

CMSC 451 - Algorithm Design

Lecture 8 - Dynamic Programming: Weighted Interval Sched.

Dynamic Programming -

- A fundamental algorithm design principle
- Involves recursively breaking a problem into subproblems

- **Optimal substructure** - Property of some optimization problems. To obtain a globally optimal result, all subproblems should be solved optimally

- Developed in 1950's by **Richard Bellman**

- Bellman-Ford algorithm
- Coined the term "**curse of dimensionality**"

Isn't this obvious?
No - Sometimes it is better to be suboptimal on one subproblem so you can do better on another subproblem

Overlapping subproblems -

- Prevents methods like **divide-and-conquer**
- Can be solved **top-down** or **bottom-up**

Weighted Interval Scheduling -

Given a set of n requests to be scheduled on an exclusive resource.

Each request has:

- start-finish time interval - $[s_i, f_i]$
- weight or value - v_i

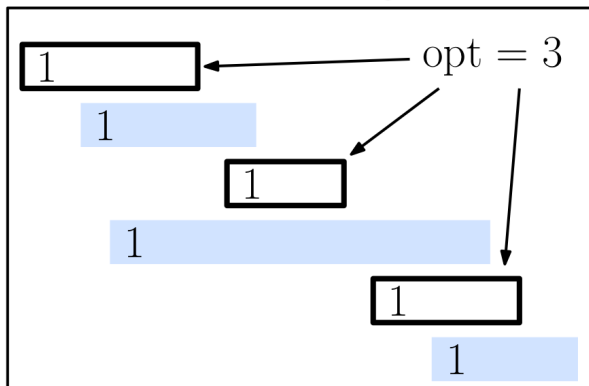
Objective - Schedule a set of non-overlapping requests to maximize sum of weights.

Example: People make bids to use picnic table at local park

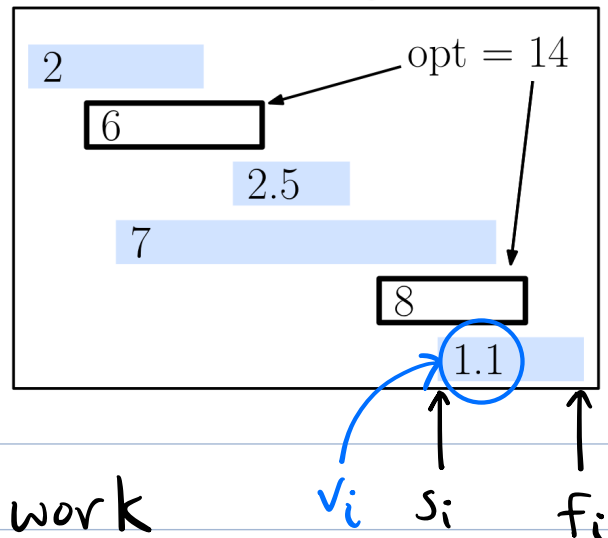
$[s_i, f_i]$ - when they want to use it

v_i - amount they'll pay for use

optimal unweighted



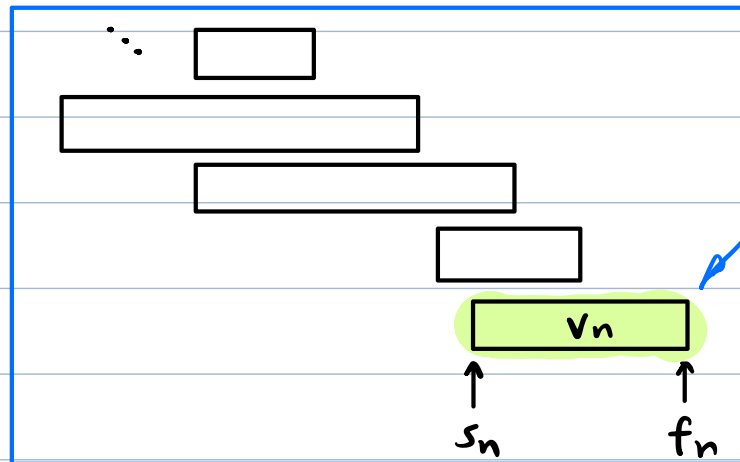
optimal weighted



Note: Greedy does not work for weighted version.

Recursive Formulation:

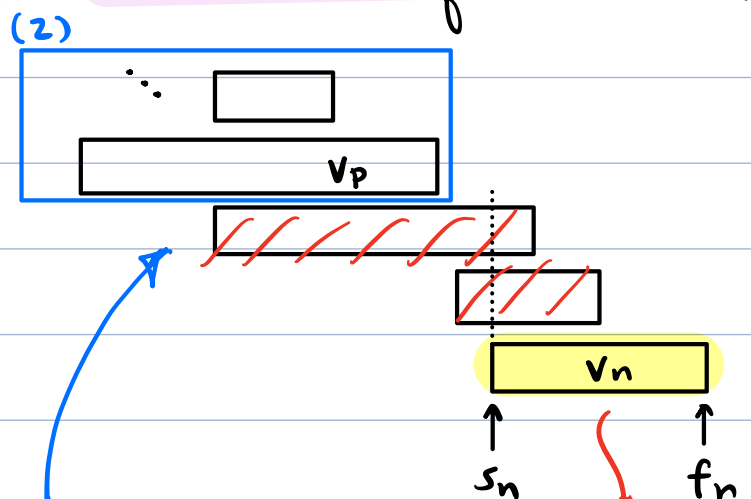
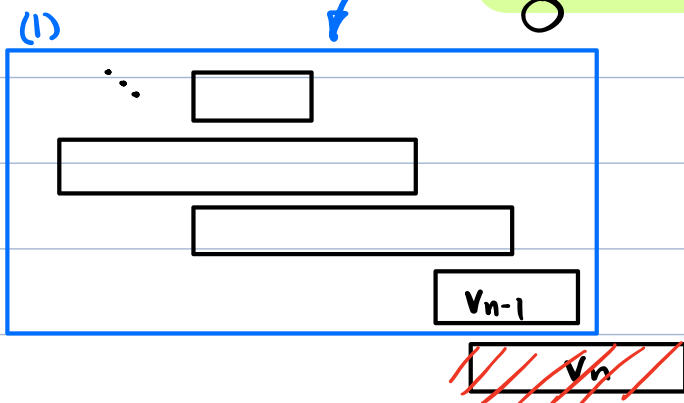
- Assume requests sorted by finish times
- Consider the last request



- Two possibilities:

(1) $[s_n, f_n]$ not in opt schedule

- Ignore it + recurse on requests 1..n-1



(2) $[s_n, f_n]$ is in opt schedule

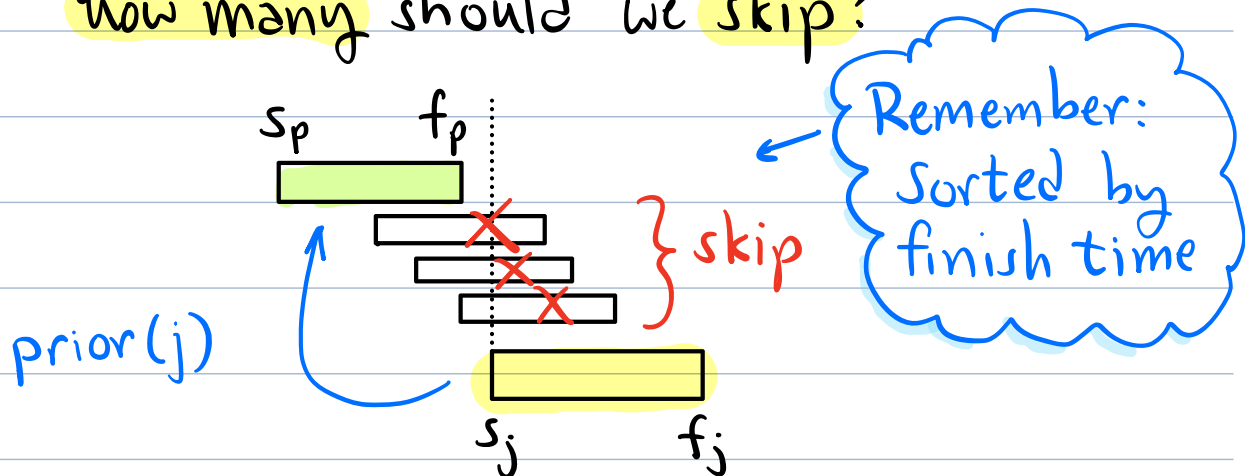
- Add to schedule + $\$v_n$

- Skip overlapping intervals $\{p+1, \dots, n-1\}$

- Recurse on requests 1..p

+ $\$v_n$

When we add a request j to schedule, how many should we skip?



Define: for $1 \leq j \leq n$

$$\text{prior}(j) = \max_P \text{ s.t. } f_p < s_j$$

(or 0 if there is none)

Example:

j	intervals and values	$\text{prior}(j)$
1		0
2		0
3		1
4		0
5		3
6		3

Optimal Total Value:

for $0 \leq j \leq n$, $W(j) = \text{max value}$
possible for requests $1, 2, \dots, j$

$$W(j) = \begin{cases} 0 & \text{(basis)} & \text{if } j = 0 \\ \max \left\{ \begin{array}{l} W(j-1) \text{ (reject)} \\ v_j + W(\text{prior}(j)) \text{ (accept)} \end{array} \right\} & \text{if } j > 0 \end{cases}$$

skips requests
that overlap j

Recursive implementation: (+ why this is bad!)

$WIS(s[1..n], f[1..n], v[1..n])$

Sort requests by finish time

Compute $\text{prior}[j]$ (for $1 \leq j \leq n$)

return $\text{rec-WIS}(n)$ // total value

$\text{rec-WIS}(j)$

// value of $1..j$

if ($j = 0$) return 0

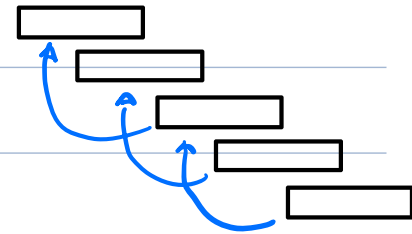
// basis

else return $\max \left\{ \begin{array}{l} W(j-1) \\ v[j] + \text{rec-WIS}(\text{prior}[j]) \end{array} \right.$

Too Slow! Why?

Let $T(j)$ = num. of recursive calls to $recWIS(0)$ arising from $recWIS(j)$

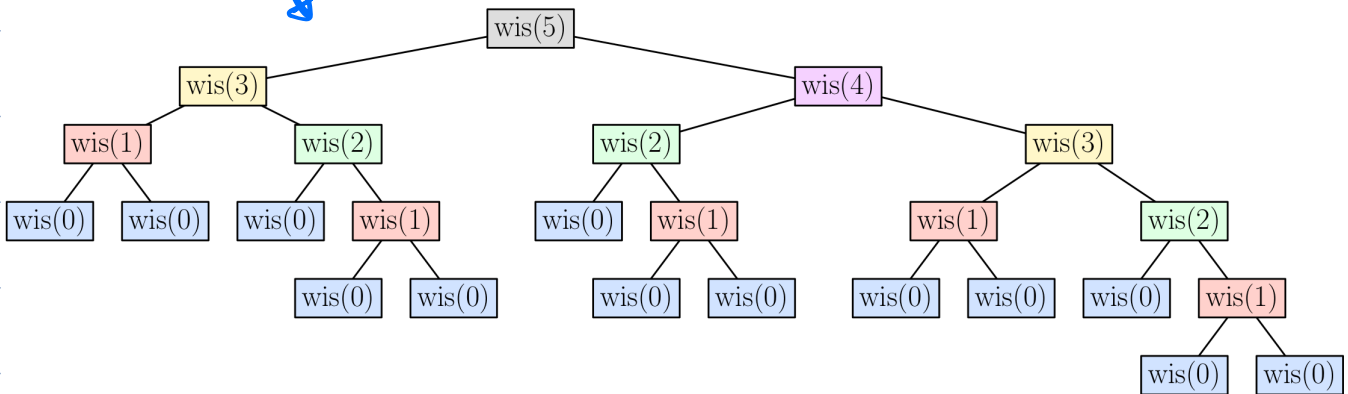
Suppose $prior(j) = j-2, \forall j$



$rec-WIS(j)$ calls:

- $rec-WIS(j-1)$

- $rec-WIS(prior(j)) = rec-WIS(j-2)$



$$\Rightarrow T(j) = T(j-1) + T(j-2) \quad \left. \vphantom{T(j)} \right\} \text{Fibonacci}$$
$$+ T(0) = 1$$

Grows fast!

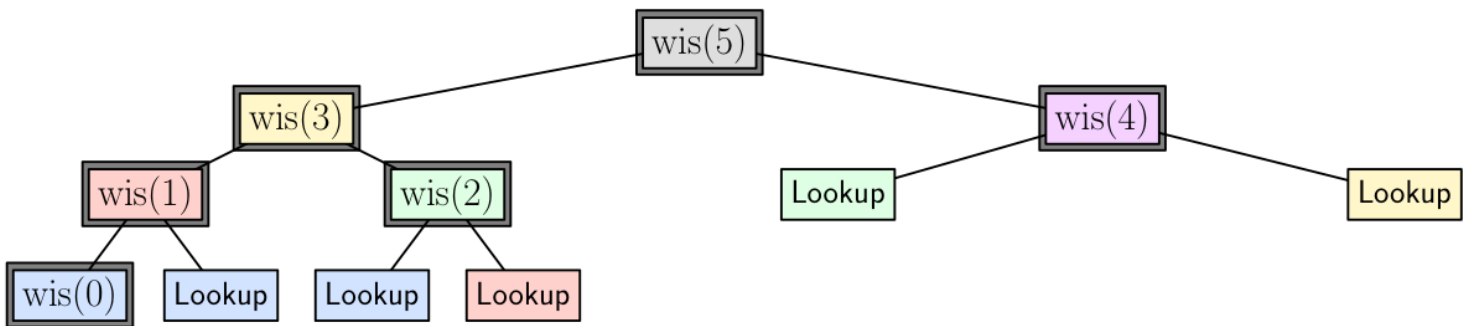
j :	0	1	2	3	4	5...	30	50
$T(j)$:	1	2	3	5	8	13...	2 Meg!	30 Gig!

How do we improve?

Memoization (a.k.a. caching)

Idea: After computing $W(j)$, save it in an array, say $W[j]$.

- Next time we need its value, look it up.
- Results in many fewer recursive calls, $O(n)$



Updated implementation:

- Sort by finish times } (as before)
- Compute prior $[]$ array }
- Init: $W[j] = -1$ (means "undefined")
- Array: $accept[1..n]$

$accept[j] = True$ - accept request j
 $False$ - reject " "

We'll use this to construct final schedule (later)

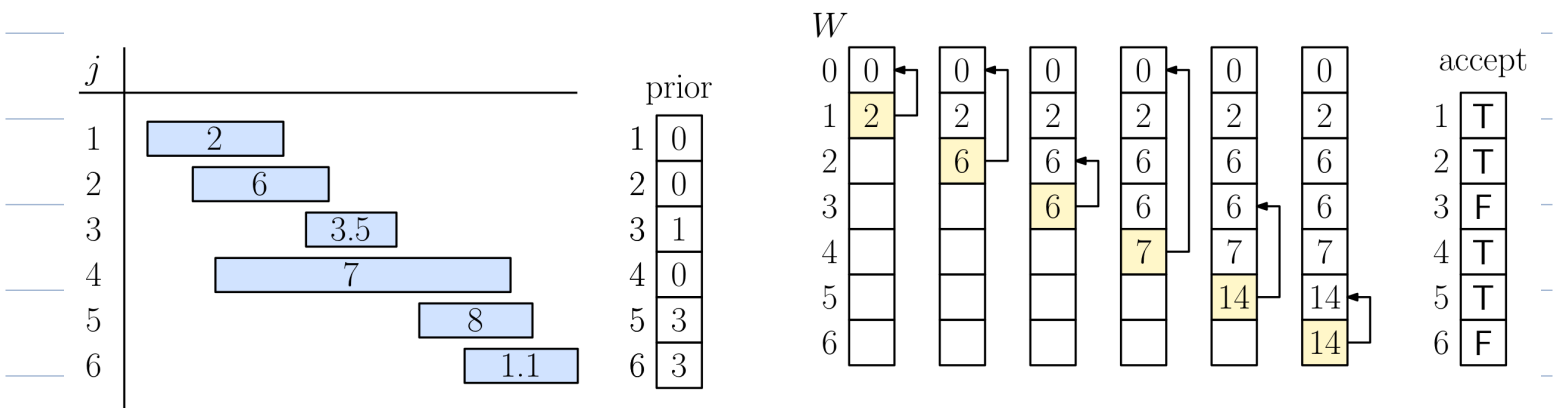
- return memo-WIS(n)

```

memo-WIS(j) // memoized WIS
if (W[j] = -1) // W[j] undefined?
  if (j = 0) W[j] ← 0 // basis
  else
    rejVal ← memo-WIS(j-1) // rej/acc values
    accVal ← v[j] + memo-WIS(prior[j])
    if (rejVal > accVal) // better to reject
      W[j] ← rejVal
      accept[j] ← false
    else // better to accept
      W[j] ← accVal
      accept[j] ← true
return W[j] // return value

```

Example: (W-values are created bottom-up)



Running Time - $O(n)$ [$n+1$ rec. calls, each $O(1)$]

Bottom-Up Construction: (Optional)

- In practice it is often more efficient to unravel the recursion, and build W bottom-up
- As before:
 - Sorted by finish times
 - prior [...] computed

```
bottom-up-WIS() // bottom-up implementation
W[0] ← 0 // basis
for (i ← 1 to n)
  rejVal ← W[j-1] // rej/acc values
  accVal ← v[j] + W[prior[j]]
  if (rejVal > accVal) // better to reject
    W[j] ← rejVal
    accept[j] ← false
  else // better to accept
    W[j] ← accVal
    accept[j] ← true
return W[n] // final value
```

Running Time - $O(n)$ (obvious)



Computing the Final Schedule:

- So far we only compute the final value, $W[n]$
- Use the `accept[]` array to guide us

Start at end ($j \leftarrow n$) + work back (until $j == 0$)

if `accept[j] = True`:

- add j to schedule
- continue with $j \leftarrow \text{prior}[j]$

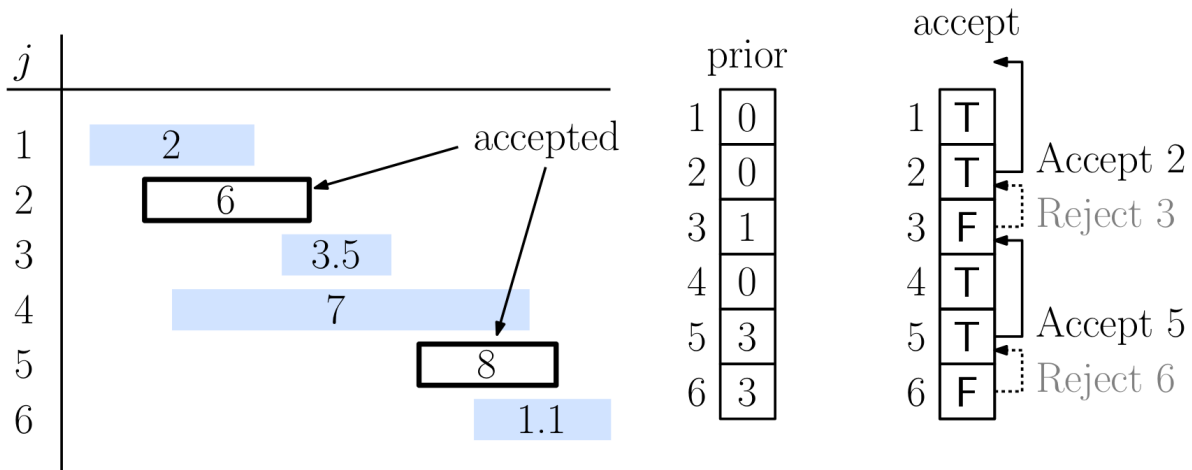
skip over overlapping requests

else:

- don't add to schedule
- continue with $j \leftarrow j - 1$

```
get-schedule() // get final schedule
  j ← n // start at end
  sched ← ∅ // init empty sched.
  while (j > 0)
    if (accept[j]) // accepted j
      prepend [j] to sched
      j ← prior[j]
    else // rejected j
      j ← j - 1
  return sched // final schedule
```

Example:



Trace: $j \leftarrow 6$

$\text{accept}[6] = F$ $j \leftarrow 6-1 = 5$

$\text{accept}[5] = T$ add 5, $j \leftarrow \text{prior}[5] = 3$

$\text{accept}[3] = F$ $j \leftarrow 3-1 = 2$

$\text{accept}[2] = T$ add 2, $j \leftarrow \text{prior}[2] = 0$

$j = 0 \rightarrow \text{terminate}$

Note: Even though
 $\text{accept}[4] = T$
 $\text{accept}[1] = T$
 we never visit these

Summary -

- Intro. to dynamic programming
 - Recursive structure (subproblems)
 - Principle of optimality
- Weighted Interval Scheduling
 - Recursive (slow!), memoized, bottom-up