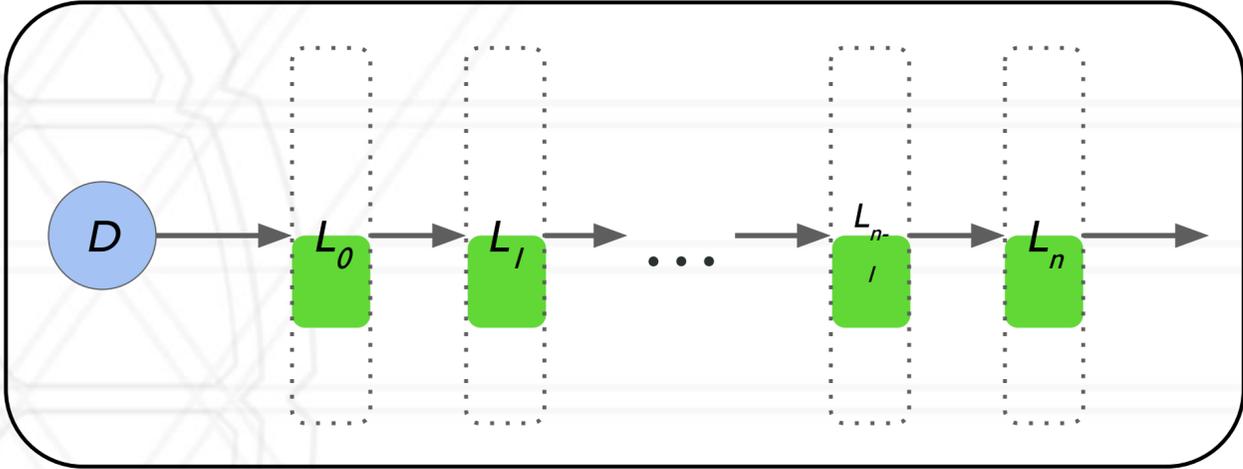


# Bandwidth Centric Partitioning

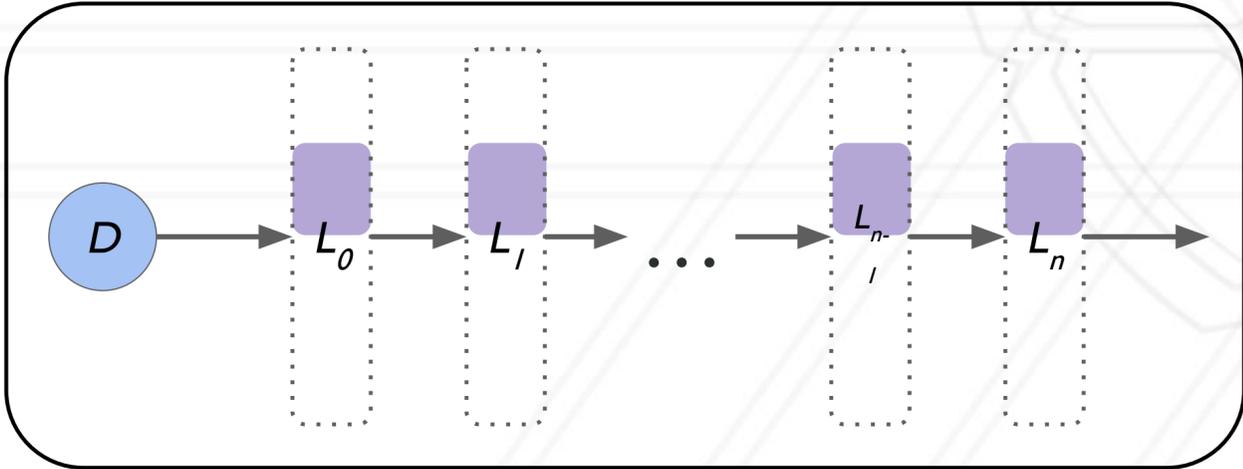
GPU 0



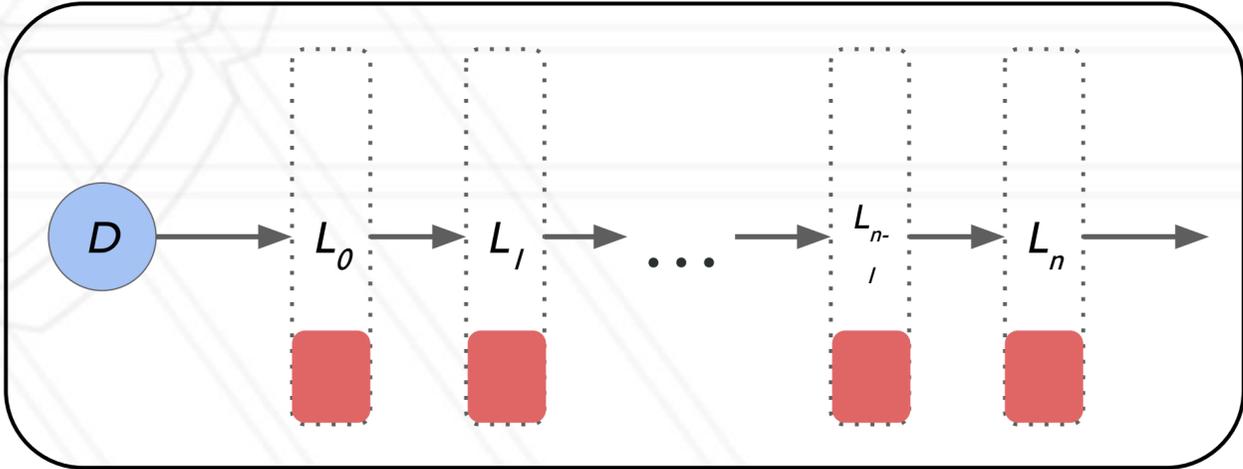
GPU 2



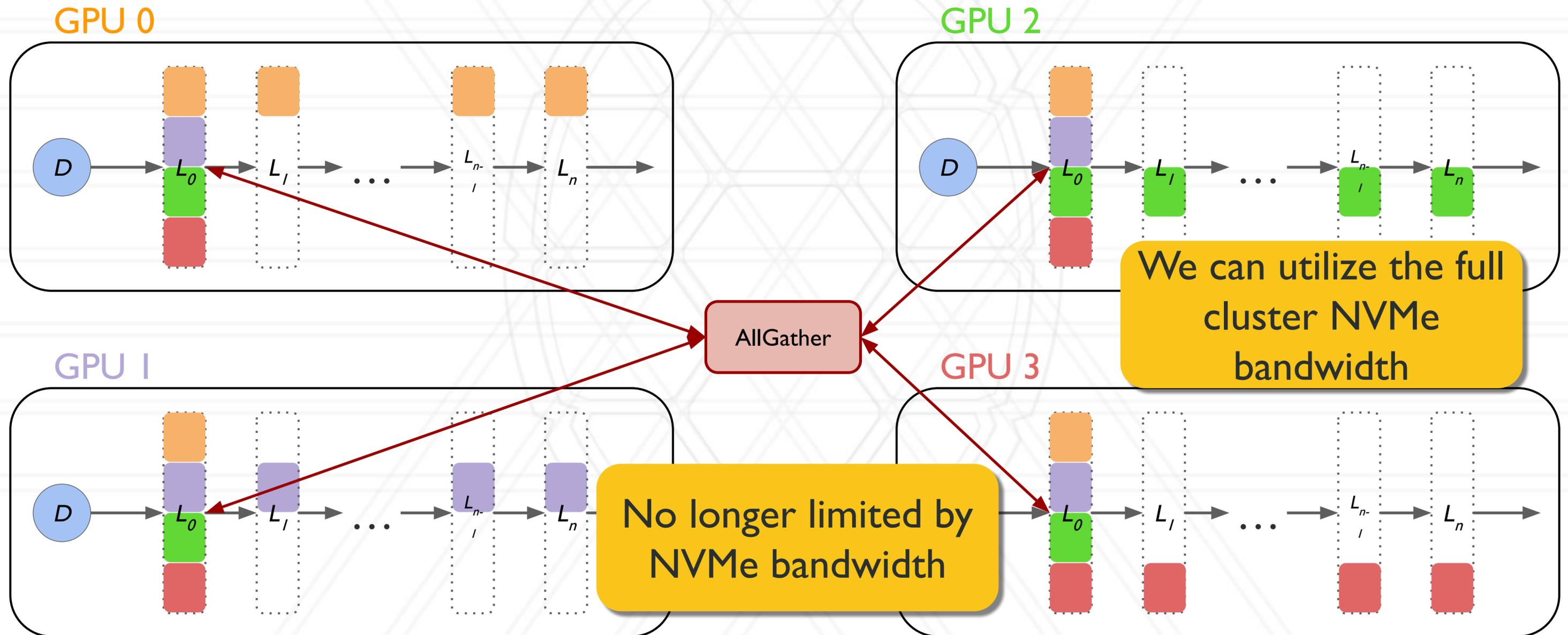
GPU 1



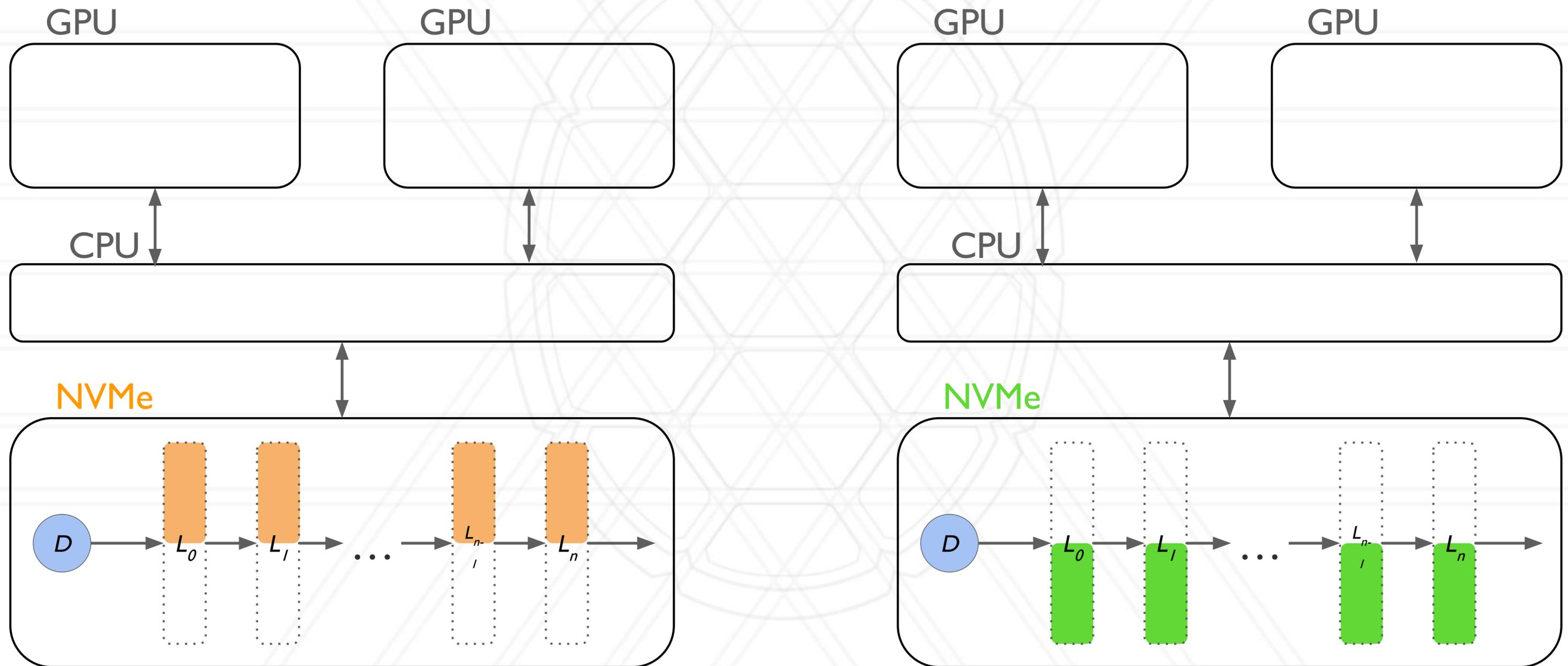
GPU 3



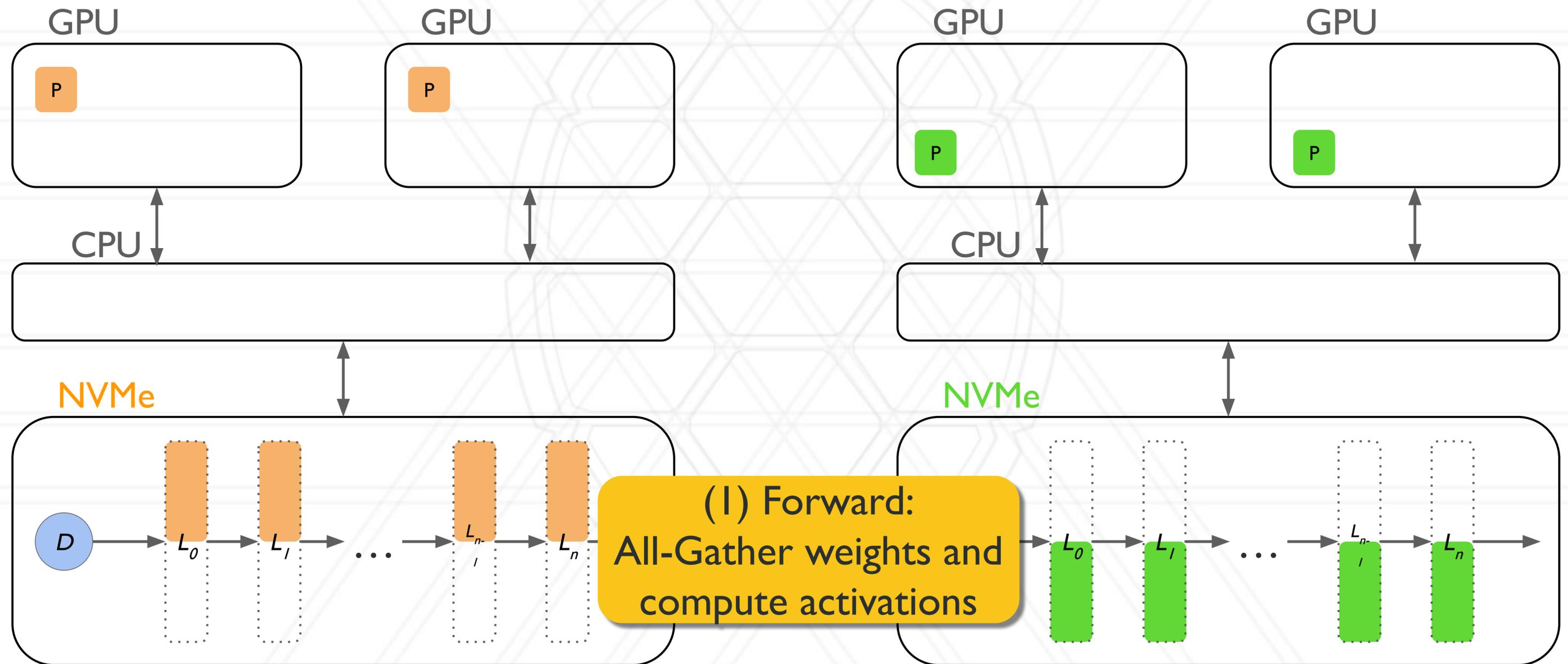
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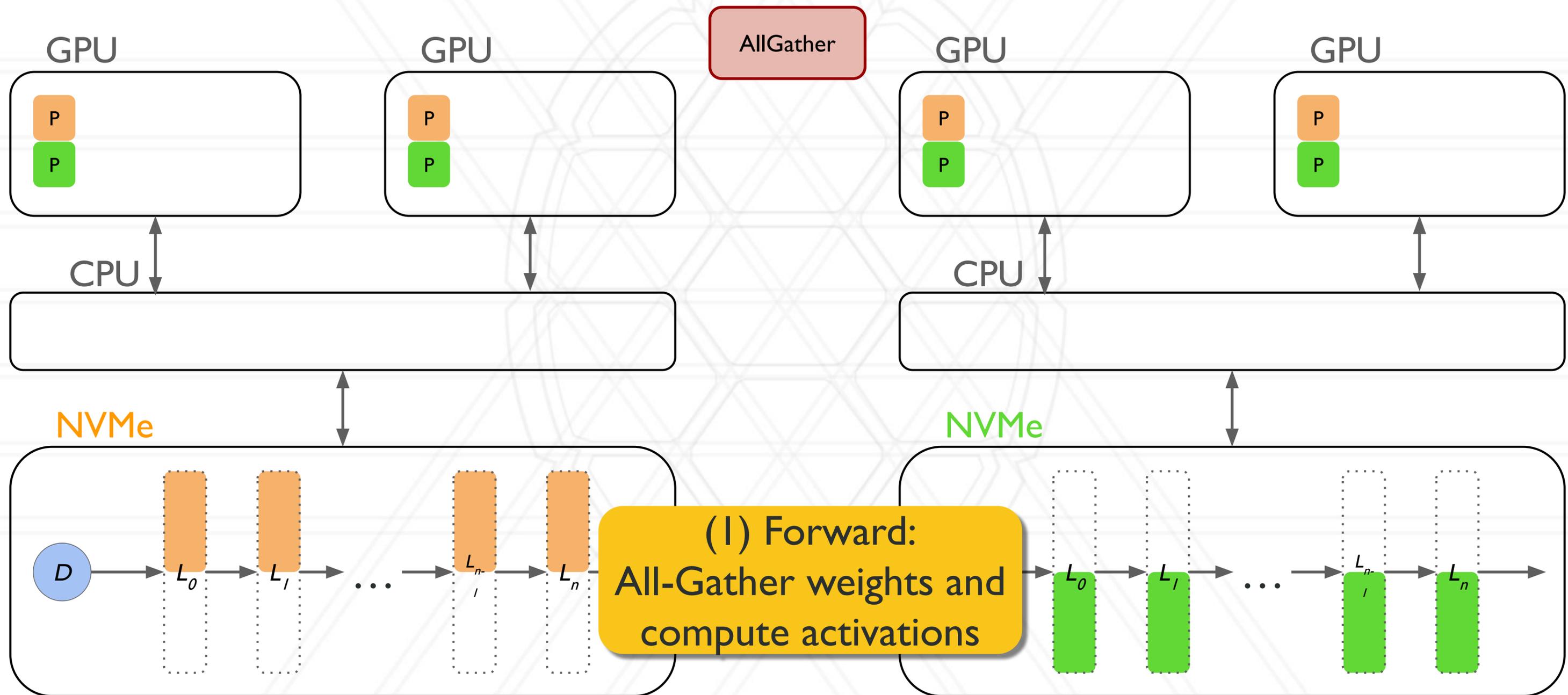
# ZeRO Infinity Algorithm



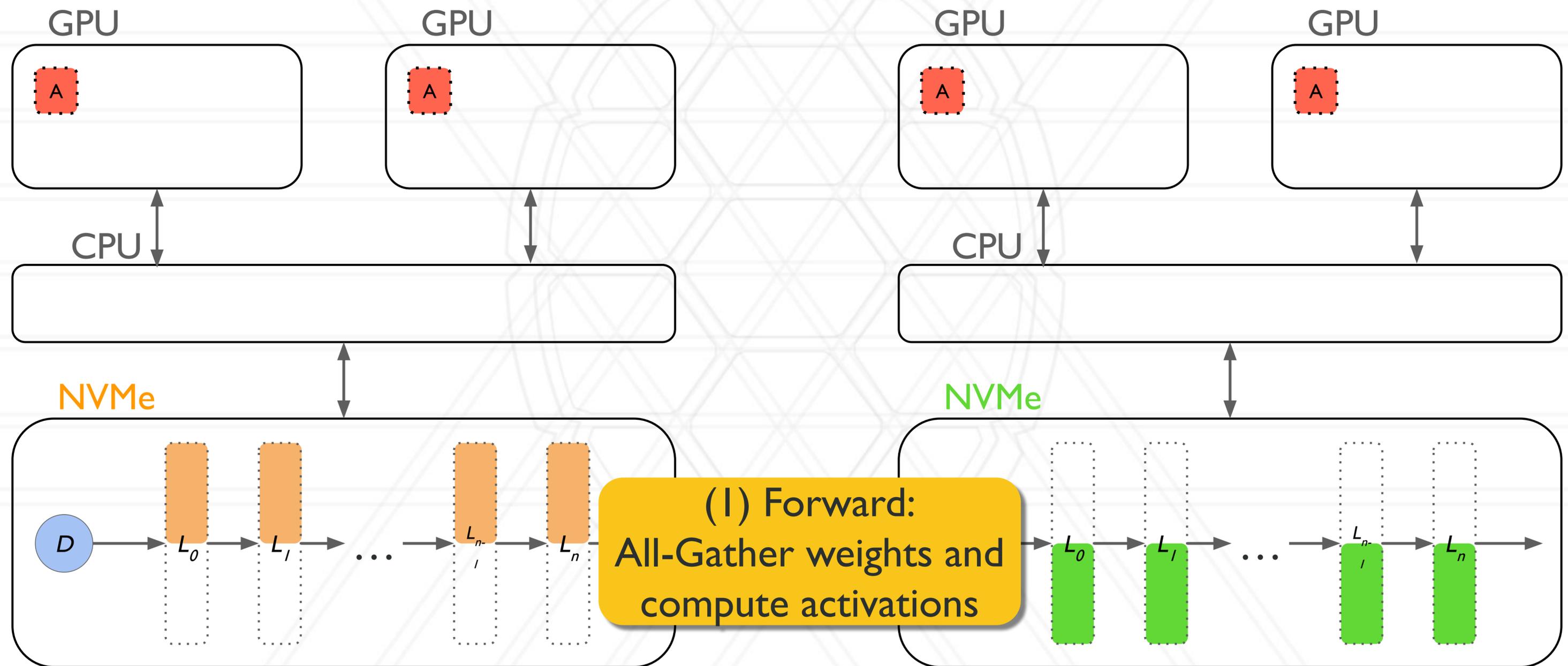
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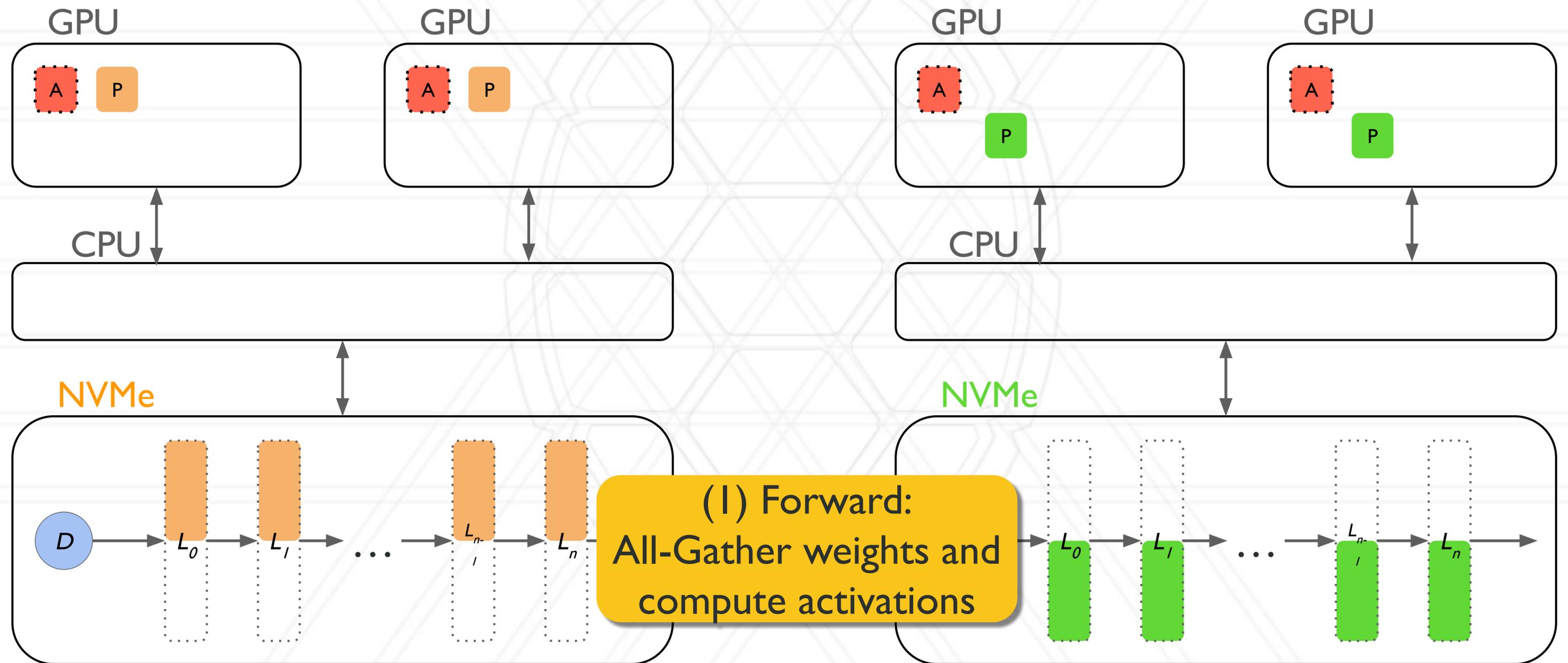
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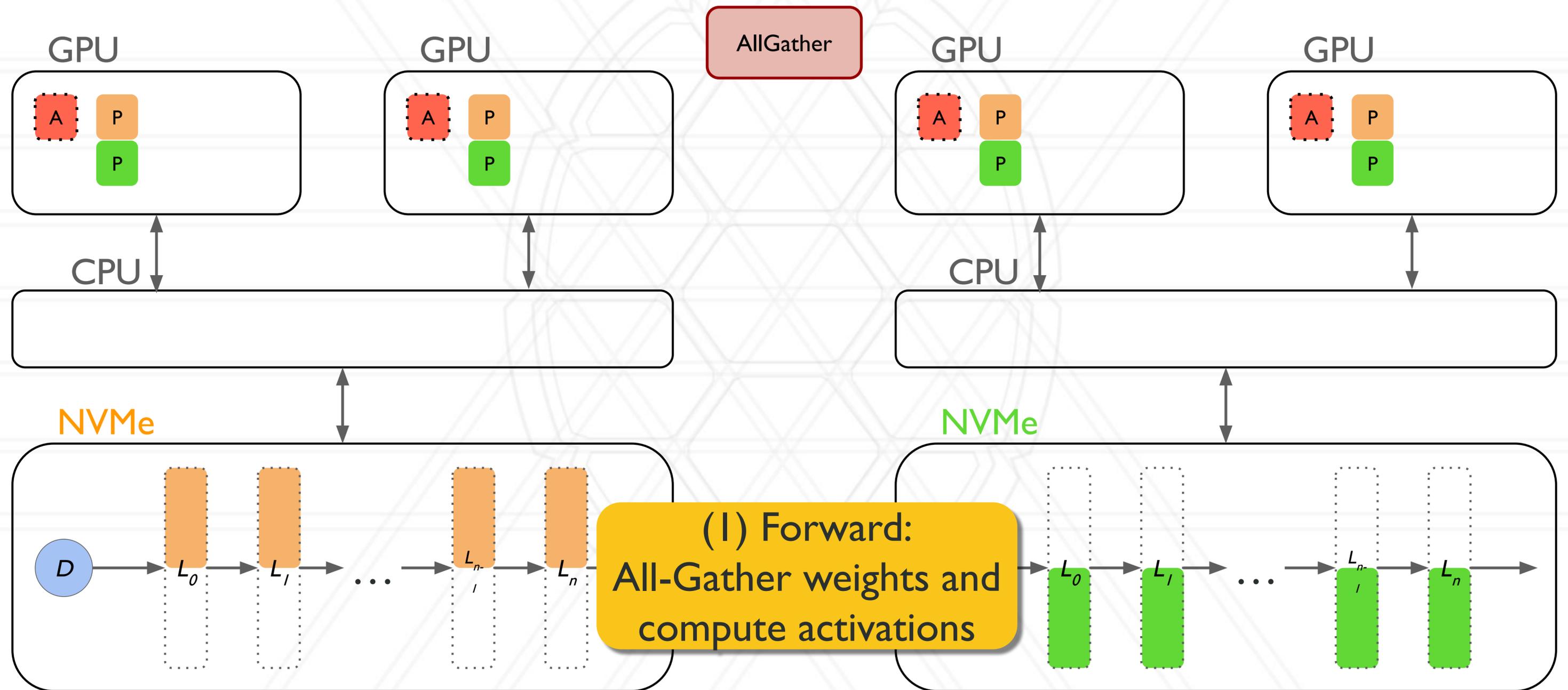
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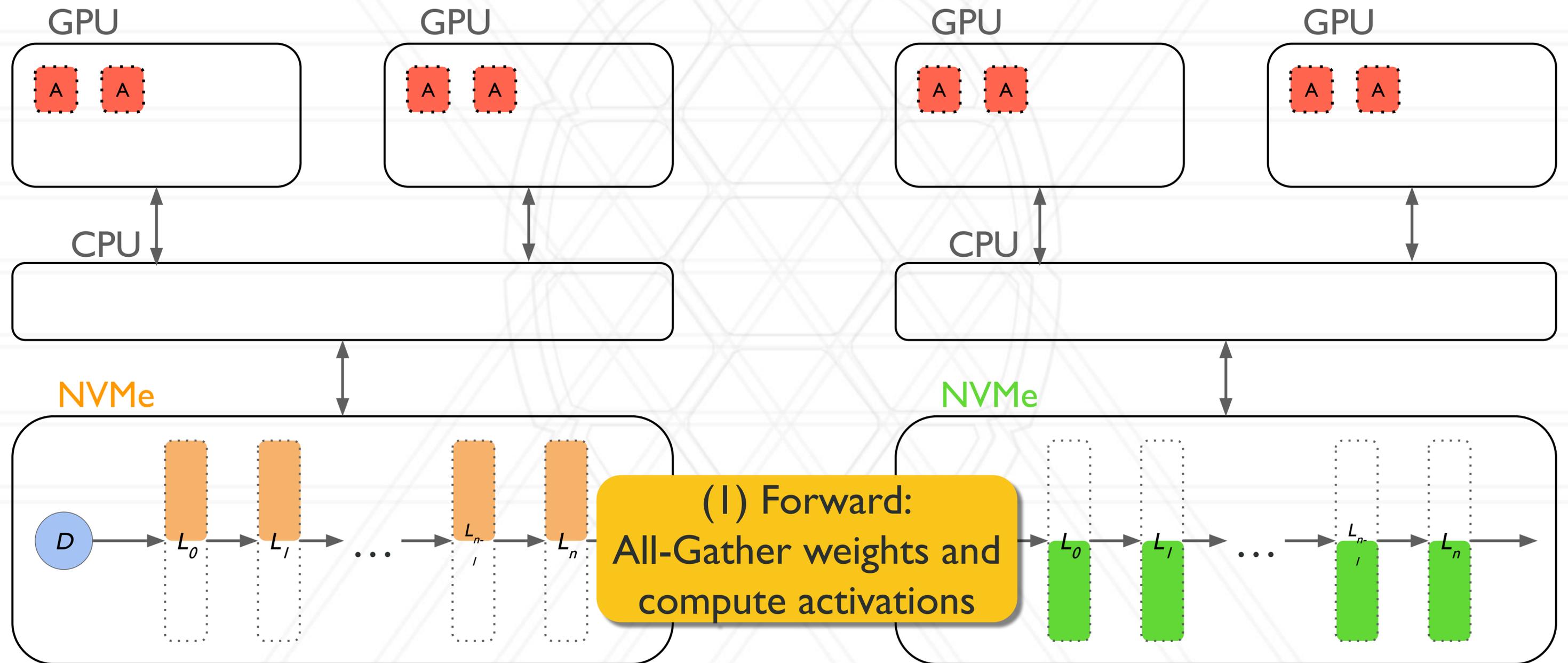
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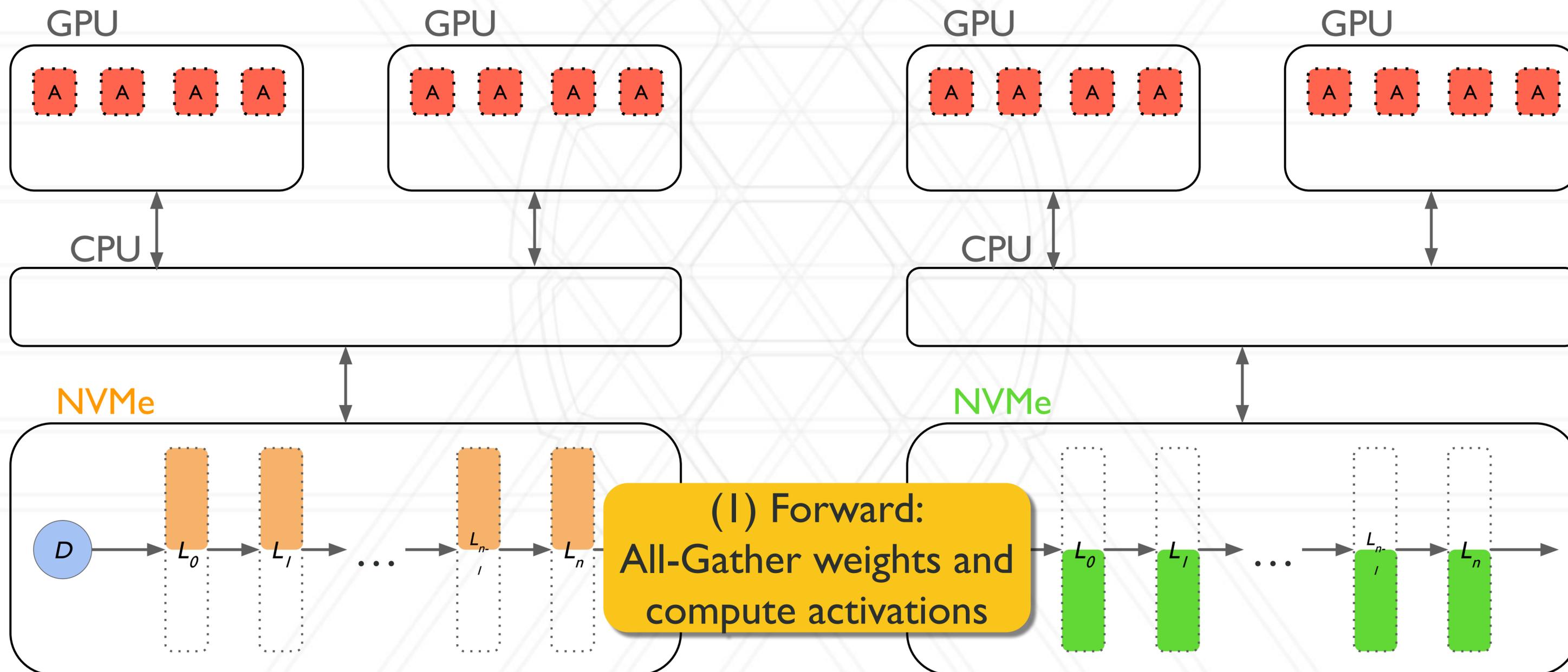
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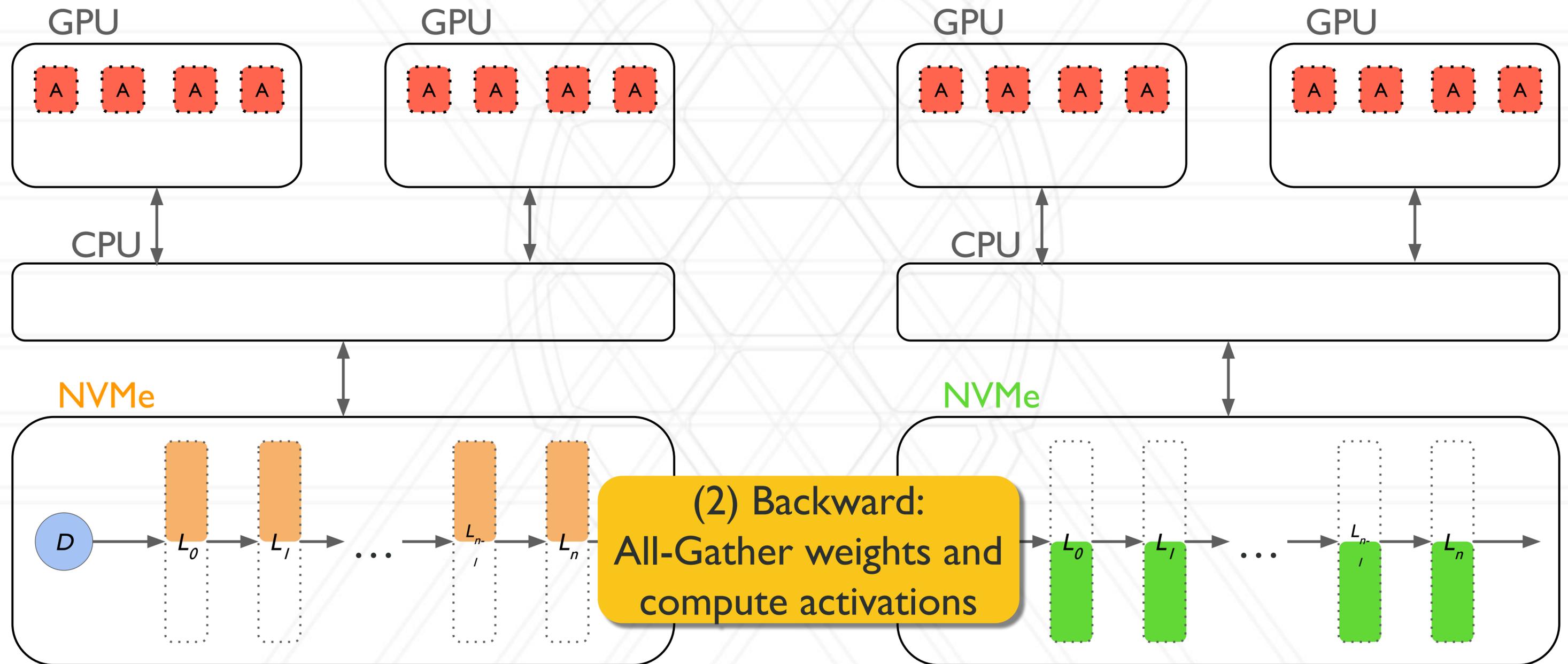
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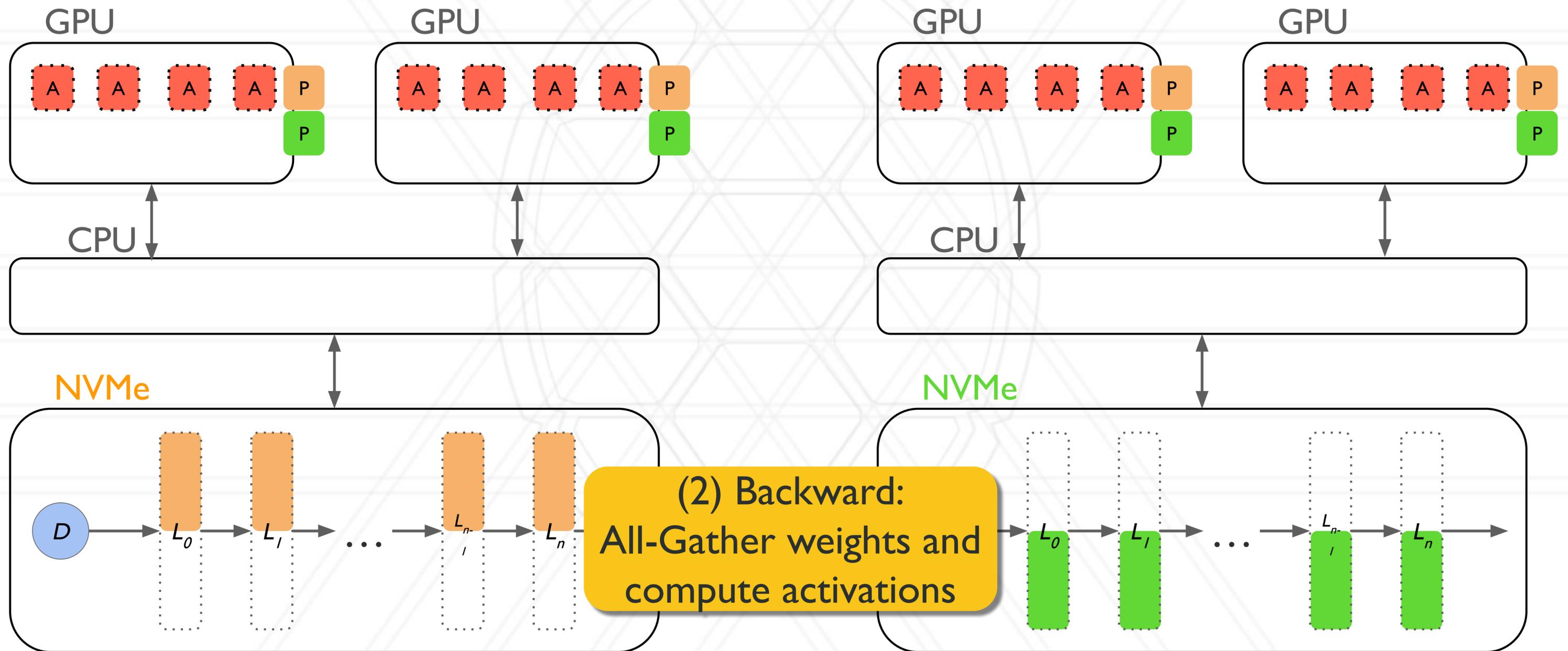
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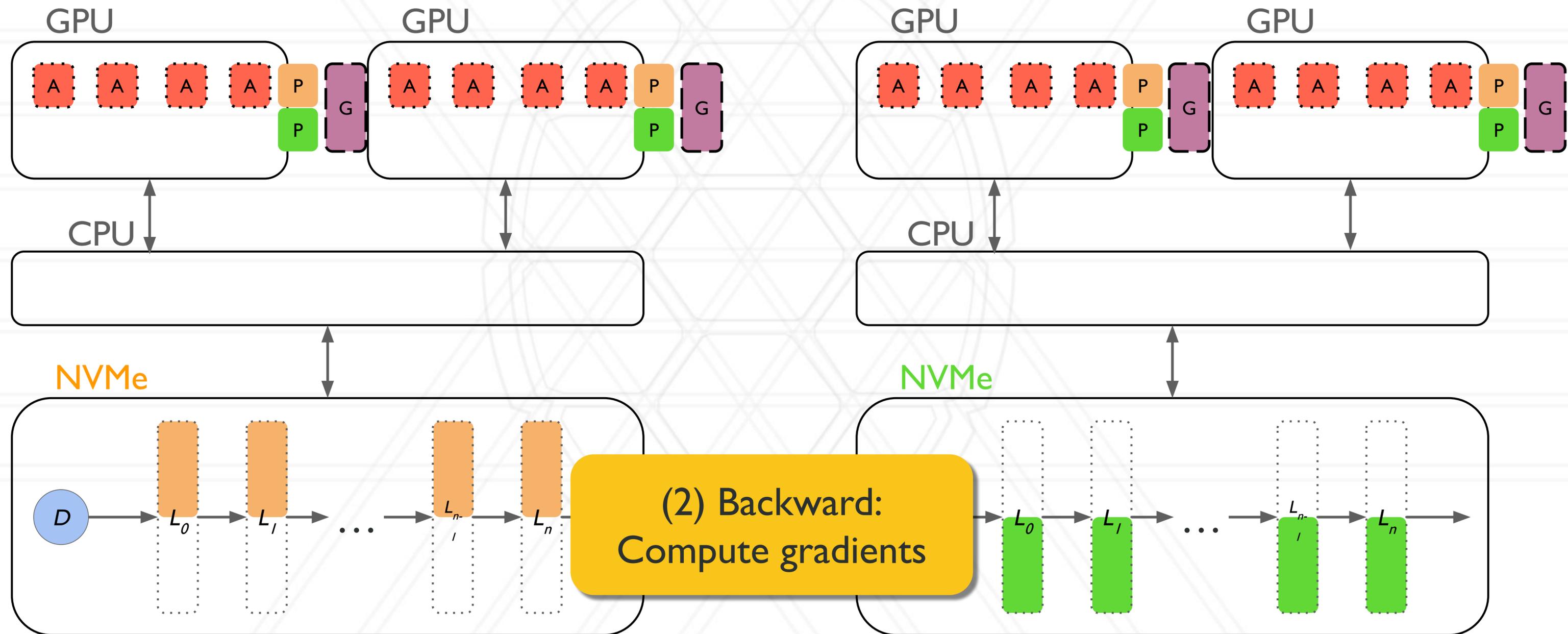
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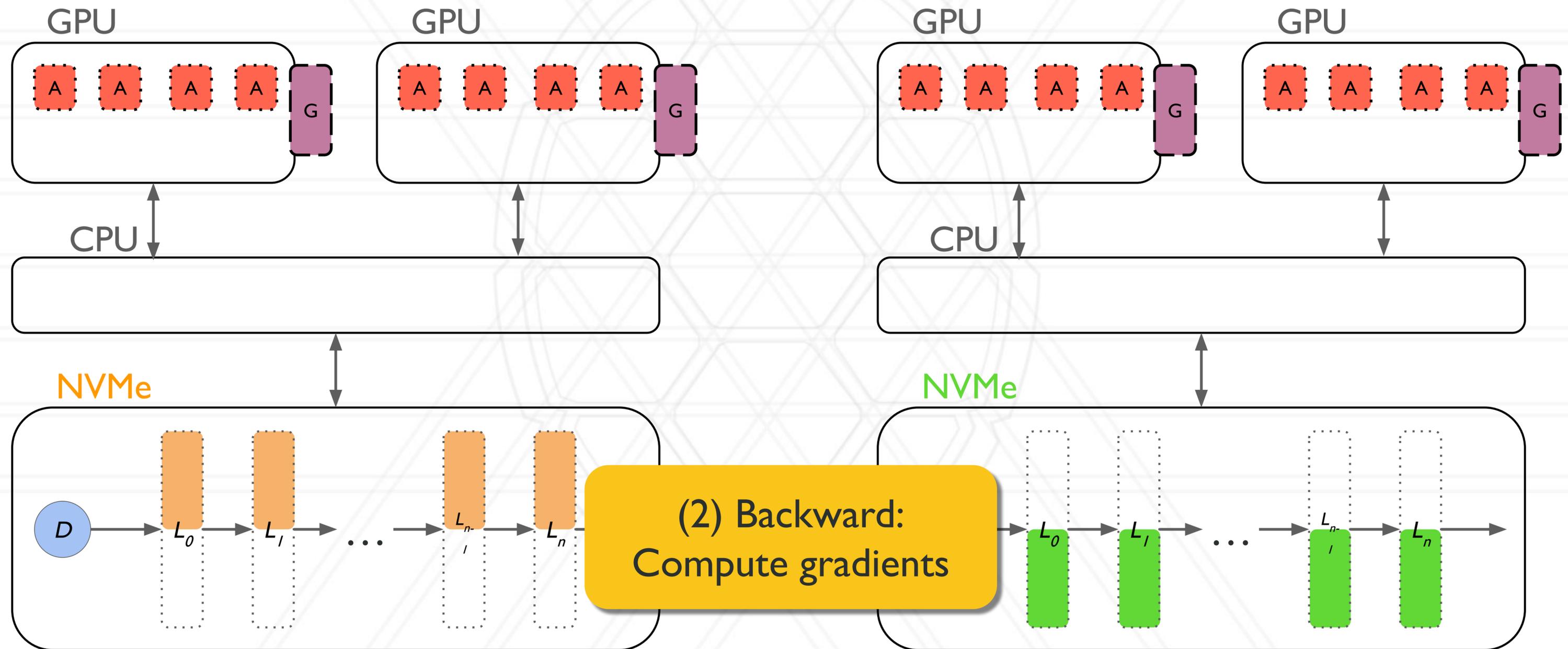
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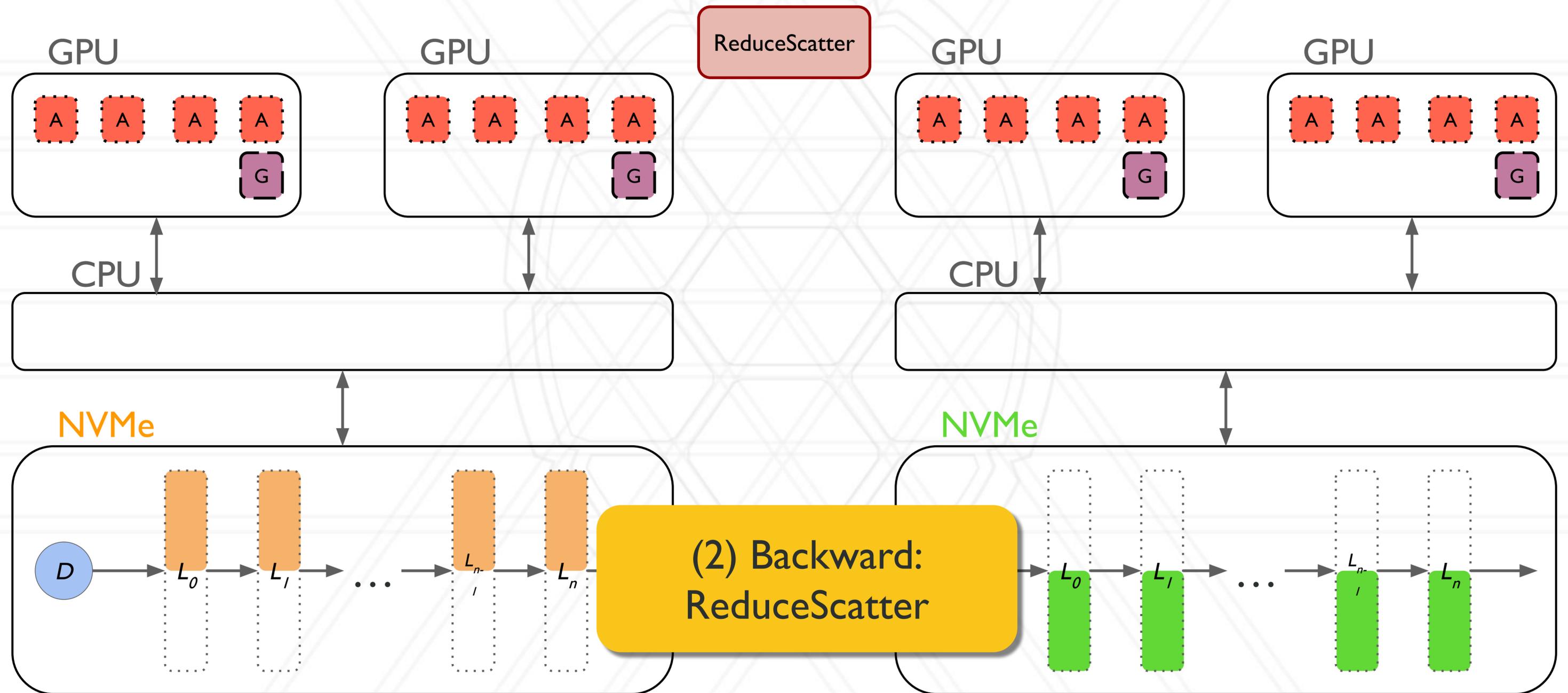
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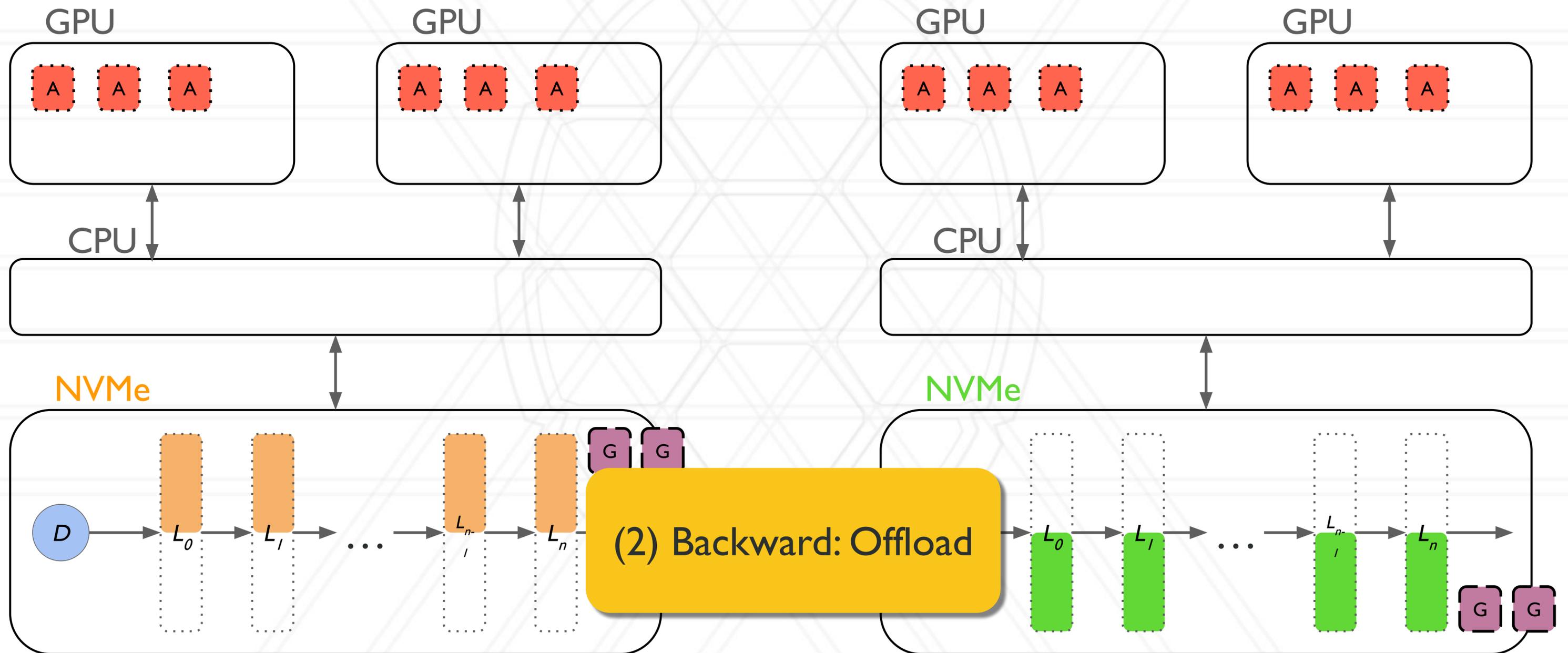
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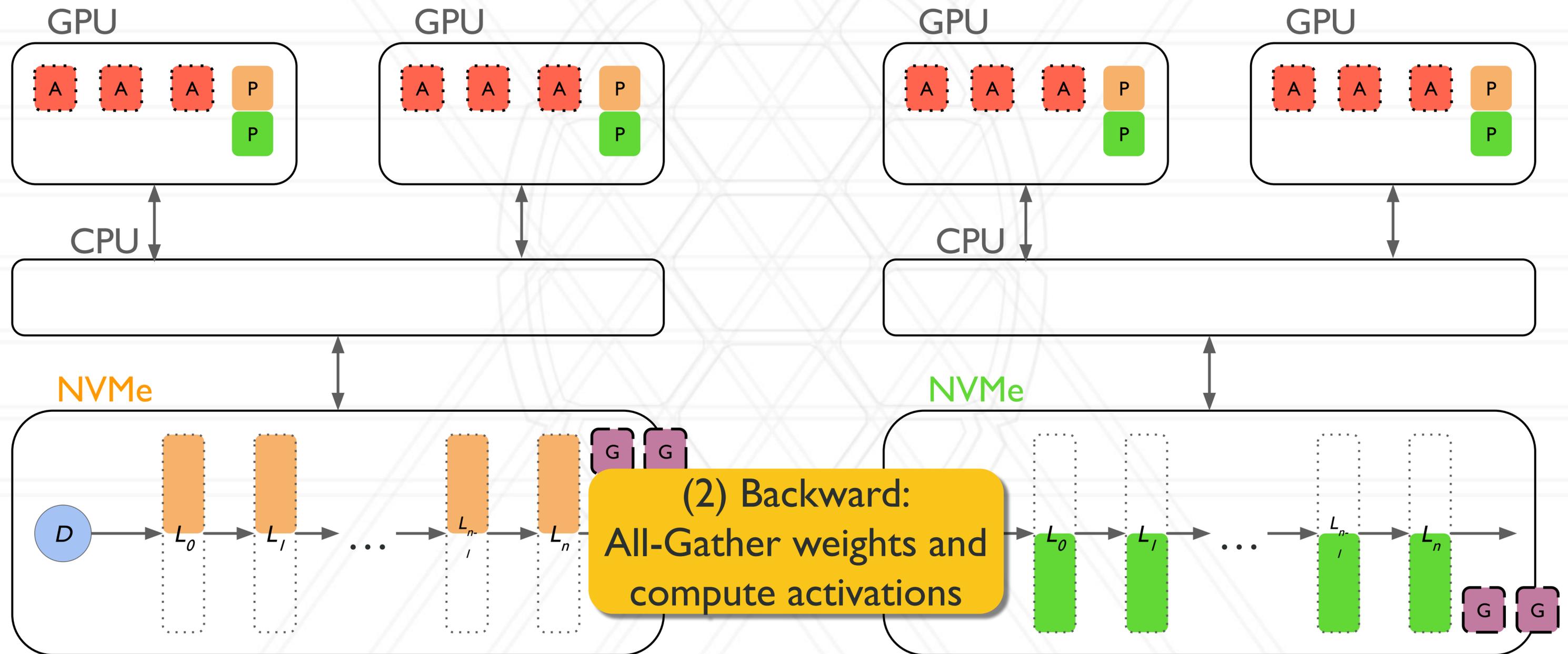
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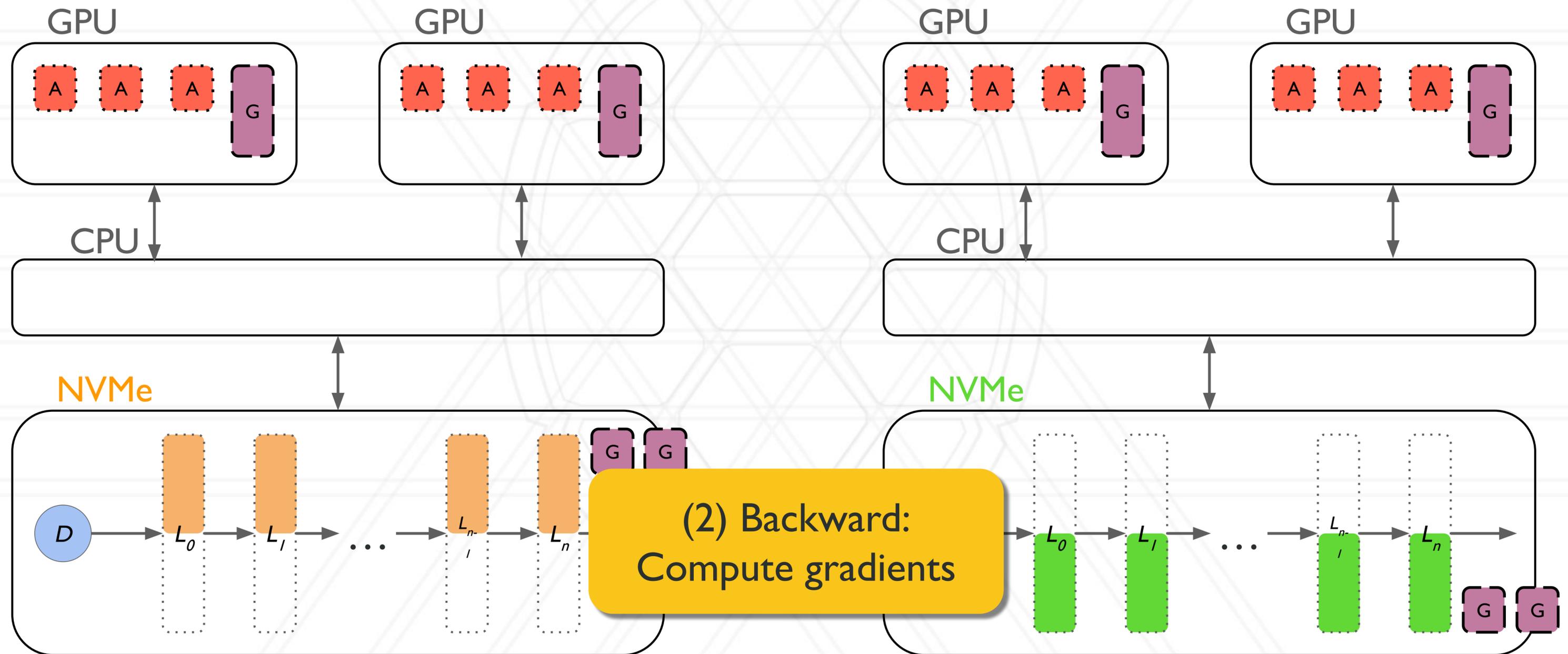
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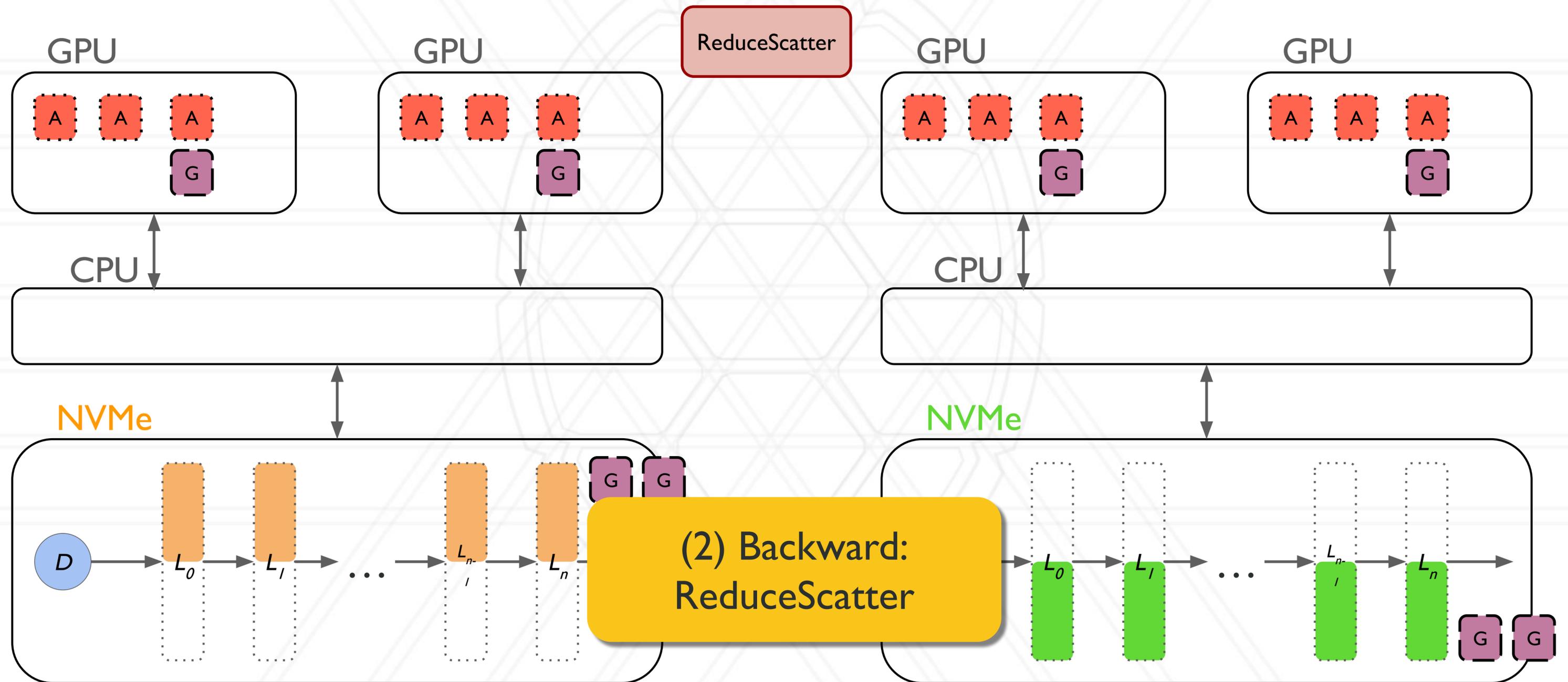
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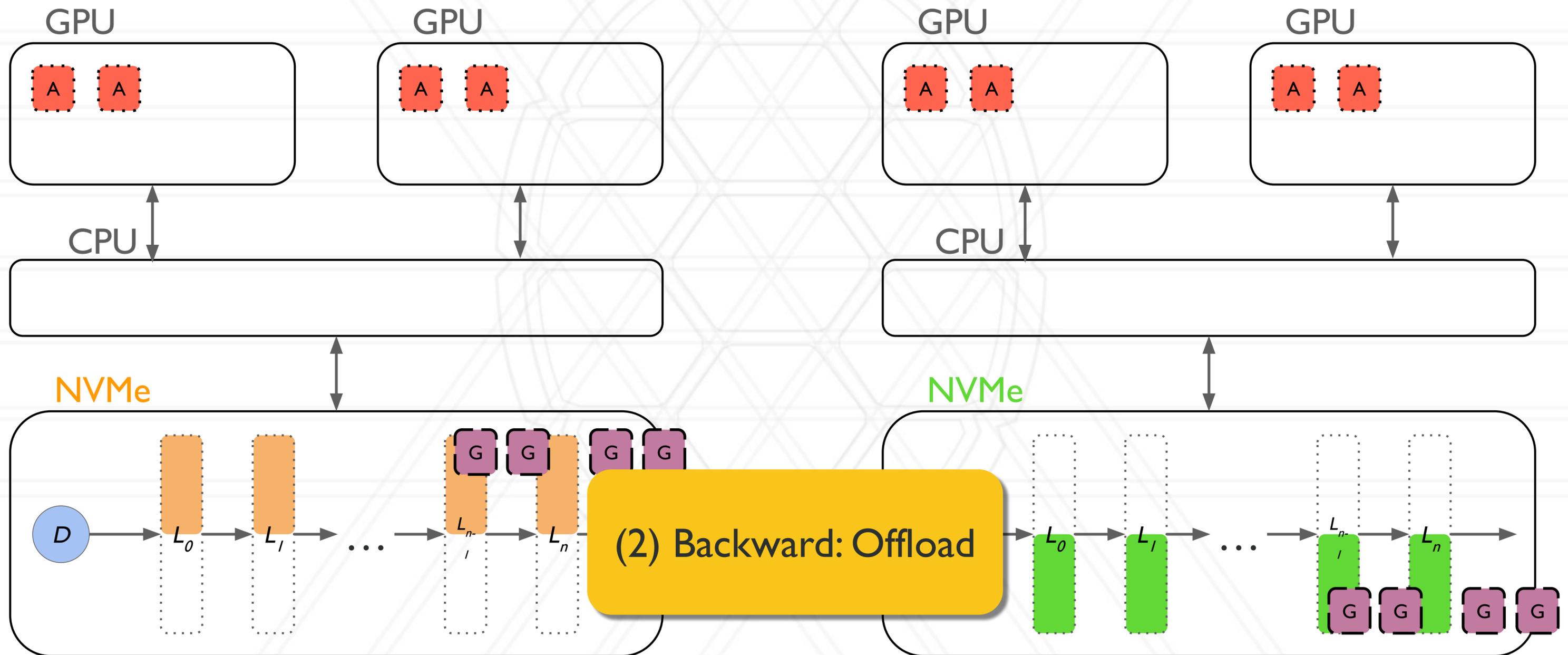
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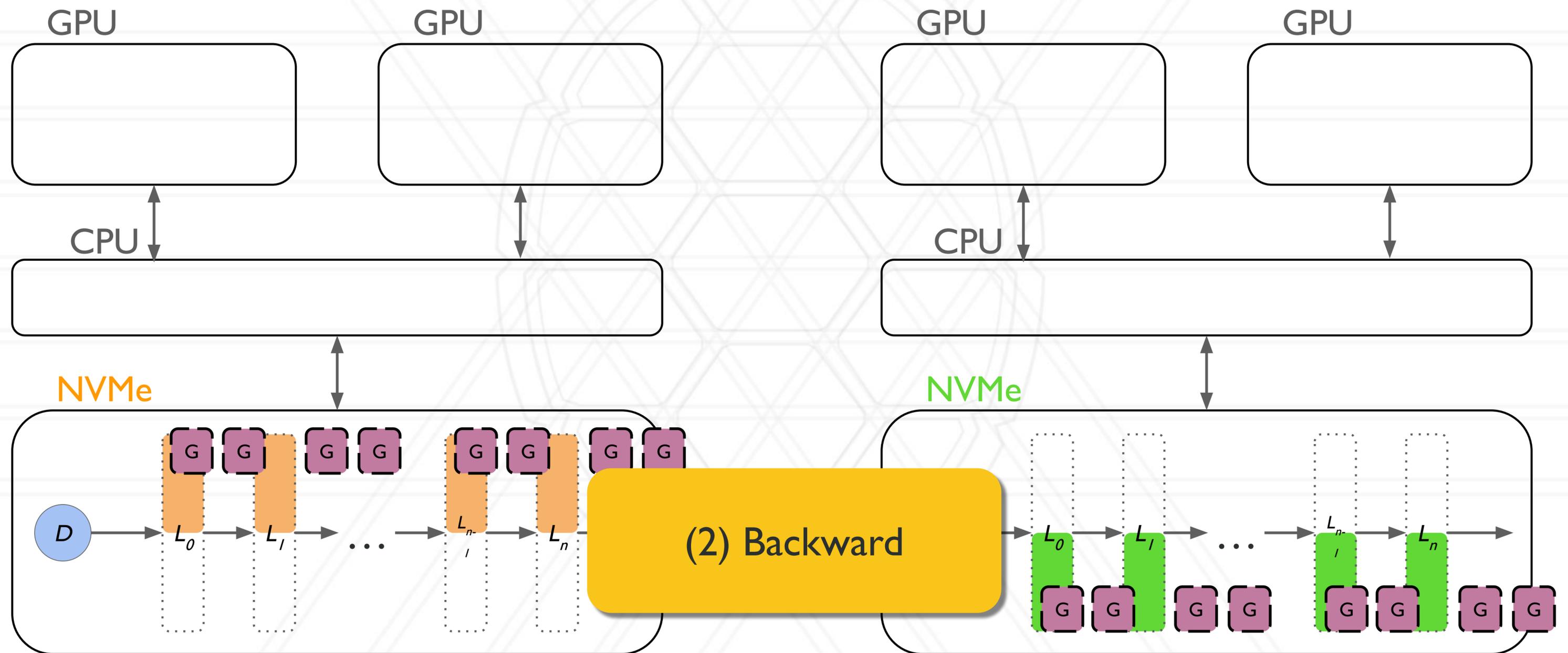
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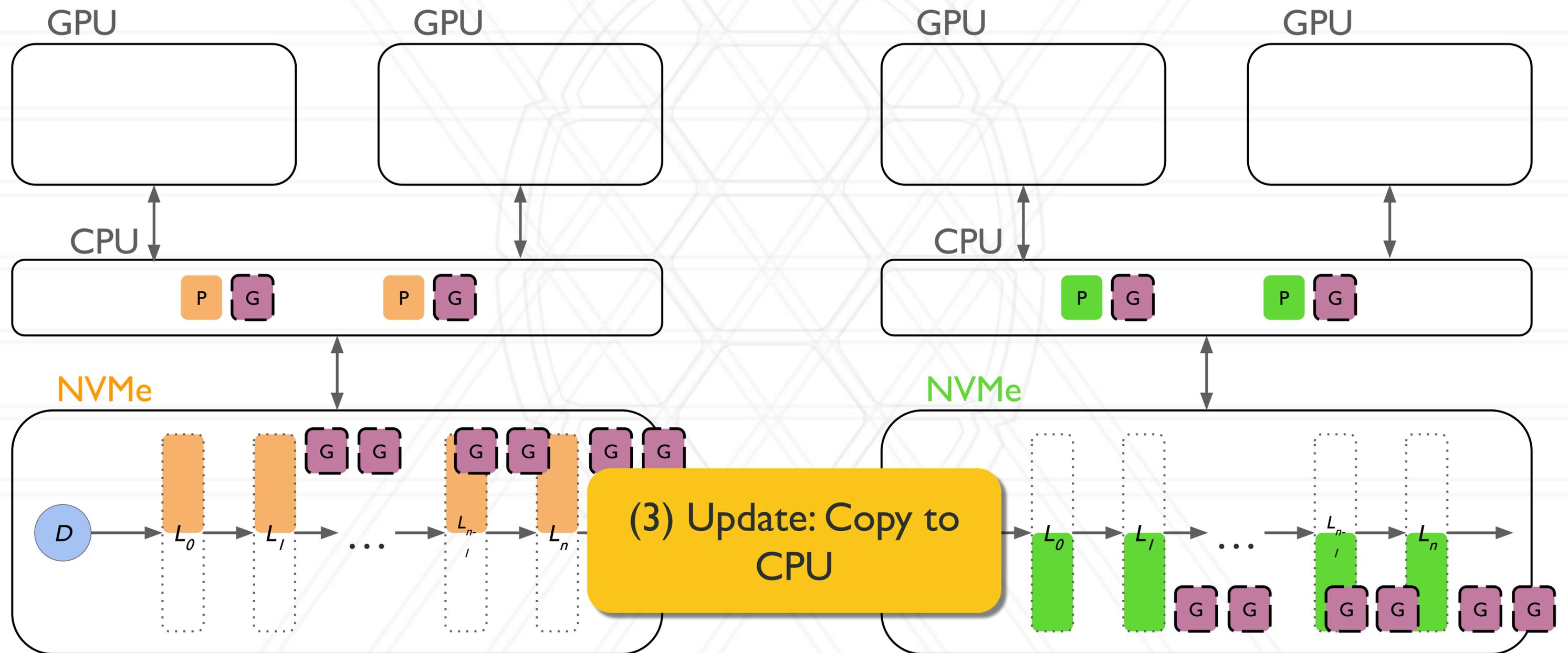
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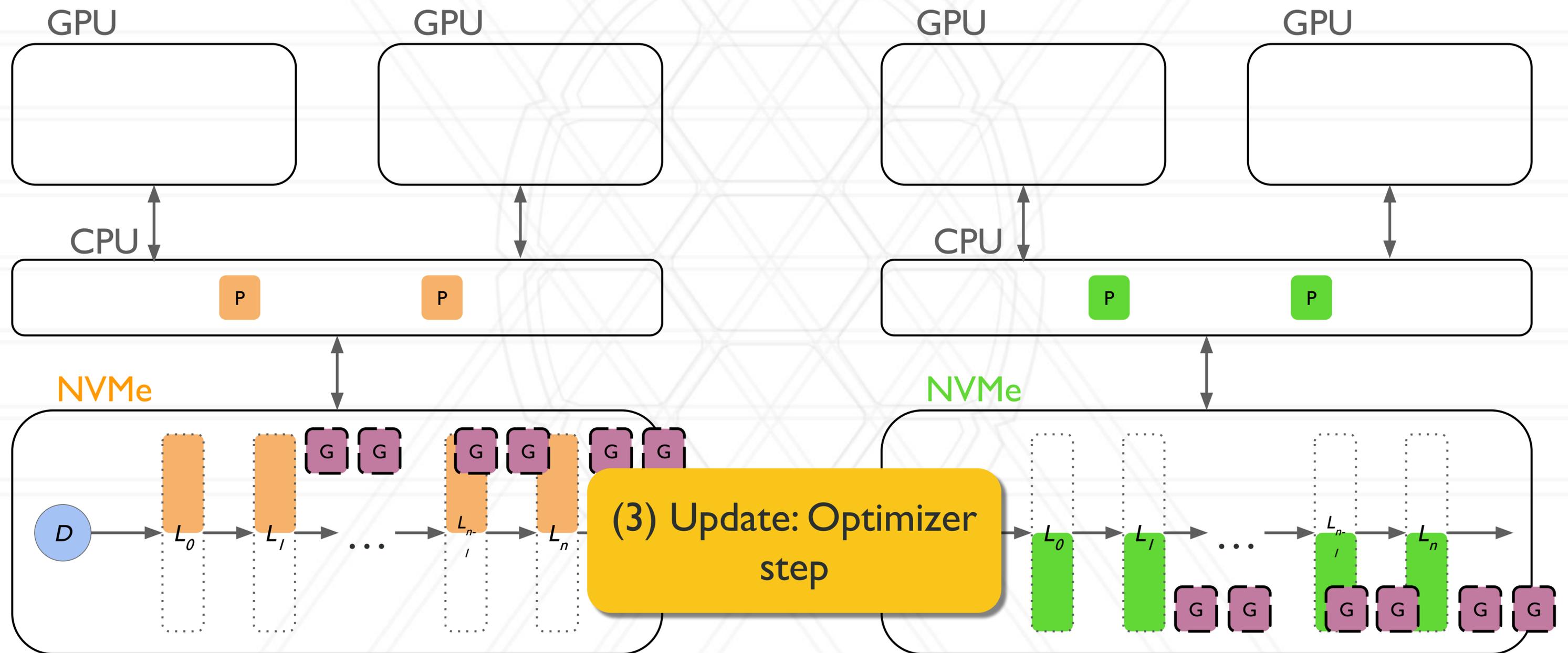
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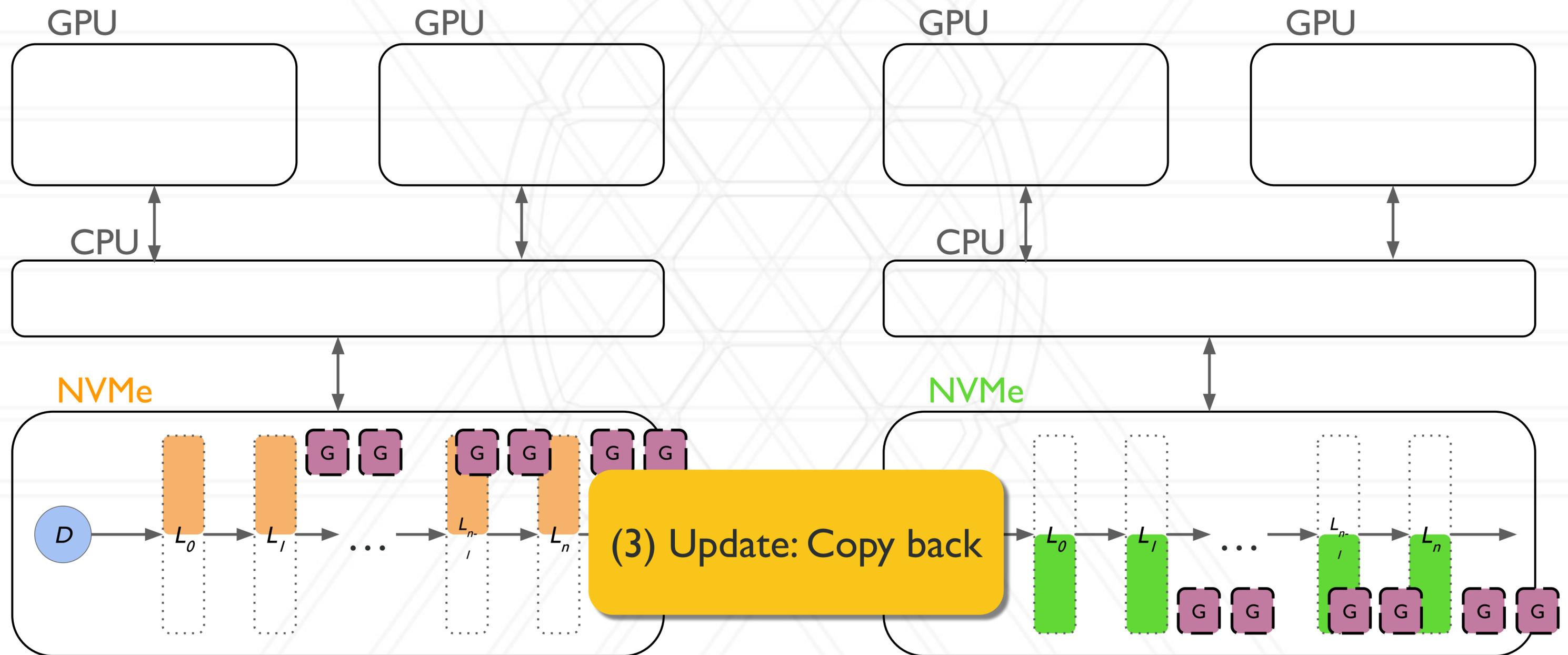
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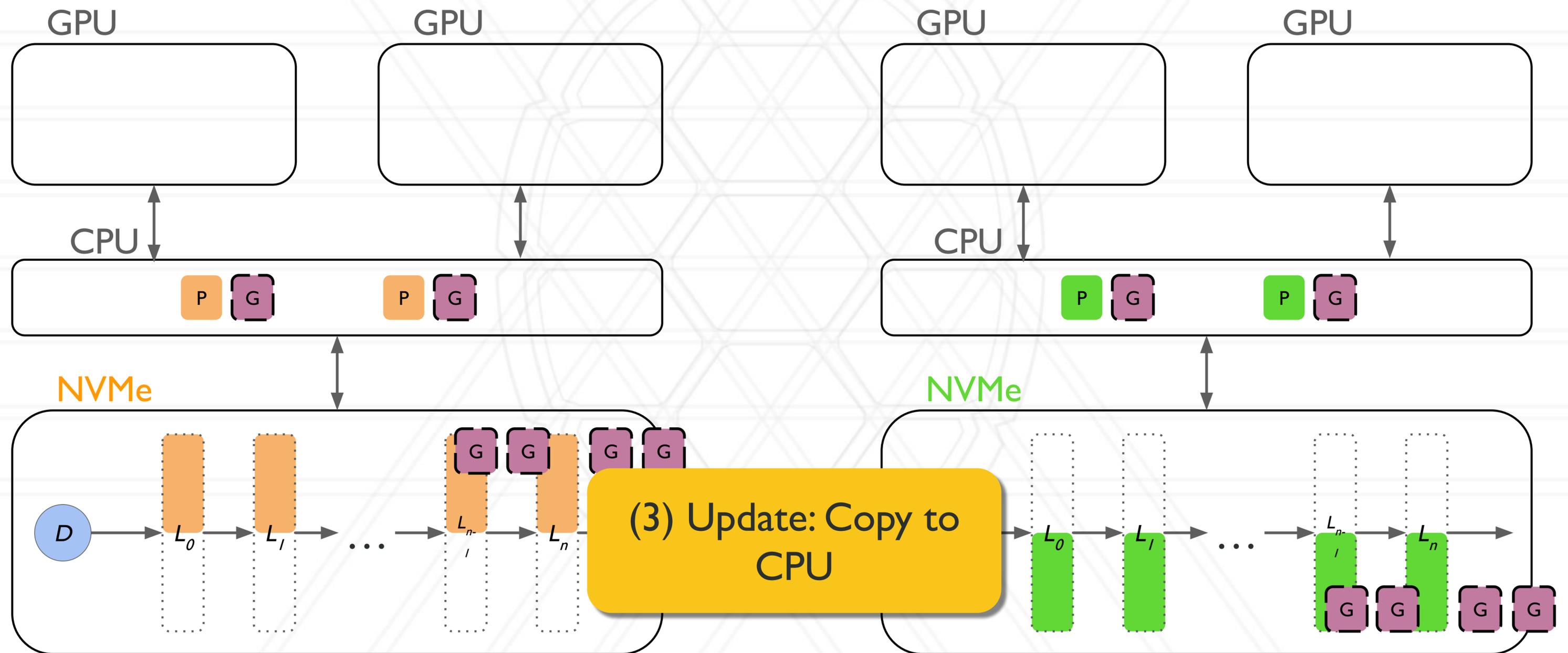
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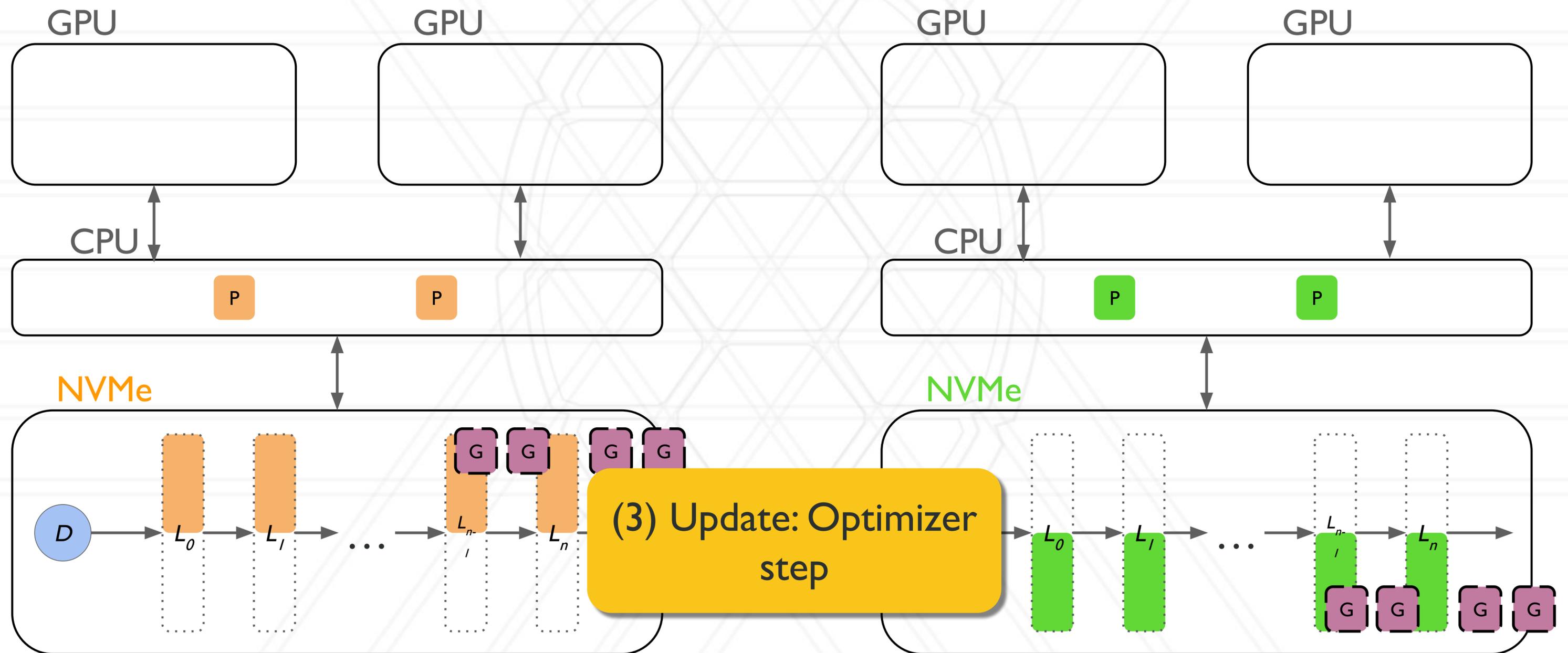
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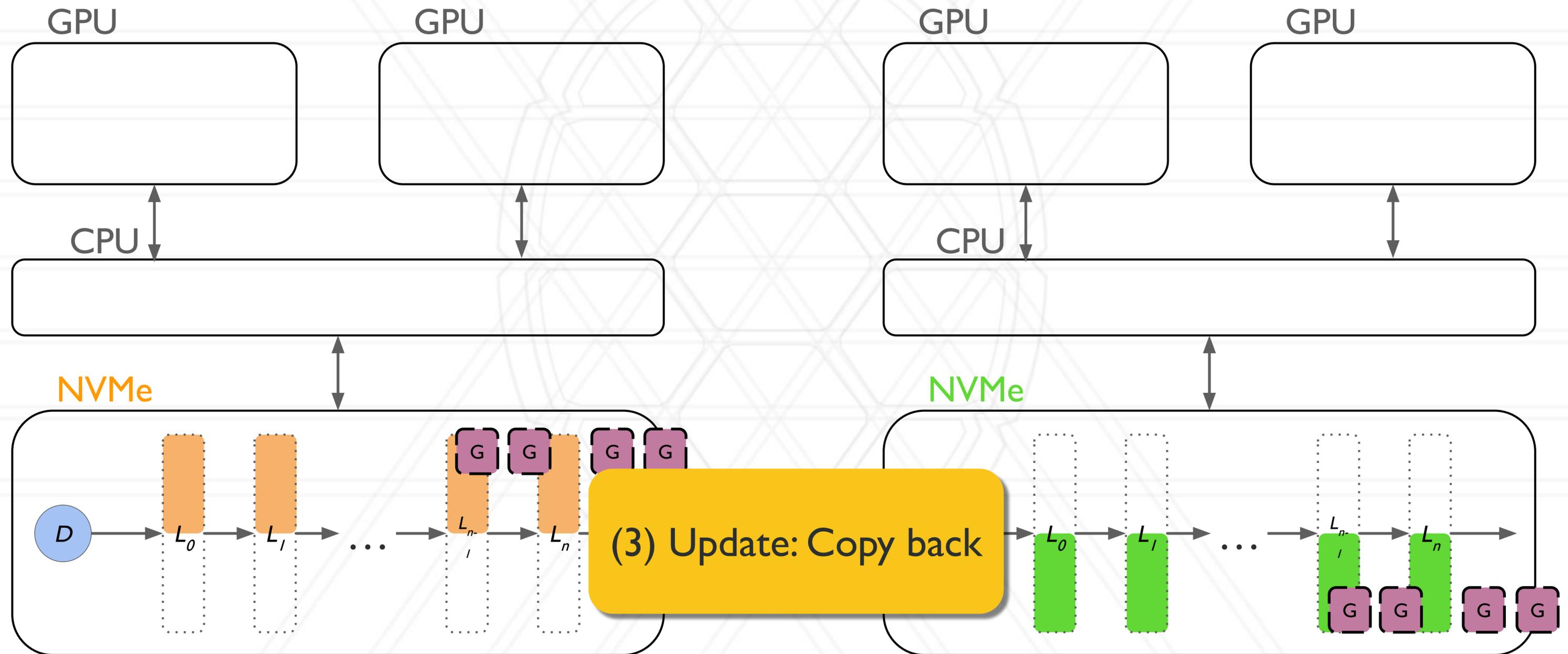
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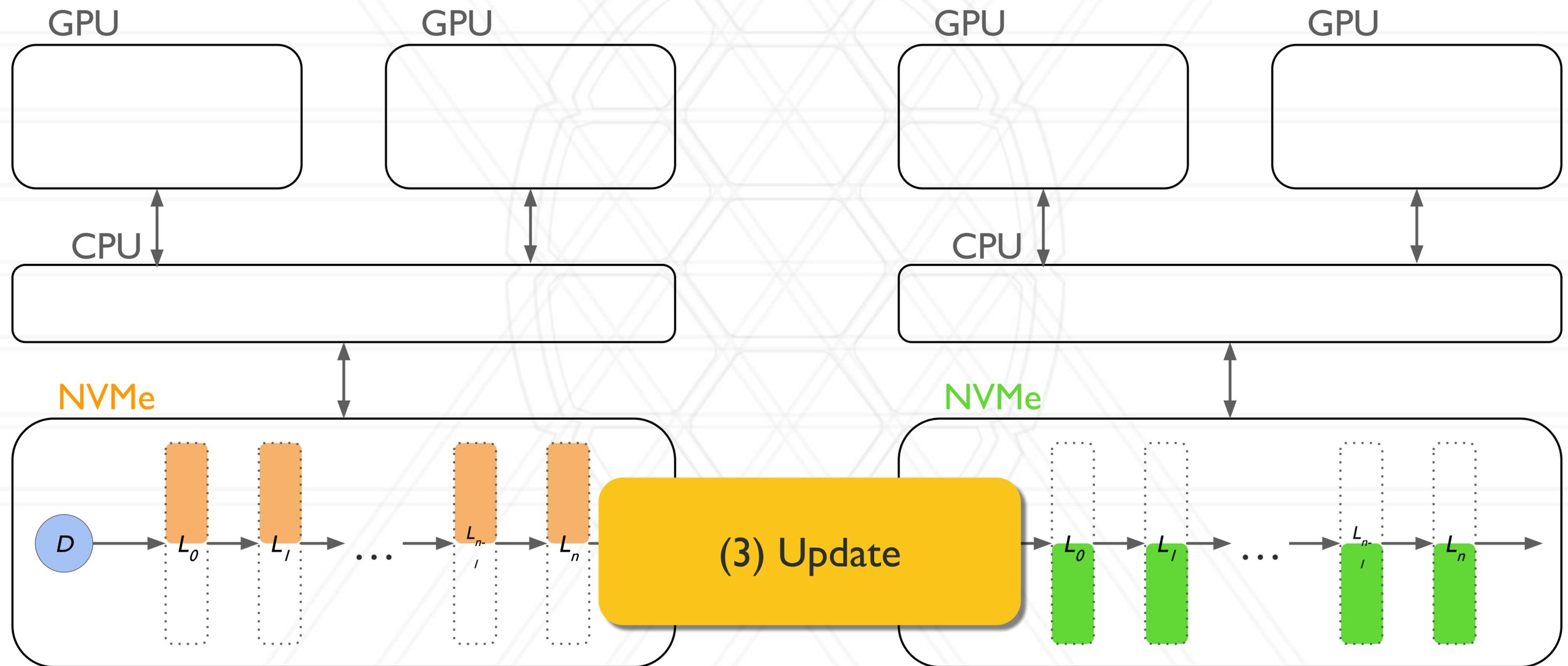
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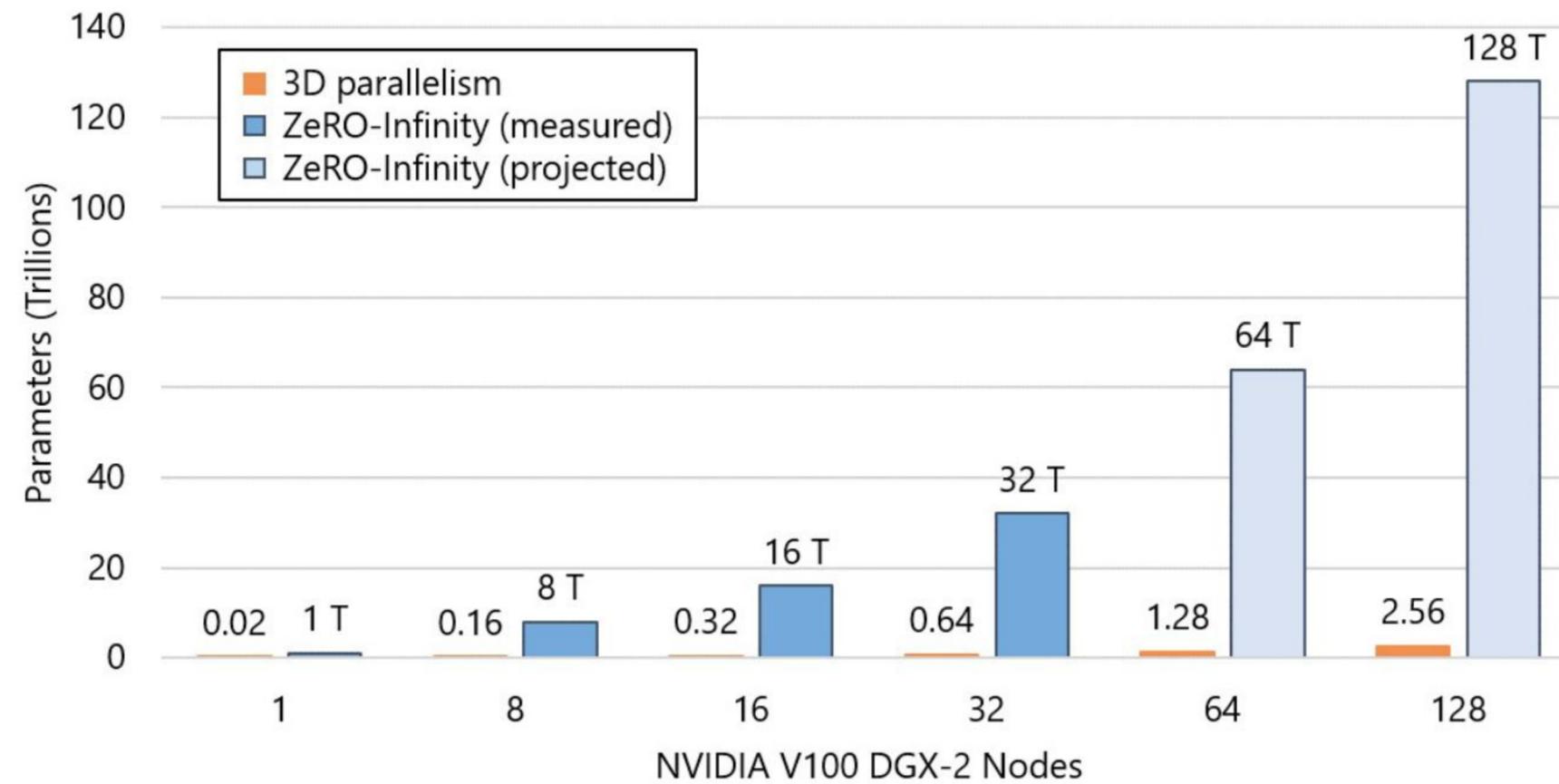


# ZeRO-Infinity Optimizations

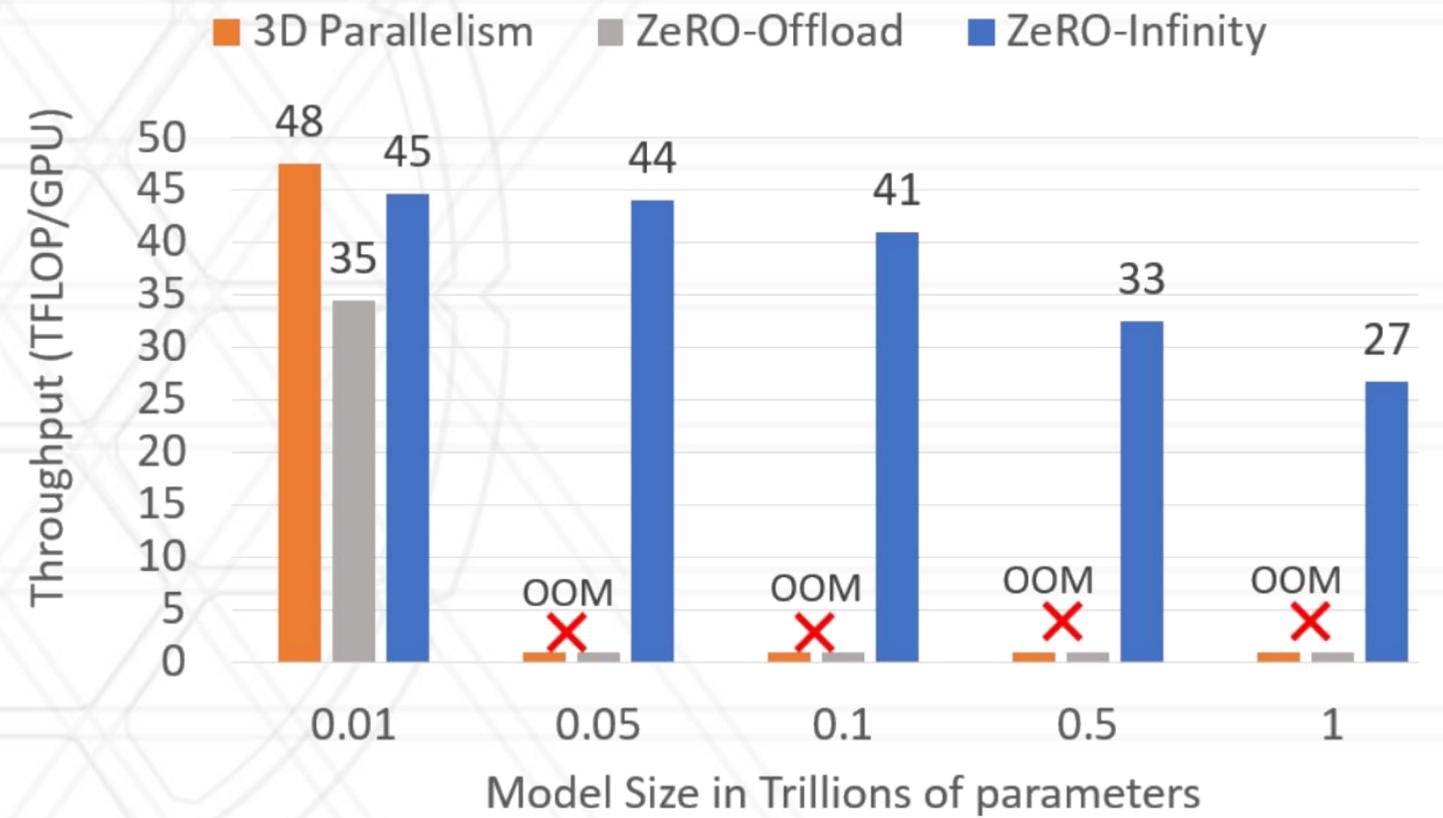
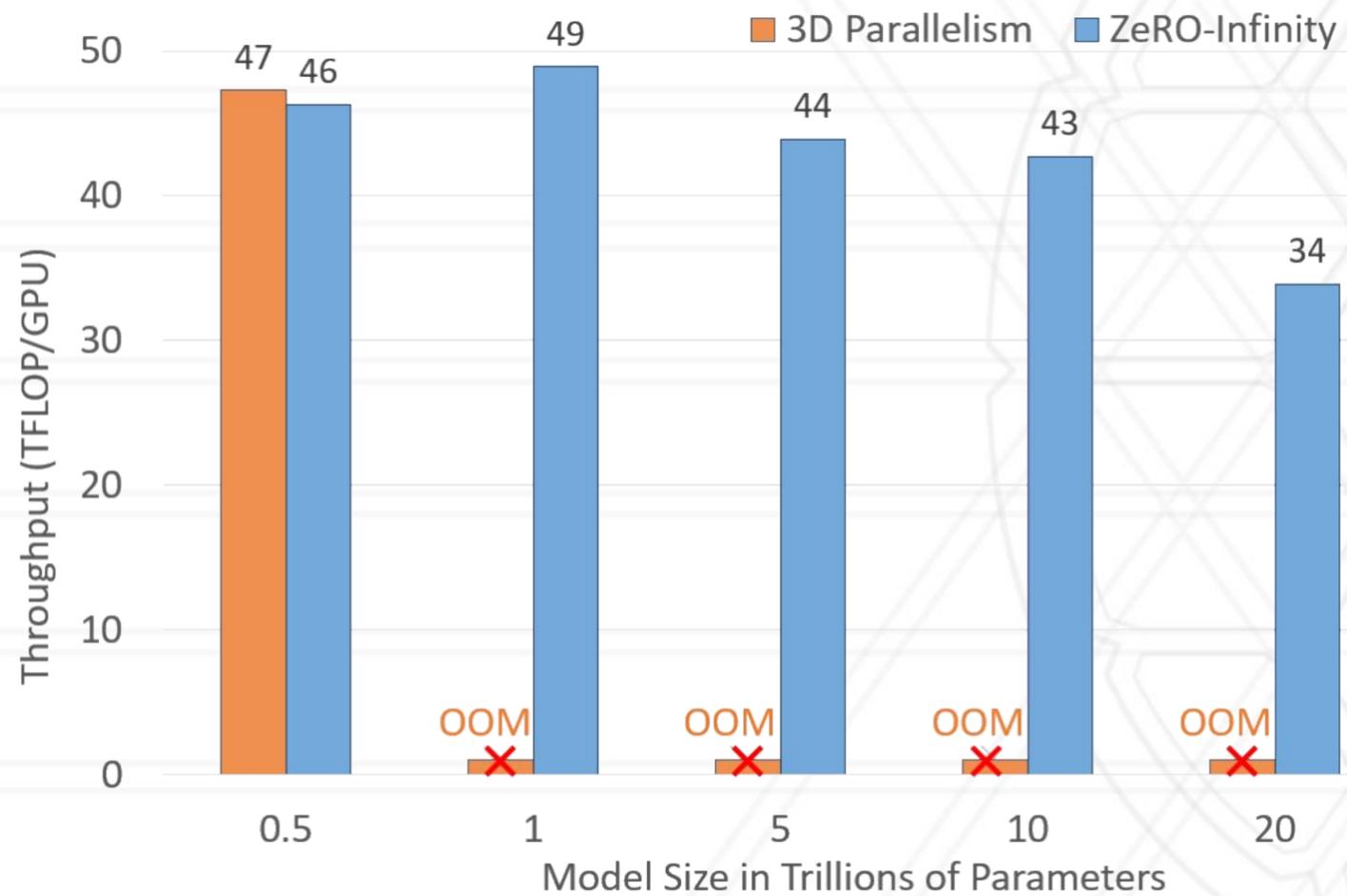
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- **Overlapped Copying/Communication**
  - All data copying is overlapped
  - Next layer data is loading while computing
- **Infinity Offload Engine**
  - Pinned memory management
  - NVMe memory optimizations

# Does it work?



# Performance



# When to use offloading?

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- You need functionality, but do not have access to more hardware
- Approximations/quantizations do not give enough fidelity
- Expensive reads/writes can be completely masked



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