#### CSMC 412

Operating Systems
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Synchronization Examples

# Synchronization Examples

- Classic Problems of Synchronization
- Synchronization within the Kernel
- POSIX Synchronization
- Synchronization in Java
- Alternative Approaches

## Classical Problems of Synchronization

- Classical problems used to test newly-proposed synchronization schemes
  - Bounded-Buffer Problem
  - Readers and Writers Problem
  - Dining-Philosophers Problem

#### Bounded-Buffer Problem

- *n* buffers, each can hold one item
- Semaphore mutex initialized to the value 1
- Semaphore full initialized to the value 0
- Semaphore empty initialized to the value n

#### Bounded Buffer Problem (Cont.)

• The structure of the producer process

```
do {
     /* produce an item in next produced */
      . . .
   wait(empty);
   wait(mutex);
     /* add next produced to the buffer */
   signal(mutex);
   signal(full);
} while (true);
```

#### Bounded Buffer Problem (Cont.)

• The structure of the consumer process

```
Do {
   wait(full);
   wait(mutex);
   /* remove an item from buffer to next consumed */
       . . .
   signal(mutex);
   signal(empty);
   /* consume the item in next consumed */
} while (true);
```

#### Readers-Writers Problem

- A data set is shared among a number of concurrent processes
  - Readers only read the data set; they do **not** perform any updates
  - Writers can both read and write
- Problem allow multiple readers to read at the same time
  - Only one single writer can access the shared data at the same time
- Several variations of how readers and writers are considered all involve some form of priorities
- Shared Data
  - Data set
  - Semaphore rw\_mutex initialized to 1
  - Semaphore mutex initialized to 1
  - Integer read\_count initialized to 0

### Readers-Writers Problem (Cont.)

• The structure of a writer process

#### Readers-Writers Problem (Cont.)

The structure of a reader process

```
do {
     wait(mutex);
      read count++;
      if (read count == 1)
       wait(rw mutex);
    signal(mutex);
      /* reading is performed */
    wait(mutex);
      read count--;
      if (read count == 0)
    signal(rw mutex);
    signal(mutex);
 while (true);
```

#### Readers-Writers Problem Variations

- First variation no reader kept waiting unless writer has permission to use shared object
- **Second** variation once writer is ready, it performs the write ASAP
- Both may have starvation leading to even more variations
- Problem is solved on some systems by kernel providing readerwriter locks

### Dining-Philosophers Problem



- Philosophers spend their lives alternating thinking and eating
- Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl
  - Need both to eat, then release both when done
- In the case of 5 philosophers
  - Shared data
    - Bowl of rice (data set)
    - Semaphore chopstick [5] initialized to 1

#### Dining-Philosophers Problem Algorithm

• The structure of Philosopher *i*:

What is the problem with this algorithm?

#### Monitor Solution to Dining Philosophers

```
monitor DiningPhilosophers
  enum { THINKING; HUNGRY, EATING) state [5] ;
  condition self [5];
 void pickup (int i) {
         state[i] = HUNGRY;
         test(i);
         if (state[i] != EATING) self[i].wait;
   void putdown (int i) {
         state[i] = THINKING;
                   // test left and right neighbors
          test((i + 4) % 5);
          test((i + 1) % 5);
```

# Solution to Dining Philosophers (Cont.)

```
void test (int i) {
        if ((state[(i + 4) % 5] != EATING) &&
        (state[i] == HUNGRY) &&
        (state[(i + 1) % 5] != EATING)) {
             state[i] = EATING ;
          self[i].signal () ;
     initialization code() {
       for (int i = 0; i < 5; i++)
       state[i] = THINKING;
```

#### Solution to Dining Philosophers (Cont.)

• Each philosopher i invokes the operations pickup() and putdown() in the following sequence:

```
DiningPhilosophers.pickup(i);
```

#### EAT

```
DiningPhilosophers.putdown(i);
```

No deadlock, but starvation is possible

## A Monitor to Allocate Single Resource

```
monitor ResourceAllocator
  boolean busy;
  condition x;
  void acquire(int time) {
           if (busy)
              x.wait(time);
           busy = TRUE;
  void release() {
           busy = FALSE;
           x.signal();
initialization code() {
  busy = FALSE;
```

# Synchronization Examples

- Solaris
- Windows
- Linux
- Pthreads

# Solaris Synchronization

- Implements a variety of locks to support multitasking, multithreading (including real-time threads), and multiprocessing
- Uses adaptive mutexes for efficiency when protecting data from short code segments
  - Starts as a standard semaphore spin-lock
  - If lock held, and by a thread running on another CPU, spins
  - If lock held by non-run-state thread, block and sleep waiting for signal of lock being released
- Uses condition variables
- Uses readers-writers locks when longer sections of code need access to data
- Uses turnstiles to order the list of threads waiting to acquire either an adaptive mutex or reader-writer lock
  - Turnstiles are per-lock-holding-thread, not per-object
- Priority-inheritance per-turnstile gives the running thread the highest of the priorities of the threads in its turnstile

## Windows Synchronization

- Uses interrupt masks to protect access to global resources on uniprocessor systems
- Uses spinlocks on multiprocessor systems
  - Spinlocking-thread will never be preempted
- Also provides dispatcher objects user-land which may act mutexes, semaphores, events, and timers
  - Events
    - An event acts much like a condition variable
  - Timers notify one or more thread when time expired
  - Dispatcher objects either signaled-state (object available) or non-signaled state (thread will block)

## Linux Synchronization

#### • Linux:

- Prior to kernel Version 2.6, disables interrupts to implement short critical sections
- Version 2.6 and later, fully preemptive
- Linux provides:
  - Semaphores
  - atomic integers
  - spinlocks
  - reader-writer versions of both
- On single-cpu system, spinlocks replaced by enabling and disabling kernel preemption

# Pthreads Synchronization

- Pthreads API is OS-independent
- It provides:
  - mutex locks
  - condition variable
- Non-portable extensions include:
  - read-write locks
  - spinlocks

## Alternative Approaches

- Transactional Memory
- OpenMP
- Functional Programming Languages

#### **Transactional Memory**

• A memory transaction is a sequence of readwrite operations to memory that are performed atomically.

```
void update()
{
   /* read/write memory */
}
```

#### **OpenMP**

 OpenMP is a set of compiler directives and API that support parallel programming.

```
void update(int value)
{
    #pragma omp critical
    {
        count += value
    }
}
```

The code contained within the **#pragma omp critical** directive is treated as a critical section and performed atomically.

#### **Functional Programming Languages**

- Functional programming languages offer a different paradigm than procedural languages in that they do not maintain state.
- Variables are treated as immutable and cannot change state once they have been assigned a value.
- There is increasing interest in functional languages such as Erlang and Scala for their approach in handling data races.