

# CMSC 451 - Algorithm Design

## Lecture 10 - DP: Chain Matrix Multiplication

Dynamic programming for tree structures -

- Many optimization problems produce a tree structure as output

Optimal:

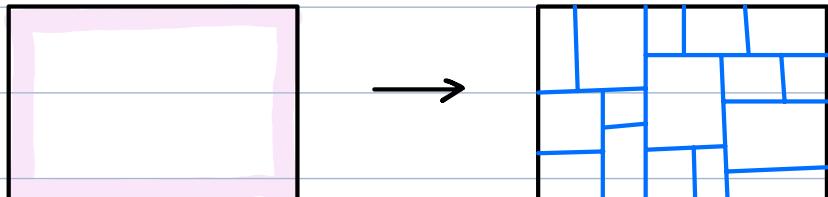
Binary search  
tree



Polygon  
triangulation



Quadtree or  
k-d tree

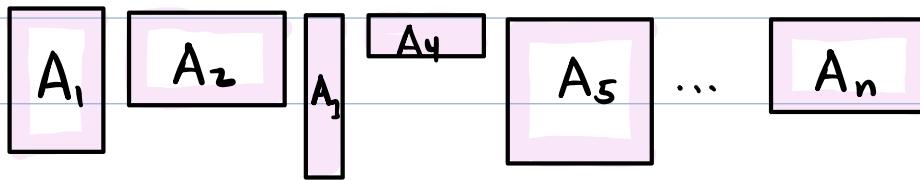


Chain Matrix Multiplication -

A simple example of tree-based DP solutions.

Problem: Given a sequence of matrices (of various sizes), what is the best evaluation order?

$A_1 \cdot A_2 \cdot \dots \cdot A_n$



### Facts:

- Matrix mult is associative, but  
not commutative

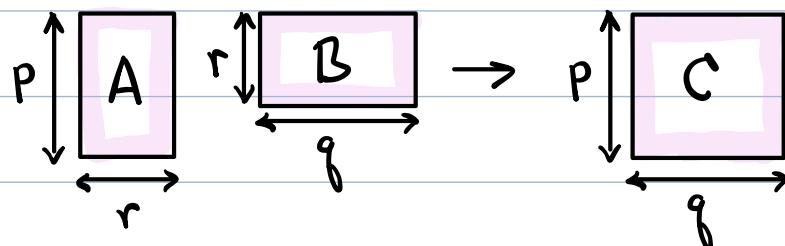
⇒ Can parenthesize as you like,  
but cannot change order

- To multiply:  $A \cdot B \rightarrow C$

$A$  is  $p \times r$  (p rows, r columns)

$B$  is  $r \times q$

$C$  is  $p \times q$



$$(p \times r)(r \times q) \rightarrow (p \times q)$$

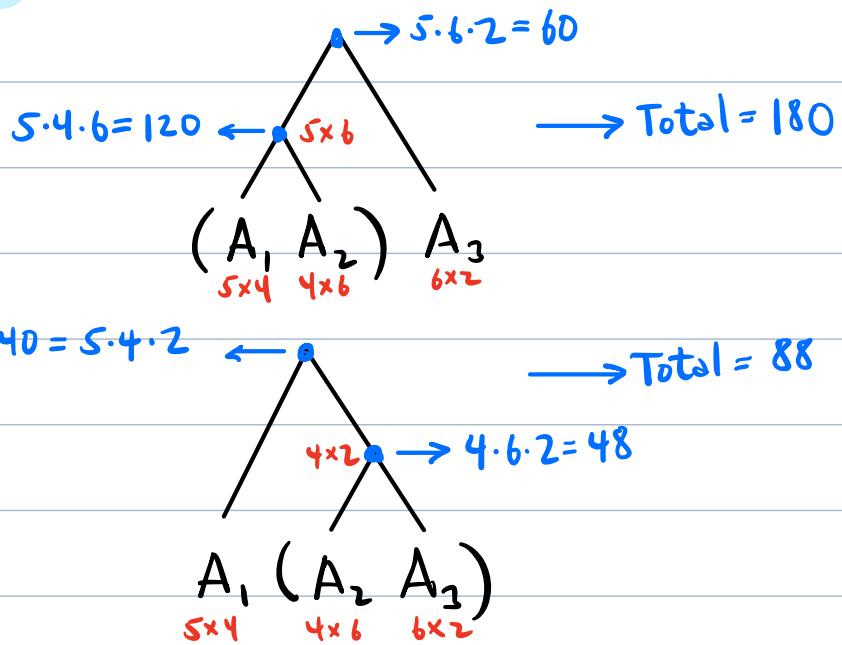
for  $1 \leq i \leq p$ ,  $1 \leq j \leq q$ ,  $c_{ij} = \sum_{k=1}^r a_{ik} \cdot b_{kj}$

- Time to multiply  $\sim p \cdot q \cdot r$  (simplified)

## Order matters:

$$\begin{array}{c} A_1 \\ \boxed{A_1} \end{array} \quad \begin{array}{c} A_2 \\ \boxed{A_2} \end{array} \quad \begin{array}{c} A_3 \\ \boxed{A_3} \end{array}$$

$5 \times 4$      $4 \times 6$      $6 \times 2$

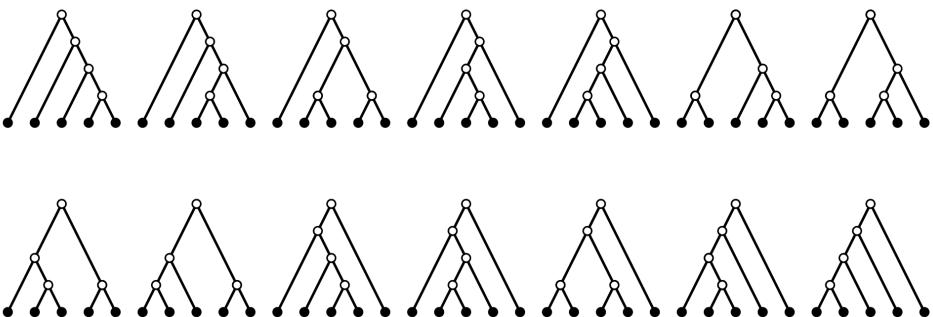


## Chain Matrix Mult Problem:

Given a seq. of matrices  $A_1, \dots, A_n$  presented by their dimensions  $\bar{p} = \langle p_0, p_1, \dots, p_n \rangle$  where  $A_i$  is  $p_{i-1} \times p_i$ , determine the order of multiplications (binary tree) that minimizes num. of ops.

## Brute force Solution?

- Enumerate all binary trees with  $n$  leaves
- Exponentially many!
- $n = 5$ :



- Number of possible parenthesizations:

$$P(n) = \begin{cases} 1 & \text{if } n=1 \\ \sum_{k=1}^{n-1} P(k) \cdot P(n-k) & n \geq 2 \end{cases}$$

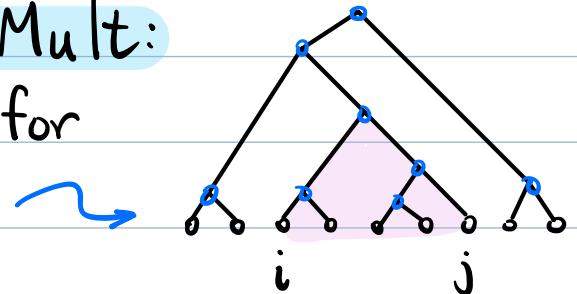
Solution is related to famous combinatorial function, Catalan Numbers.  $P(n) = C(n-1)$

$$C(n) = \frac{1}{n+1} \binom{2n}{n} \approx \frac{4^n}{n^{3/2} \sqrt{\pi}}$$

Aside: Named for Eugène Catalan (1800's)  
but originally discovered in 1730's by  
Mongolian mathematician/astronomer  
Ming Antu.

### DP Solution to Chain Matrix Mult:

- How to form subproblems for partitioning problems?



- For  $1 \leq i \leq j \leq n$ , let

$$A(i, j) = A_i \cdot A_{i+1} \cdot \dots \cdot A_j$$

$M(i, j)$  = min. num. of ops to compute  $A(i, j)$

- Goal:  $M(1, n)$

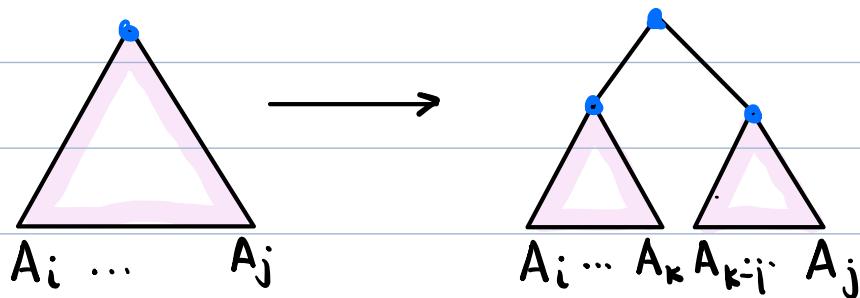
## Deriving the recursive formulation:

- $A(i,i) = A_i$  — trivial (no ops. needed)
- Assume  $i < j$

$$A_i \cdot A_{i+1} \cdots A_j = A(i,j)$$

$p_{i-1} \times p_i$     $p_i \times p_{i+1}$     $\cdots$     $p_{j-1} \times p_j$        $p_{i-1} \times p_j$

- Where's the top split?



$$(A_i \cdots A_j) = (A_i \cdots A_k)(A_{k+1} \cdots A_j) \quad \text{for } i \leq k \leq j-1$$

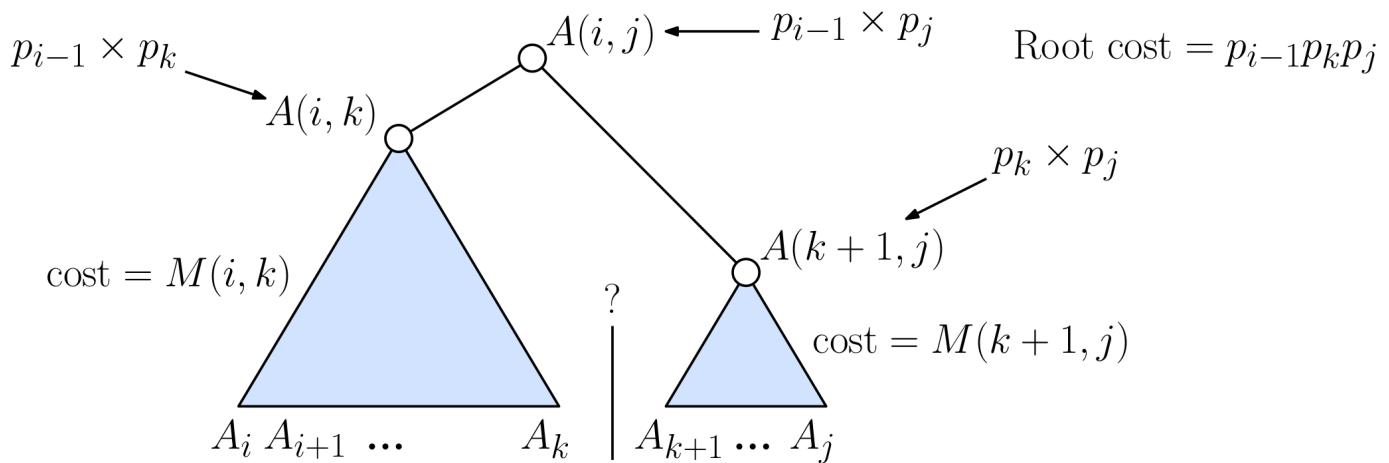
$$A(i,j) = A(i,k) \cdot A(k+1,j)$$

Issues:

- ① Where to split? (value of  $k$ )
- ② Cost to compute  $A(i,k) + A(k+1,j)$ ?
- ③ How many ops for last multiplication?

## Answers:

- ① DP Credo - Try all  $k$ . Take the best
- ② Princip. of Optimality - Best possible  
 $M(i, k) + M(k+1, j)$
- ③  $A(i, k)$  is  $p_{i-1} \times p_k$   
 $A(k+1, j)$  is  $p_k \times p_j$   
 $A(i, k) \cdot A(k+1, j)$  takes  $p_{i-1} \cdot p_k \cdot p_j$  ops



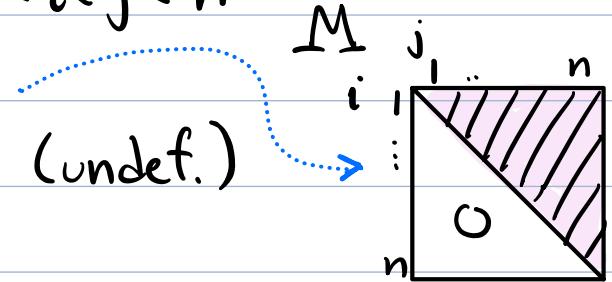
Recursive DP formulation: for  $1 \leq i \leq j \leq n$

$$M(i, j) = \begin{cases} 0 & \text{if } i=j \\ \min_{i \leq k \leq j-1} \left\{ M(i, k) + M(k+1, j) + p_{i-1} \cdot p_k \cdot p_j \right\} & \text{if } i < j \end{cases}$$

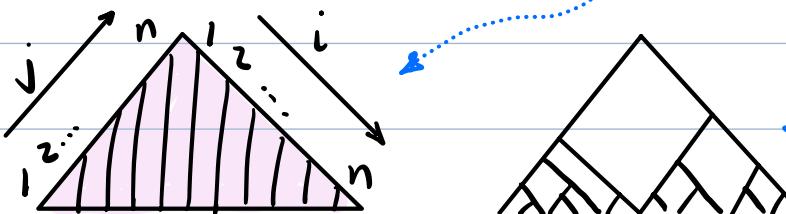
Final answer is  $M(1, n)$

## Memoized Implementation:

- Array  $M[i, j]$ ,  $1 \leq i \leq j \leq n$
- Upper triangular
- Init:  $M[i, j] = -1$  (undef.)



- In our pictures we'll rotate it:



so it looks more like a tree.

- Hooks -  $H[i, j]$  stores optimal split index  $k$

`memo-cmm(i, j)`

// Memoized CMM

if ( $M[i, j] = -1$ )

// undefined?

minCost  $\leftarrow +\infty$

for ( $k \leftarrow i$  to  $j-1$ ) // try all splits

cost  $\leftarrow (\text{memo-cmm}(i, k) + \text{memo-cmm}(k+1, j))$

+  $p[i-1] * p[k] * p[j]$  // cost

if ( $cost < \text{minCost}$ ) // new best cost?

$\text{minCost} \leftarrow cost$  // ... save it

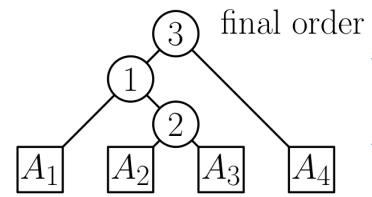
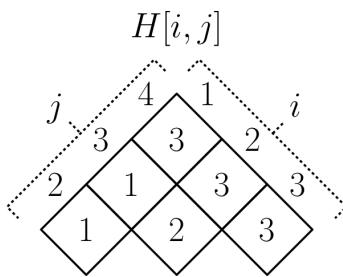
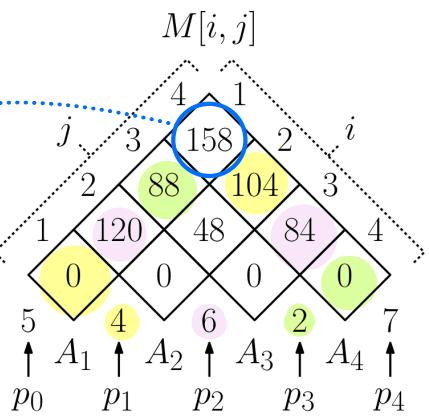
$H[i, j] \leftarrow k$  // ... save split index

$M[i, j] \leftarrow \text{minCost}$

// save final cost

`return  $M[i, j]$`

## Example:



$$M[1,4] = \min:$$

$$(k=1) \quad M[1,1] + M[2,4] + p_0 \cdot p_1 \cdot p_4 = 0 + 104 + 140 = 244$$

$$(k=2) \quad M[1,2] + M[3,4] + p_0 \cdot p_2 \cdot p_4 = 120 + 84 + 210 = 414$$

$$(k=3) \quad M[1,3] + M[4,4] + p_0 \cdot p_3 \cdot p_4 = 88 + 0 + 70 = 158$$

↑ best split

$M[1,4] \leftarrow 158$   
 $H[1,4] \leftarrow 3$

min

## Correctness:

- Follows from correctness of DP formulation

## Running Time:



-  $\mathcal{O}(n^2)$  table entries

- Each takes  $\mathcal{O}(j-i+1) \leq \mathcal{O}(n)$  time to compute

- Total:  $\mathcal{O}(n^3)$

## Extracting the Final Sequence:

- So far we only compute the opt. cost
- To extract final sequence - use hooks
- Recall -  $H[i, j]$  stores best split for  $A_i \dots A_j$
- $A(i, j) = A_i A_{i+1} \dots A_j$   
 $= (A_i \dots A_k)(A_{k+1} \dots A_j)$   
where  $k = H[i, j]$
- Continue splitting until  $i = j$ ,  $A(i, i) = A_i$

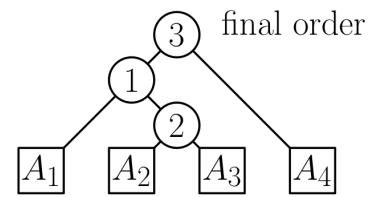
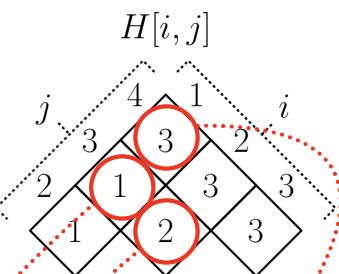
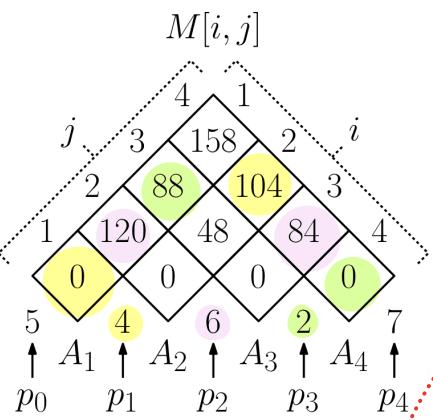
```
do-mult(i, j) // multiply  $A_i \dots A_j$  optimally
if (i = j) return  $A_i$  // basis - one matrix
else
    k ←  $H[i, j]$  // opt split index
    X ← do-mult(i, k) //  $X \leftarrow A_i \dots A_k$ 
    Y ← do-mult(k+1, j) //  $Y \leftarrow A_{k+1} \dots A_j$ 
    return  $X \cdot Y$  // final product
```

Initial call:  $\text{do-mult}(1, n)$

Running time:

- $O(n)$  to extract opt. evaluation tree
- $O(M[1, n])$  to perform multiplications

## Example:



$$\begin{aligned}
 A_1..A_4 &= \\
 &\xrightarrow{H[1,4]=3} (A_1..A_3)(A_4) \\
 &\xrightarrow{H[1,3]=1} ((A_1)(A_2..A_3))(A_4) \\
 &\xrightarrow{H[2,3]=2} ((A_1)((A_2)(A_3)))(A_4)
 \end{aligned}$$

## Bottom-Up Implementation:

- Normally this is an easy extension.  
Just fill table row by row.
- Doesn't work!

E.g., Computing  $M[2,5]$  accesses

$M[2,2]$ $M[3,5]$ $M[2,3]$ $M[4,5]$ $M[2,4]$ $M[5,5]$
---

	1	2	3	4	5
1					→
2		○	○	○	→
3					○
4					○
5					○

} Not yet computed!

Trick: Compute entries diagonal by diagonal, working out from main diagonal.

	1	2	3	4	5
1	...	...	...	...	...
2	...	...	...	...	...
3	...	...	...	...	...
4	...	...	...	...	...
5	...	...	...	...	...

Coding this is a bit tricky. (Think about it)

Recall:  $1 \leq i \leq j \leq n$  (upper triangular)

Main = 1 <sup>st</sup> diagonal: $[1,1] [2,2] \dots [n,n]$ $\Rightarrow j-i+1=1$
2 <sup>nd</sup> diagonal: $[1,2] [2,3] \dots [n-1,n]$ $\Rightarrow j-i+1=2$
3 <sup>rd</sup> diagonal: $[1,3] [2,4] \dots [n-2,n]$ $\Rightarrow j-i+1=3$
⋮
n <sup>th</sup> diagonal: $[1,n]$ $\Rightarrow j-i+1=n$

Let  $l = j-i+1$  = which diagonal

$l$  runs from 1 (main diag) to  $n$  (corner)

$i = 1, 2, \dots, n-l+1$

$j = i+l-1$  chosen so that  $j \leq n$

```

bottom-up-cmm () // bottom-up CMM
for (i ← 1 to n) M[i,i] = 0 // basis-main diag.
for (l ← 2 to n) // l = diagonal number
    for (i ← 1 to n-l+1)
        j ← i+l-1 // pick j so j-i+l = l
        minCost ← ∞
        for (k ← i to j-1)
            minCost ← min (minCost,
                M[i,k]+M[k+1,j] + p_{i..i} p_k · p_j)
        M[i,j] ← minCost
return M[1,n]

```

same as before

Running Time:

$\mathcal{O}(n^3)$  - 3 nested loops

- Each in range 1..n

Summary:

- $\mathcal{O}(n^3)$  DP algorithm for chain matrix mult
- Explayr of DP's that build hierarchies
- Example: Optimum binary search tree