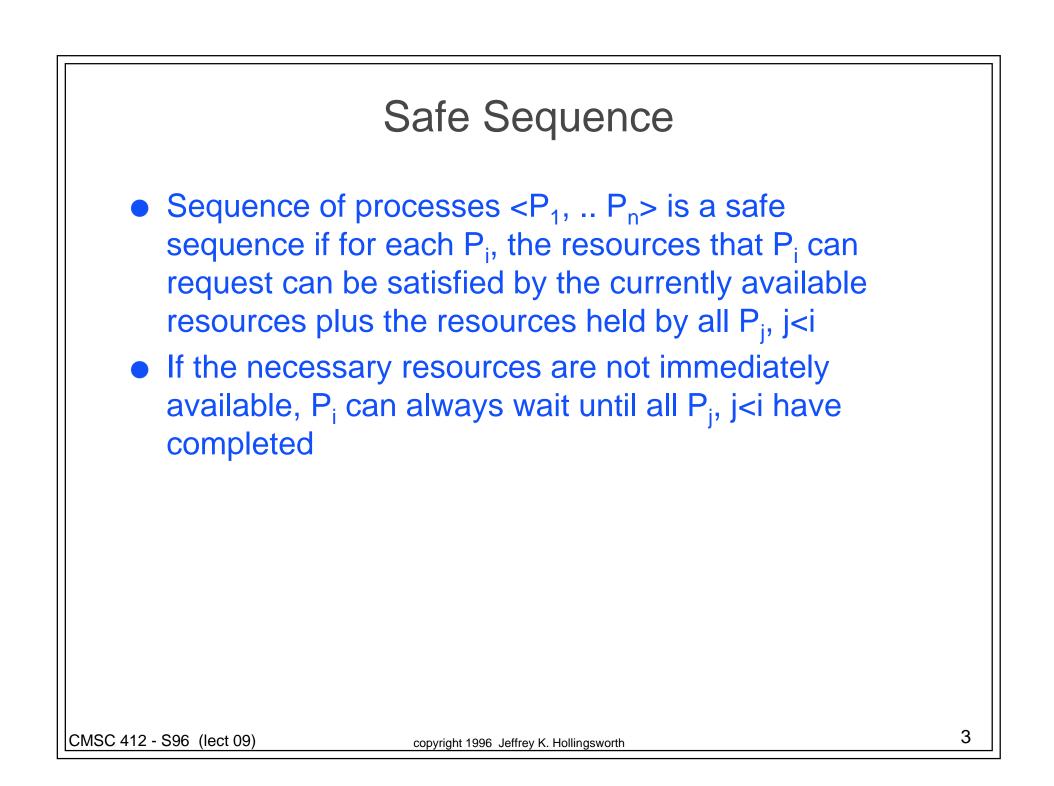
Announcements

- Reading 7 (7.5-7.9)
- Midterm #1 is March 5 in class
 - covers material through and including lecture 09
 - problems at the end of the chapters
 - synchronization problems
 - questions about the project
 - Suggestions for study
- Reader-writers example from last time
 - the Z semaphore appears not to be needed

Deadlock Avoidance

- Require additional information about how resources are to be requested - decide to approve or disapprove requests on the fly
- Assume that each process lets us know its maximum resource request
- Safe state:
 - system can allocate resources to each process (up to its maximum) in *some order* and still avoid a deadlock
 - A system is in a safe state if there exists a safe sequence



Banker's Algorithm

- Each process must declare the maximum number of instances of each resource type it may need
- Maximum cannot exceed resources available to system
- Variables: (n is the number of processes, m is the number of resource types)
 - Available vector of length m indicating the number of available resources of each type
 - Max n by m matrix defining the maximum demand of each process
 - Allocation n by m matrix defining number of resources of each type currently allocated to each process
 - Need: n by m matrix indicating remaining resource needs of each process

- Work is a vector of length m (resources)
- Finish is a vector of length n (processes)
- 1. Work = Available; Finish = false
- 2. Find an *i* such that Finish[i] = false and Need <= Work if no such i, go to 4
- 3. Work += Allocation_i; Finish[i] = true; goto step 2
- 4. If Finish[i] = true for all i, system is in a safe state

Note this requires m x n² steps

all elements

in the vector

are <=

	Banker's	C		
Ihree	resources: A, B	5, C (10, 5, 7 II	nstances eac	n)
Consid	ler the snapsho	ot of the syster	m at this time	Max - alloc
	Alloc	Max	Avail	Need
	ABC	ABC	ABC	ABC
P0	010	753	332	743
P1	200	322		122
P2	302	902		600
P3	211	222		011
P4	002	433		431

System is in a safe state, since the sequence <P1, P3, P4, P2, P0> satisfy the safety criteria.

CMSC 412 - S96 (lect 09)

Resource Request Algorithm

(1) If $Request_i \le Need_i$ then goto 3

- otherwise the process has exceeded its maximum claim
- (2) If Request_i <= Available then goto 3
 - otherwise process must wait since resources are not available
- (3) Check request by having the system pretend that it has allocated the resources by modifying the state as follows:
 - Available = Available Request_i
 - Allocation = Allocation + Request_i
 - Need_i = Need_i Request_i

• Find out if resulting resource allocation state <u>CMSC 412 - Sys (Sector)</u>, otherwise the request must wait.

Deadlock Detection

• Resource Allocation Graph

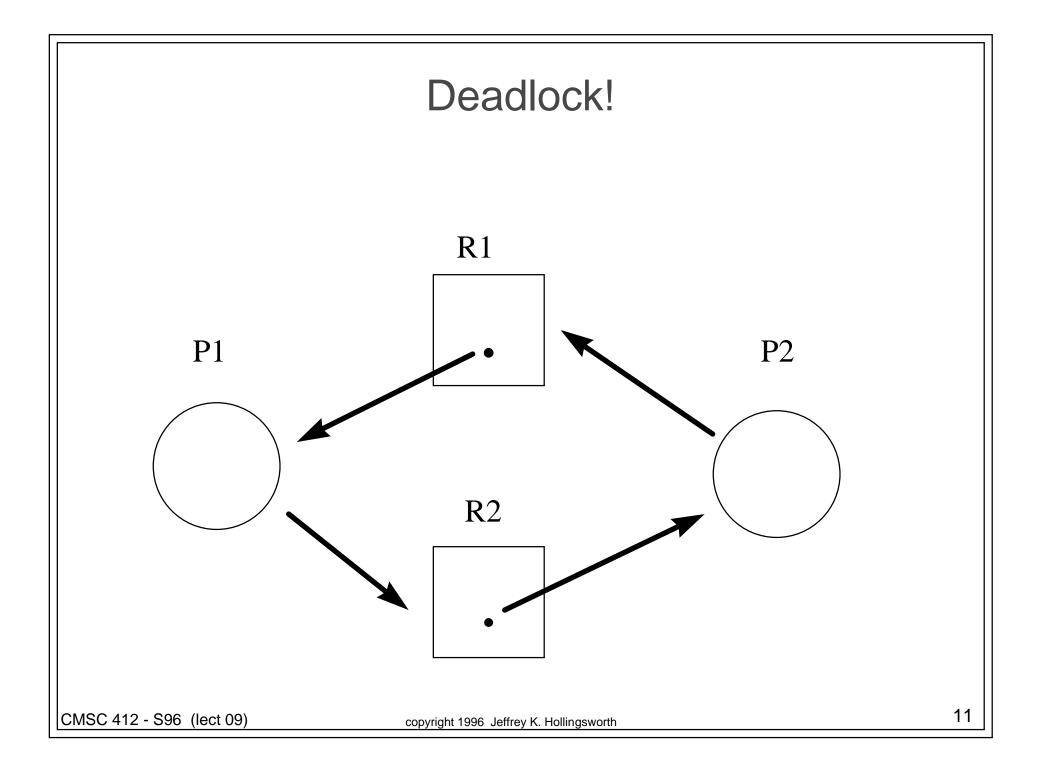
- Graph consists of vertices
 - type $P = \{P_1, ..., P_n\}$ represent processes
 - type R = {R₁,..,R_n} represent resources
- Directed edge from process P_i to resource type R_j signifies that a process i has requested resource type j
- request edge
- A directed edge from R_j to P_i indicates that resource R_j has been allocated to process P_i
- assignment edge

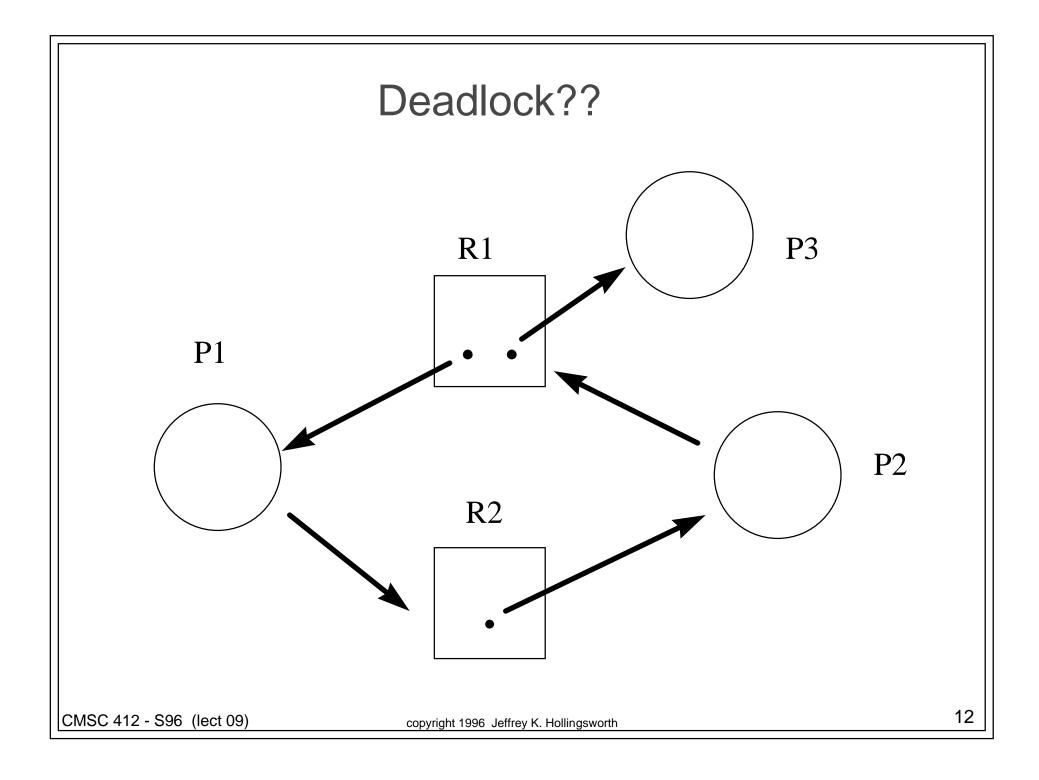
Deadlock Detection (cont.)

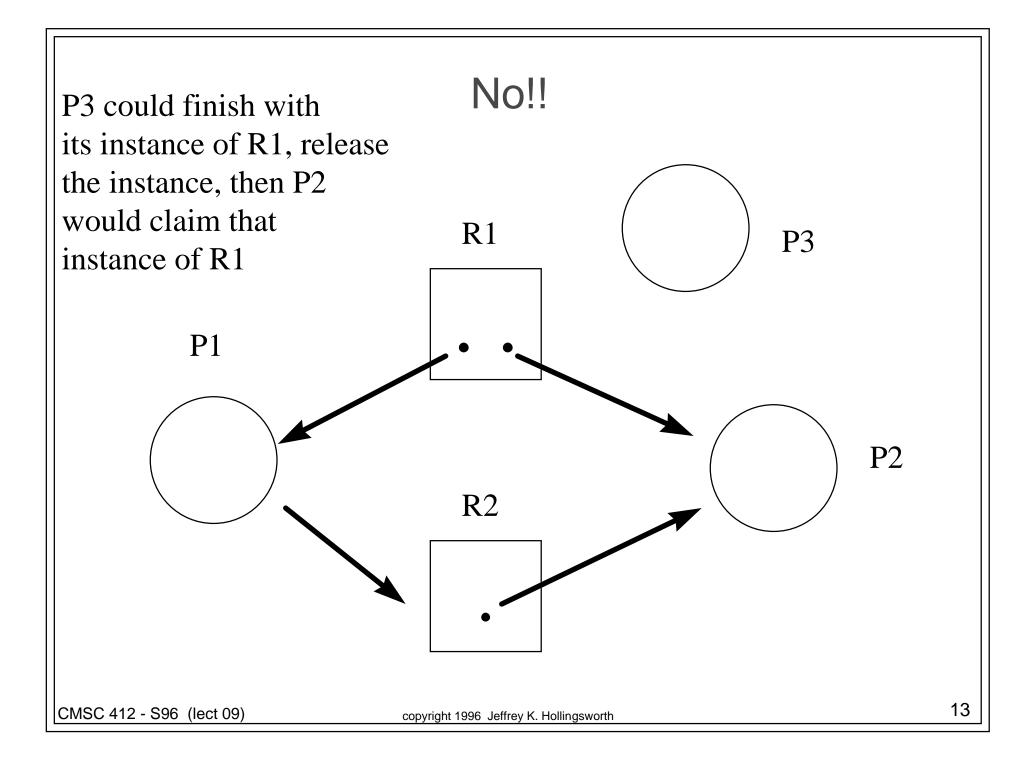
- Resource types may have more than one instance
- Each resource vertex represents a resource type.
- Each resource instance is of a unique resource type, each resource instance is represented by a "subvertex" associated with a resource vertex
 - (Silverschatz represents resource vertices by squares, resource instance "subvertices" by dots in the square.
 Process vertices are represented by circles)
- A request edge points to a resource vertex
- An assignment edge points from a resource "subvertex" to a process vertex

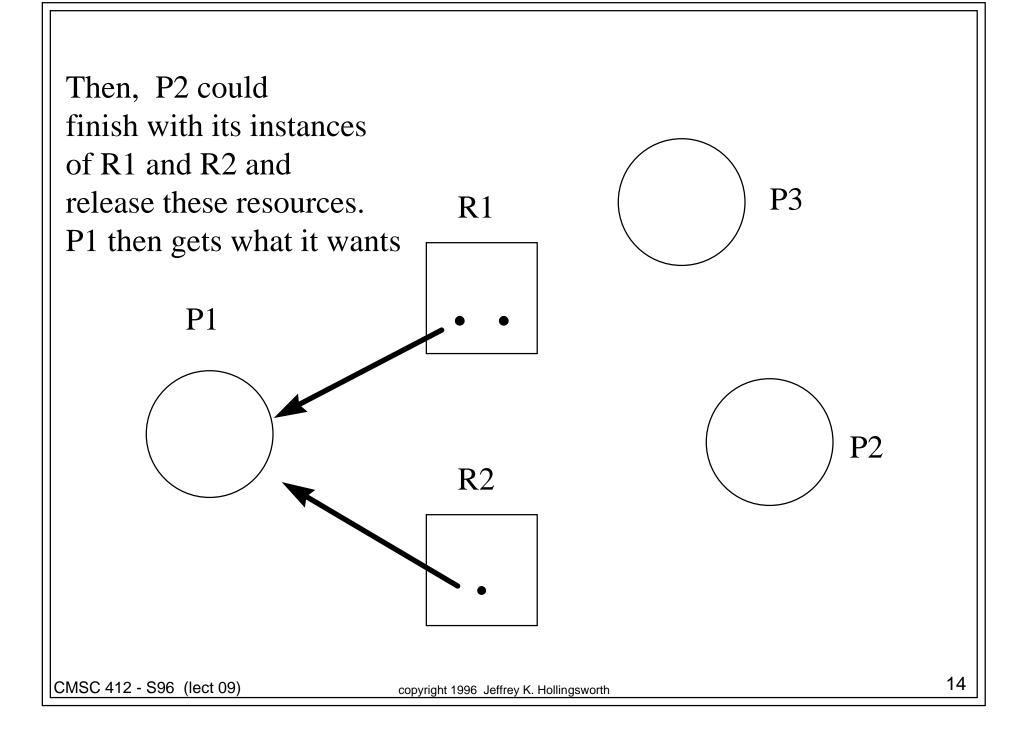
Resource Allocation Graph

- When a process P_i requests an instance of resource type R_j, a request edge is inserted into the resource allocation graph
- When the request can be fulfilled, the request edge is transformed into an assignment edge
- When the process is done using the resource, the assignment edge is deleted
- If the graph contains no cycles, no deadlock can exist









Detecting Deadlock

- Work is a vector of length m (resources)
- Finish is a vector of length n (processes)
- Allocation is an n x m matrix indicating the number of each resource type held by each process
- Request is an m x n matrix indicating the number of additional resources requested by each process
- 1. Work = Available;
 - if Allocation[i] != 0 Finish = false else Finish = true;
- 2. Find an *i* such that Finish[i] = false and Request_i <= Work if no such i, go to 4</p>
- 3. Work += Allocation ; Finish[i] = true; goto step 2
- 4. If Finish[i] = false for some i, system is in deadlock
 Note: this requires m x n² steps

CMSC 412 - S96 (lect 09)

Recovery from deadlock

- Must free up resources by some means
- Process termination
 - kill all deadlocked processes
 - select one process and kill it
 - must re-run deadlock detection algorithm again to see if it is freed.
- Resource Preemption
 - select a process, resource and de-allocate it
 - rollback the process
 - needs to be reset the process to a safe state
 - this requires additional state
 - starvation
 - what prevents a process from never finishing?