

CSMC 412

Operating Systems

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Synchronization

Set 9

Semaphore

- Invented by Edsger Dijkstra in 1962
 - When working on and operating system for Electrologica X which became THE.
- A non-negative, integer, Global variable (S)
 - Initialized at set up time, and
 - Two operations are allowed
 - P(S) ----- Wait(S)
 - Decrement S
 - Wait until this operation can be carried out.
 - V(S) -----Signal(S)
 - Increment S
- Both operations are considered Atomic

Semaphore

- Synchronization tool that provides more sophisticated ways (than Mutex locks) for process to synchronize their activities.
- Semaphore S – integer variable
- Can only be accessed via two indivisible (atomic) operations
 - **wait()** and **signal()**
 - Originally called **P()** and **V()**

- Definition of the **wait()** operation

```
wait(S) {  
    while (S <= 0)  
        ; // busy wait  
    S--;  
}
```

- Definition of the **signal()** operation

```
signal(S) {  
    S++;  
}
```

Information Implications of Semaphore

- A process has synch points
 - To go past a synch point certain conditions must be true
 - Conditions depend not only on ME but other processes also
 - Must confirm that the conditions are true before proceeding, else have to wait.
- $P(S)$ – Wait (S)
 - If can complete this operation
 - Inform others through changed value of S
 - Proceed past the synch point
 - If can not complete
 - Wait for the event when S becomes >0
- $V(S)$ – Signal (S)
 - Inform others that I have gone past a synch point.

Semaphore Usage

- **Counting semaphore** – integer value can range over an unrestricted domain
- **Binary semaphore** – integer value can range only between 0 and 1
 - Same as a **mutex lock**
- Can solve various synchronization problems
- Consider P_1 and P_2 that require S_1 to happen before S_2

Create a semaphore “**synch**” initialized to 0

P1:

```
S1;  
signal (synch) ;
```

P2:

```
wait (synch);  
S2;
```

- Can implement a counting semaphore S as a binary semaphore

Semaphore as General Synchronization Tool

- Counting semaphore – integer value can range over an unrestricted domain
- Binary semaphore – integer value can range only between 0 and 1; can be simpler to implement
 - Also known as mutex locks
- Can implement a counting semaphore S as a binary semaphore
- Provides mutual exclusion

Semaphore S ; // initialized to 1

P(S);
CriticalSection();
V(S);

Binary Semaphore

- Data structures:

binary-semaphore S1, S2;

int C;

- Initialization:

S1 = 1

S2 = 0

C = initial value of semaphore S

Implementing *Counting Semaphore*

- *wait* operation

```
wait(S1);  
C--;  
if (C < 0) {  
    signal(S1);  
    wait(S2);  
}  
signal(S1);
```

- *signal* operation

```
wait(S1);  
C ++;  
if (C <= 0)  
    signal(S2);  
else  
    signal(S1);
```


Semaphore Implementation

- Must guarantee that no two processes can execute the `wait()` and `signal()` on the same semaphore at the same time
- Thus, the implementation becomes the critical section problem where the `wait` and `signal` code are placed in the critical section
 - Could now have **busy waiting** in critical section implementation
 - But implementation code is short
 - Little busy waiting if critical section rarely occupied
- Note that applications may spend lots of time in critical sections and therefore this is not a good solution

Semaphore Implementation with no Busy waiting

- With each semaphore there is an associated waiting queue
- Each entry in a waiting queue has two data items:
 - value (of type integer)
 - pointer to next record in the list
- Two operations:
 - **block** – place the process invoking the operation on the appropriate waiting queue
 - **wakeup** – remove one of processes in the waiting queue and place it in the ready queue
- ```
typedef struct{
 int value;
 struct process *list;
} semaphore;
```

# Implementation with no Busy waiting (Cont.)

```
wait(semaphore *S) {
 S->value--;
 if (S->value < 0) {
 add this process to S->list;
 block();
 }
}

signal(semaphore *S) {
 S->value++;
 if (S->value <= 0) {
 remove a process P from S->list;
 wakeup(P);
 }
}
```

# Deadlock and Starvation

- **Deadlock** – two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes
- Let  $s$  and  $q$  be two semaphores initialized to 1

| $P_0$                   | $P_1$                   |
|-------------------------|-------------------------|
| <code>wait(S);</code>   | <code>wait(Q);</code>   |
| <code>wait(Q);</code>   | <code>wait(S);</code>   |
| <code>...</code>        | <code>...</code>        |
| <code>signal(S);</code> | <code>signal(Q);</code> |
| <code>signal(Q);</code> | <code>signal(S);</code> |

- **Starvation – indefinite blocking**
  - A process may never be removed from the semaphore queue in which it is suspended
- **Priority Inversion** – Scheduling problem when lower-priority process holds a lock needed by higher-priority process
  - Solved via **priority-inheritance protocol**

# Problems with Semaphores

- Incorrect use of semaphore operations:
  - signal (mutex) .... wait (mutex)
  - wait (mutex) ... wait (mutex)
  - Omitting of wait (mutex) or signal (mutex) (or both)
- Deadlock and starvation are possible.

# Monitors

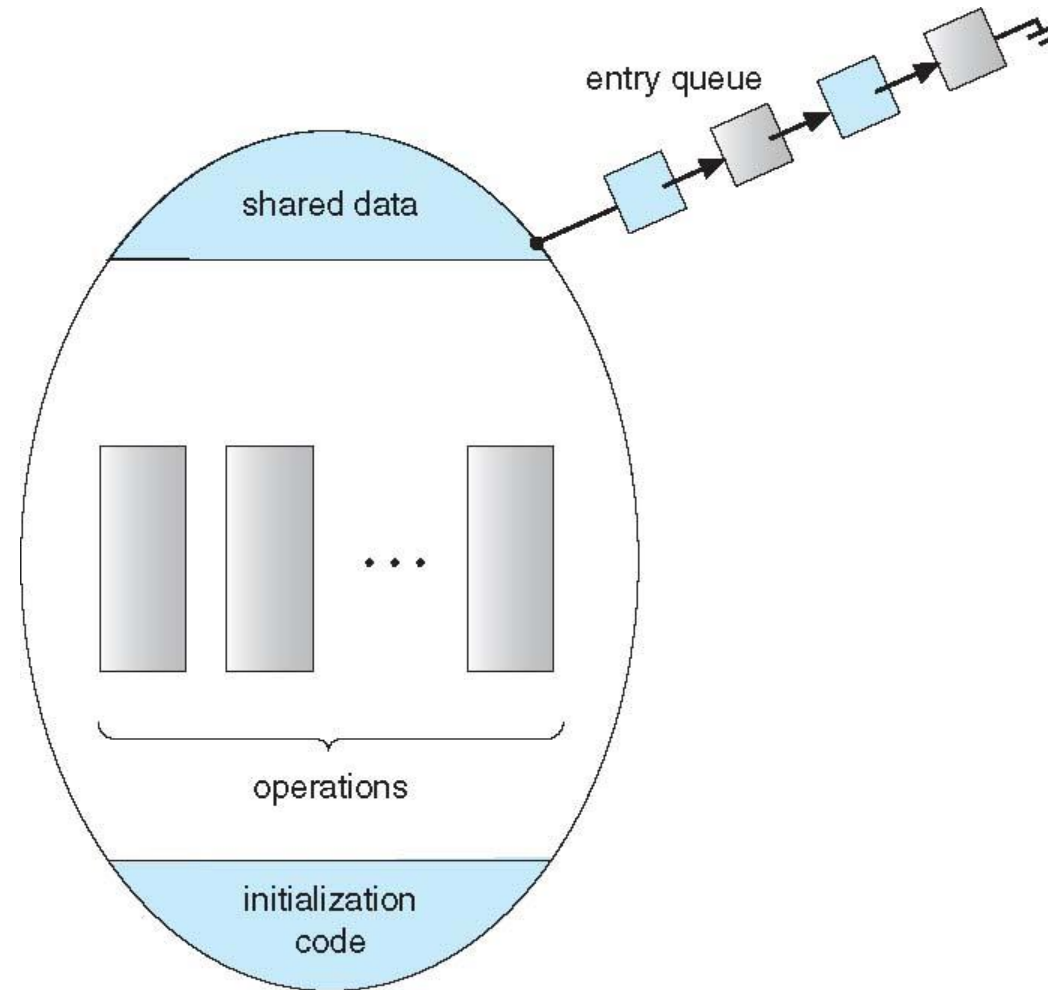
- A high-level abstraction that provides a convenient and effective mechanism for process synchronization
- *Abstract data type*, internal variables only accessible by code within the procedure
- Only one process may be active within the monitor at a time
- But not powerful enough to model some synchronization schemes

```
monitor monitor-name
{
 // shared variable declarations
 procedure P1 (...) { ... }

 procedure Pn (...) {.....}

 Initialization code (...) { ... }
}
```

# Schematic view of a Monitor

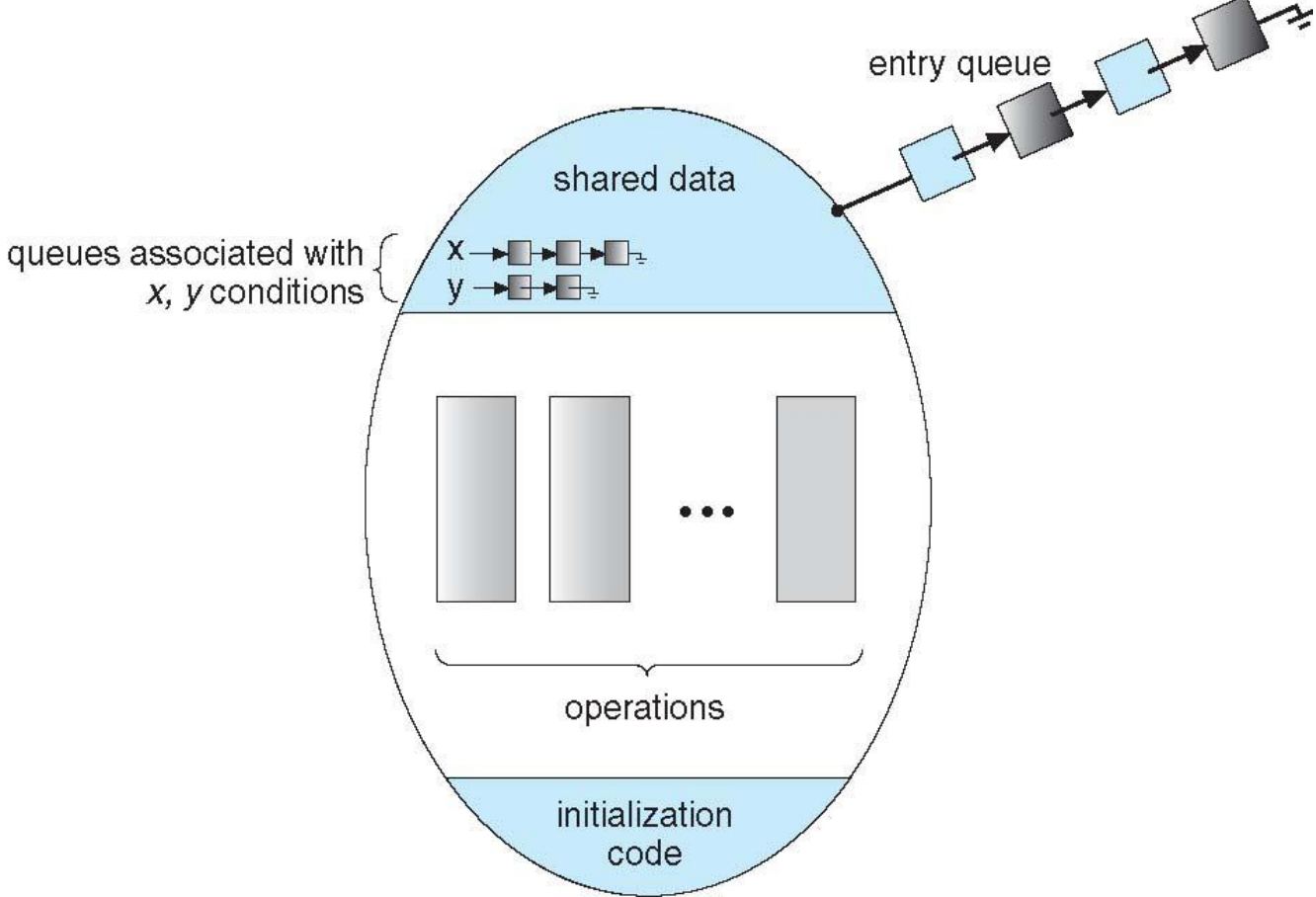


# Condition Variables

- `condition x, y;`
- Two operations are allowed on a condition variable:
  - `x.wait()` – a process that invokes the operation is suspended until `x.signal()`
  - `x.signal()` – resumes one of processes (if any) that invoked `x.wait()`
    - If no `x.wait()` on the variable, then it has no effect on the variable



# Monitor with Condition Variables



# Condition Variables Choices

- If process P invokes `x.signal()`, and process Q is suspended in `x.wait()`, what should happen next?
  - Both Q and P cannot execute in parallel. If Q is resumed, then P must wait
- Options include
  - **Signal and wait** – P waits until Q either leaves the monitor or it waits for another condition
  - **Signal and continue** – Q waits until P either leaves the monitor or it waits for another condition
  - Both have pros and cons – language implementer can decide
  - Monitors implemented in Concurrent Pascal compromise
    - P executing signal immediately leaves the monitor, Q is resumed
  - Implemented in other languages including Mesa, C#, Java

# Monitor Implementation Using Semaphores

- Variables

```
semaphore mutex; // (initially = 1)
semaphore next; // (initially = 0)
int next_count = 0;
```

- Each procedure  $F$  will be replaced by

```
wait(mutex);
...
body of F;
...
if (next_count > 0)
 signal(next)
else
 signal(mutex);
```

- Mutual exclusion within a monitor is ensured

# Monitor Implementation – Condition Variables

- For each condition variable  $x$ , we have:

```
semaphore x_sem; // (initially = 0)
int x_count = 0;
```

- The operation  $x.wait$  can be implemented as:

```
x_count++;
if (next_count > 0)
 signal(next);
else
 signal(mutex);
wait(x_sem);
x_count--;
```

# Monitor Implementation (Cont.)

- The operation `x.signal` can be implemented as:

```
if (x_count > 0) {
 next_count++;
 signal(x_sem);
 wait(next);
 next_count--;
}
```

# Resuming Processes within a Monitor

- If several processes queued on condition `x`, and `x.signal()` executed, which should be resumed?
- FCFS frequently not adequate
- **conditional-wait** construct of the form `x.wait(c)`
  - Where `c` is **priority number**
  - Process with lowest number (highest priority) is scheduled next

# Single Resource allocation

- Allocate a single resource among competing processes using priority numbers that specify the maximum time a process plans to use the resource

```
R.acquire(t) ;
```

```
...
```

```
access the resource ;
```

```
...
```

```
R.release ;
```

- Where R is an instance of type `ResourceAllocator`

# A Monitor to Allocate Single Resource

```
monitor ResourceAllocator
{
 boolean busy;
 condition x;
 void acquire(int time) {
 if (busy)
 x.wait(time);
 busy = TRUE;
 }
 void release() {
 busy = FALSE;
 x.signal();
 }
 initialization code() {
 busy = FALSE;
 }
}
```