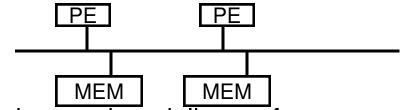
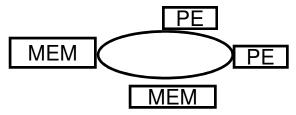
Communication Networks

- Connect
 - PE's, memory, I/O
- Key Performance Issues
 - latency: time for first byte
 - throughput: average bytes/second
- Possible Topologies
 - bus simple, but doesn't scale



ring - orders delivery of messages



CMSC 714 - F15 (lect 2)

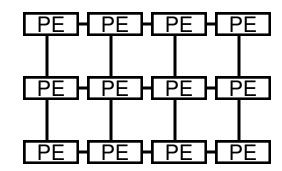
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Topologies (cont)

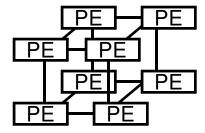
tree - needs to increase bandwidth near the top



-mesh - two or three dimensions



–hypercube - needs a power of number of nodes



Memory Systems

- Key Performance Issues
 - latency: time for first byte
 - throughput: average bytes/second
- Design Issues
 - Where is the memory
 - divided among each node
 - centrally located (on communication network)
 - Access by processors
 - can all processors get to all memory?
 - is the access time uniform?

Coordination

- Synchronization
 - protection of a single object (locks)
 - coordination of processors (barriers)
- Size of a unit of work by a processor
 - need to manage two issues
 - load balance processors have equal work
 - coordination overhead communication and sync.
 - often called "grain" size large grain vs. fine grain

Sources of Parallelism

Statements

- called "control parallel"
- can perform a series of steps in parallel

Loops

- called "data parallel"
- most common source of parallelism
- each processor gets one (or more) iterations to perform

Example of Parallelism

- Easy (embarrassingly parallel)
 - multiple independent jobs (i.e..., different simulations)
- Scientific
 - Largest users of parallel computing
 - dense linear algebra (divide up matrix)
 - physical system simulations (divide physical space)
- Databases
 - biggest commercial success of parallel computing (divide tuples)
 - exploits semantics of relational calculus
- Al
 - search problems (divide search space)
 - pattern recognition and image processing (divide image)

Metrics in Application Performance

- Speedup (often call strong scaling)
 - ratio of time on n nodes to time on a single node
 - hold problem size fixed
 - should really compare to best serial time
 - goal is linear speedup
 - super-linear speedup is possible due to:
 - adding more memory
 - · search problems
- Weak Scaling (also called Iso-Speedup)
 - scale data size up with number of nodes
 - goal is a flat horizontal curve
- Amdahl's Law
 - max speedup is 1/(serial fraction of time)
- Computation to Communication Ratio
 - goal is to maximize this ratio

How to Write Parallel Programs

- Use old serial code
 - compiler converts it to parallel
 - called the dusty deck problem
- Serial Language plus Communication Library
 - no compiler changes required!
 - PVM and MPI use this approach
- New language for parallel computing
 - requires all code to be re-written
 - hard to create a language that provides performance on different platforms
- Hybrid Approach
 - HPF add data distribution commands to code
 - add parallel loops and synchronization operations

Application Example - Weather

- Typical of many scientific codes
 - computes results for three dimensional space
 - compute results at multiple time steps
 - uses equations to describe physics/chemistry of the problem
 - grids are used to discretize continuous space
 - granularity of grids is important to speed/accuracy
- Simplifications (for example, not in real code)
 - earth is flat (no mountains)
 - earth is round (poles are really flat, earth buldges at equator)
 - second order properties

Grid Points

- Divide Continuous space into discrete parts
 - for this code, grid size is fixed and uniform
 - possible to change grid size or use multiple grids
 - use three grids
 - two for latitude and longitude
 - one for elevation
 - Total of M * N * L points
- Design Choice: where is the grid point?
 - left, right, or center of the grid



- in multiple dimensions this multiples:
 - for 3 dimensions have 27 possible points

Variables

- One dimensional
 - m geo-potential (gravitational effects)
- Two dimensional
 - pi "shifted" surface pressure
 - sigmadot vertical component of the wind velocity
- Three dimensional (primary variables)
 - <u,v> wind velocity/direction vector
 - T temperature
 - q specific humidity
 - p pressure
- Not included
 - clouds
 - precipitation
 - can be derived from others

Serial Computation

- Convert equations to discrete form
- Update from time t to t + delta t

```
foreach longitude, latitude, altitude
       ustar[i,j,k] = n * pi[i,j] * u[i,j,k]
      vstar[i,j,k] = m[j] * pi[i,j] * v[i,j,k]
       sdot[i,j,k] = pi[i,j] * sigmadot[i,j]
end
foreach longitude, latitude, altitude
       D = 4 * ((ustar[i,j,k] + ustar[i-1,j,k]) * (q[i,j,k] + q[i-1,j,k]) +
                     terms in \{i,j,k\}\{+,-\}\{1,2\}
       piq[i,j,k] = piq[i,j,k] + D * delat
       similar terms for piu, piv, piT, and pi
end
foreach longitude, latitude, altitude
       q[i,j,k] = piq[i,j,k]/pi[i,j,k]
       u[i,j,k] = piu[i,j,k]/pi[i,j,k]
      v[i,j,k] = piv[i,j,k]/pi[i,j,k]
       T[i,j,k] = piT[i,j,k]/pi[i,j,k]
end
```

Shared Memory Version

- in each loop nest, iterations are independent
- use a parallel for-loop for each loop nest
- synchronize (barrier) after each loop nest
 - this is overly conservative, but works
 - could use a single sync variable per item, but would incur excessive overhead
- potential parallelism is M * N * L
- private variables: D, i, j, k
- Advantages of shared memory
 - easier to get something working (ignoring performance)
- Hard to debug
 - other processors can modify shared data

Distributed Memory Weather

- decompose data to specific processors
 - assign a cube to each processor
 - maximize volume to surface ratio
 - minimizes communication/computation ratio
 - called a <block,block, block> distribution
- need to communicate {i,j,k}{+,-}{1,2} terms at boundaries
 - use send/receive to move the data
 - no need for barriers, send/receive operations provide sync
 - sends earlier in computation too hide communication time
- Advantages
 - easier to debug?
 - consider data locality explicitly with data decomposition
- Problems
 - harder to get the code running

Seismic Code

- Given echo data, compute under sea map
- Computation model
 - designed for a collection of workstations
 - uses variation of RPC model
 - workers are given an independent trace to compute
 - requires little communication
 - supports load balancing (1,000 traces is typical)

Performance

- max mfops = $O((F * nz * B^*)^{1/2})$
- F single processor MFLOPS
- nz linear dimension of input array
- B* effective communication bandwidth
 - $B^* = B/(1 + BL/w) \approx B/7$ for Ethernet (10msec lat., w=1400)
- real limit to performance was latency **not** bandwidth