

Topological Distance Between Nonplanar Transportation Networks

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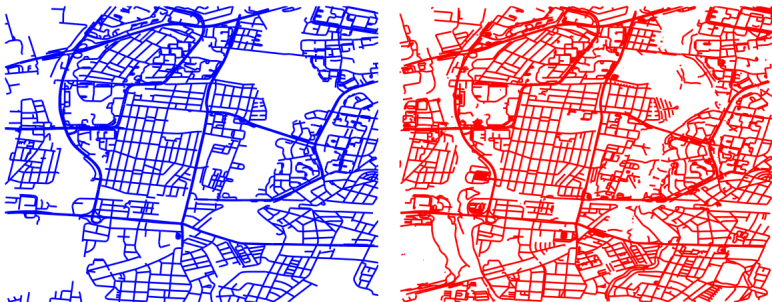
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Map Comparison

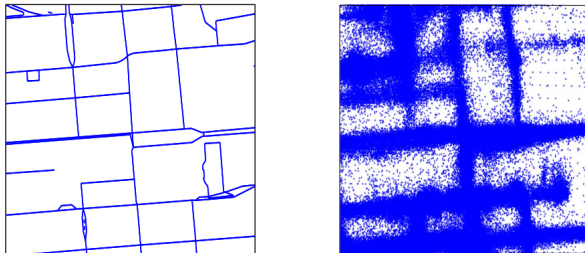


Two maps of Berlin: 2007 (left) vs. 2013 (right)
[Ahmad, Fasy and Wenk, SigSpatial'14]

Problem

How to compare two such maps?

Why Map Comparison?

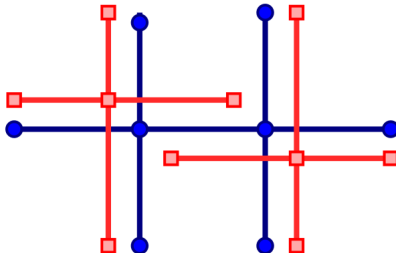


Ground truth vs. density plot [AFW, SigSpatial'15]

Applications

- Evaluation and comparison of map reconstruction algorithms
- Urban morphology

Why Topology?

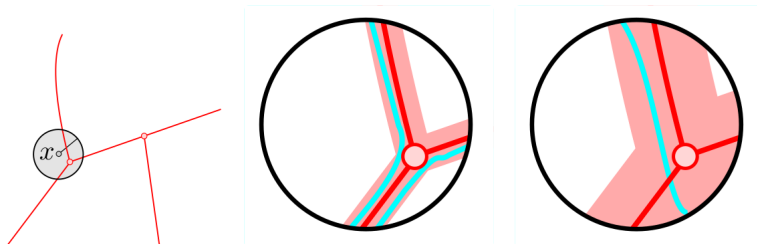


Two street intersections [AFW, SigSpatial'14]

Two types of error

- Hausdorff distance: **low**
- Topology: **different**

Topology-based Map Comparison



[AFW, SigSpatial'14]

A topological signature at x

- Compute the *local persistent homology* in the neighborhood of x
 - Define *offsets* by thickening street segments
 - Compute a filtration from overlapping offsets
 - Compute the persistent homology of the filtration
 - .. relative to the boundary of the neighborhood
- Compare the barcodes for different maps

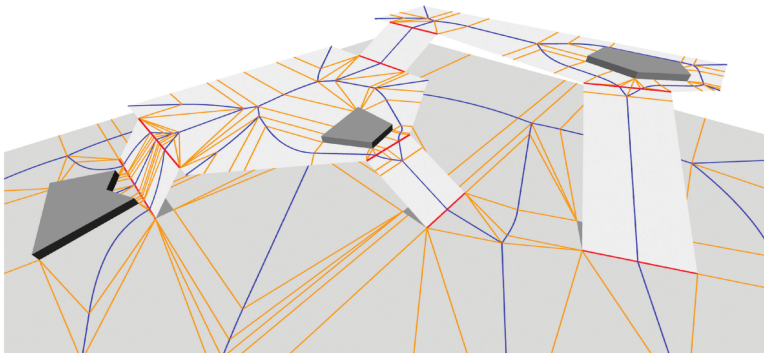
Assumption of Planarity ..



.. can lead to drastic errors in street network analysis
[Boeing, Environment & Planning B '18]

Left: High Five Interchange, Dallas, USA
Right: Magdeburg Water Bridge, Magdeburg, Germany

Multi-Layered Environments

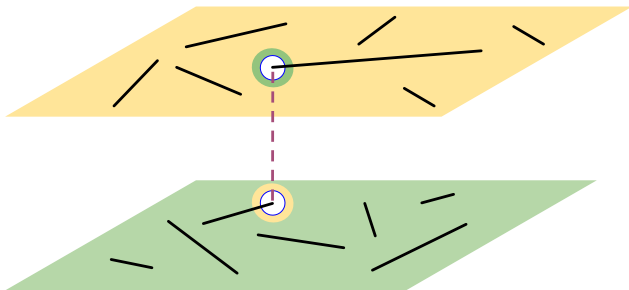


[van Toll, Cook, van Kreveld and Geraerts, TSAS'18]

Nearly 2D

- For many planning problems, 3D is an overkill
- Extend algorithms and data structures from 2D

Grade-separated Street Networks

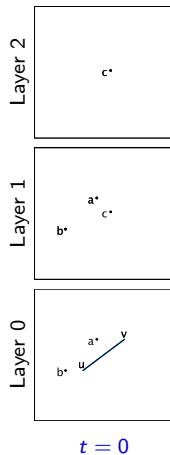


Abstract model for street networks

Allowing non-planarity

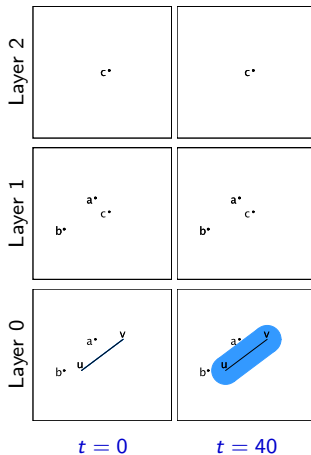
- Multiple copies of \mathbb{R}^2 (*layers*) identified at special vertices (*portals*)
- Segment offsets grow through portals onto connected layers

Segment Offsets



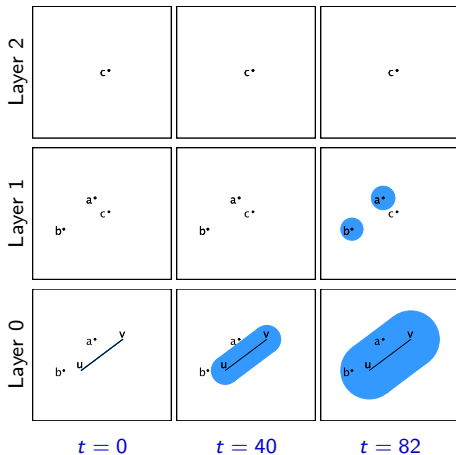
Offset of a segment \overline{uv} across three layers

Segment Offsets



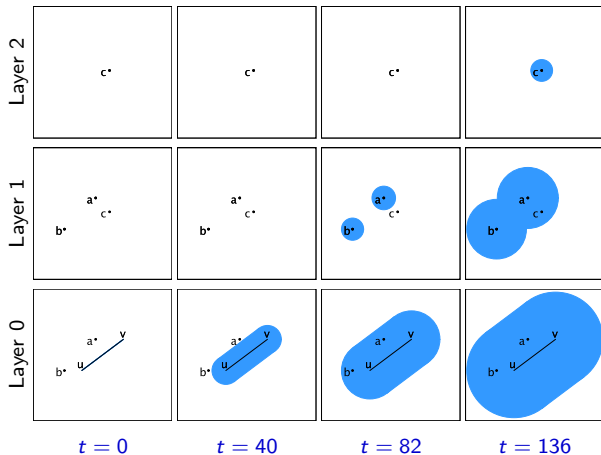
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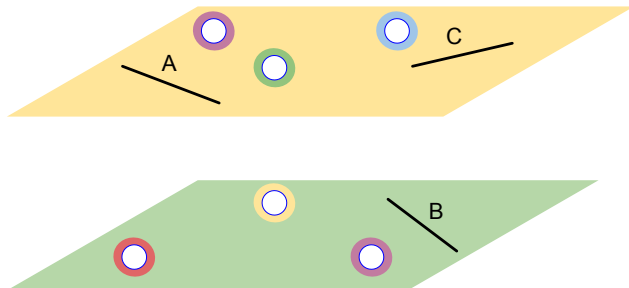
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Segment Offsets



Offset of a segment \overline{uv} across three layers

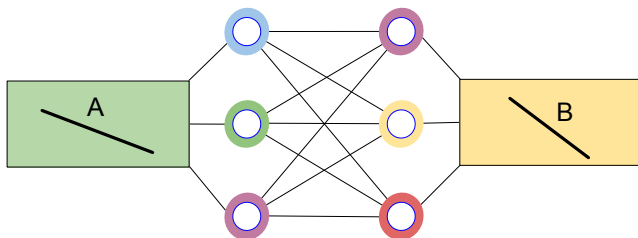
Overlap Computation - Two-way



Determine the earliest time when offsets intersect

- Case(1): segments in the same layer, e.g., A & C \Rightarrow old school
- Case(2): segments in different layers, e.g., A & B \Rightarrow via portals ..

Overlap Computation - Two-way: Case(2)



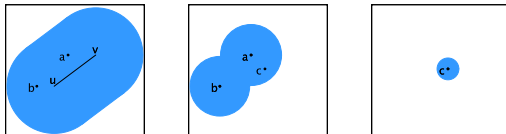
Shortest path through portal graph

- Precompute all-pairs shortest paths on a *portal graph*
- Connect A and B to portals on respective layers
- Find the shortest path from A to B

Overlap Computation - Three-way

Which layer realizes the overlap?

- Same as segment \Rightarrow offset is a segment offset (S)
- Different layer \Rightarrow offset is a disk centered at some portal (D)



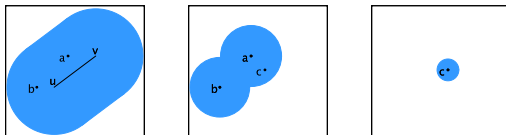
Earliest time when offsets intersect .. but at which layer?

- Case(1): SSS \Rightarrow segment Voronoi diagram
- Case(2): SSD \Rightarrow disk + segment bisector (straight & parabolic arcs)
- Case(3): SDD \Rightarrow weighted segment + disk bisector (hyperbola)
- Case(4): DDD \Rightarrow Apollonius diagram

Overlap Computation - Three-way

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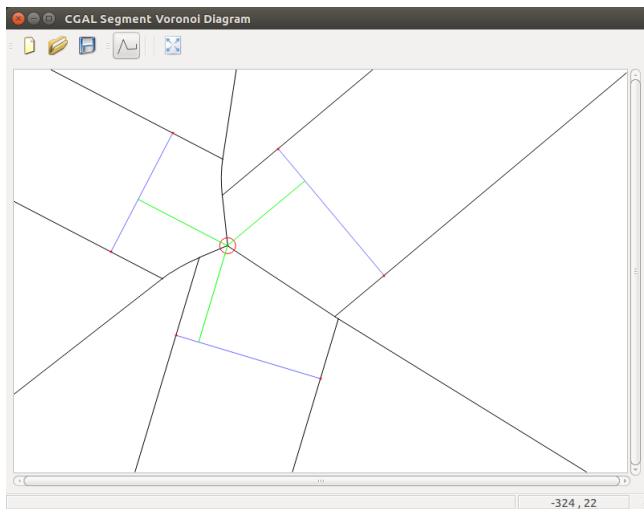
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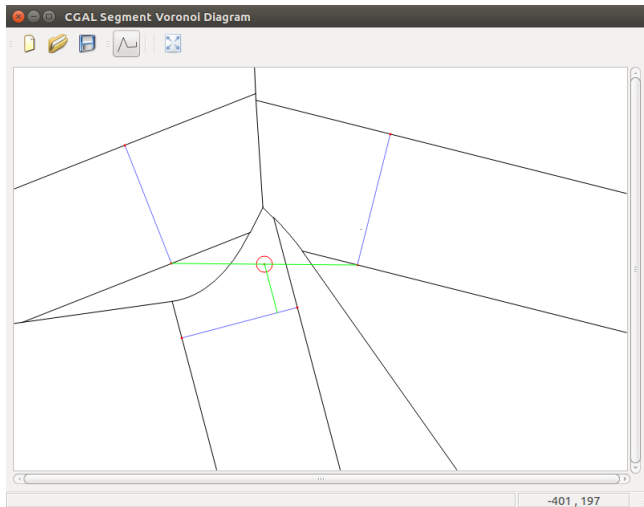
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Overlap Computation - Three-way: Case(1) SSS



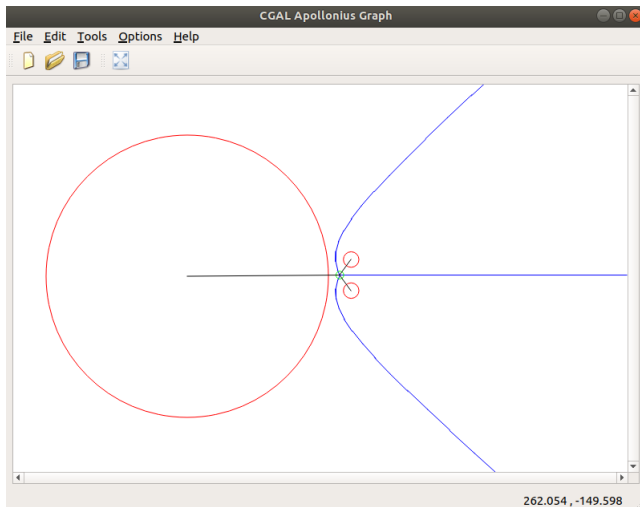
Case(1.1): earliest overlap at a Voronoi vertex

Overlap Computation - Three-way: Case(1) SSS



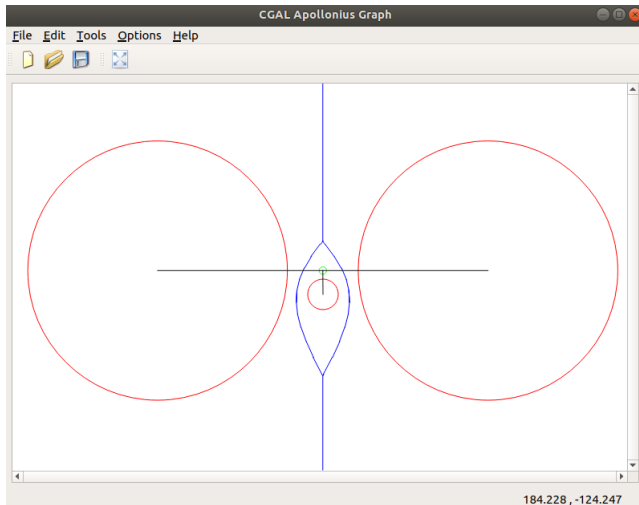
Case(1.2): earliest overlap in the interior of a cell

Overlap Computation - Three-way: Case(4) DDD



Case(4.1): earliest overlap at an Apollonius vertex

Overlap Computation - Three-way: Case(4) DDD



Case(4.2): earliest overlap in the interior of a cell

Summary

Topological Distance for Non-planar Street Networks

- Model grade-separated networks as multi-layered graphs
- Define segment offsets and filtrations across layers
- Next steps
 - Implement LPH computation (based on CGAL & Dionysus)
 - Run experiments, e.g., data from OpenStreetMap
 - Formalize the new map distance

Thanks for listening

Questions?
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