### Announcements

- Reading chapter 6 (6.7) and chapter 7 (7.1-7.4)
- Midterm #1 is March 5 in class
- Late Policy for programs
  - no late work will be accepted
  - illness and family emergency will be considered on a case by case basis

## Implementing Semaphores

#### declaration

```
type semaphore = record
      value: integer;
      L: list of process;
    end;
P(S): S.value = S.value -1
   if S.value <= 0 then {
       add this process to S.L
       block;
   };
V(S): S.value = S.value+1
   if S.value > 0 then {
       remove process P from S.L
       wakeup(P);
```

## **Readers/Writers Problem**

- Data area shared by processors
- Some processors read data, other processors can read or write data
  - Any number of readers my simultaneously read the data
  - Only one writer at a time may write
  - If a writer is writing to the file, no reader may read it
- Two of the possible approaches
  - readers have priority or writers have priority

## **Readers have Priority**

```
reader()
       repeat
           P(x);
                readcount = readcount + 1;
                if readcount = 1 then P (wsem);
           V(x);
           READUNIT;
           P(x);
                readcount = readcount - 1;
                if readcount = 0 V(wsem);
           V(x);
       forever
      };
      writer()
          repeat
              P(wsem);
              WRITEUNIT;
              V(wsem)
          forever
CMSC 412 - S96 (lect 08)
                                     copyright 1996 Jeffrey K. Hollingsworth
```

Comments on Reader Priority

- semaphores x,wsem are initialized to 1
- note that readers have priority a writer can gain access to the data only if there are no readers (i.e. when readcount is zero, signal(wsem) executes)
- possibility of starvation writers may never gain access to data

## Writers Have Priority

#### reader

#### writer

```
repeat
 repeat
                                                       P(y);
      P(z);
                                                            writecount++:
           P(rsem);
                                                            if writecount == 1 then
           P(x);
                readcount++;
                                                       V(y);
                if (readcount == 1) then
                                                       P(wsem);
                               P(wsem);
                                                       writeunit
           V(x);
                                                       V(wsem);
           V(rsem);
                                                       P(y);
      V(z);
                                                            writecount--;
      readunit;
                                                            if (writecount == 0) then
      P(x);
           readcount- -;
                                                       V(y);
           if readcount == 0 then
                                                  forever;
                            V (wsem)
      V(x)
 forever
CMSC 412 - S96 (lect 08)
                                  copyright 1996 Jeffrey K. Hollingsworth
```

6

P(rsem);

V(rsem);

# Notes on readers/writers with writers getting priority

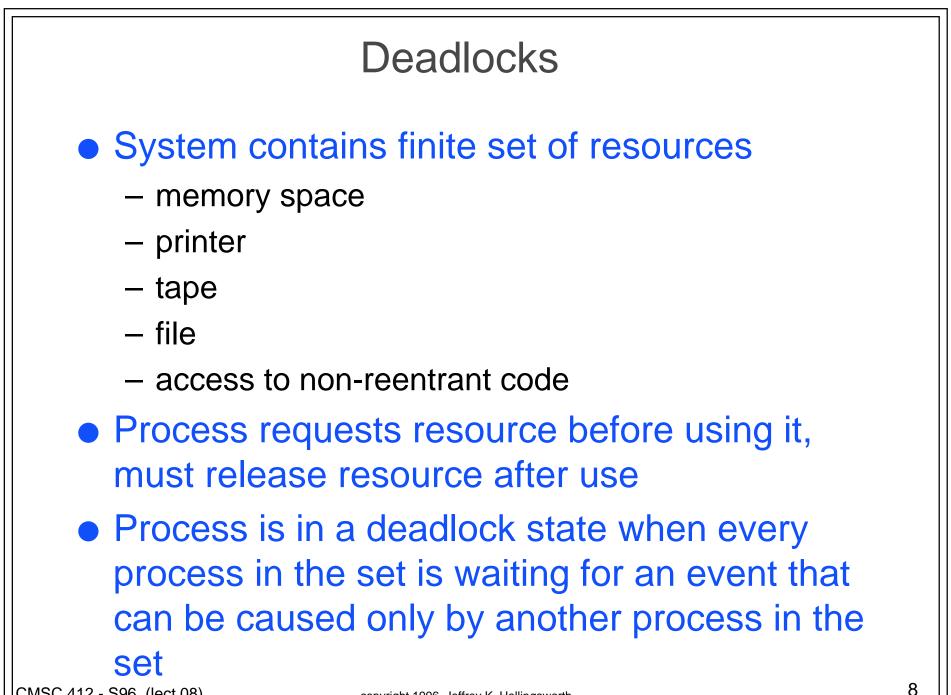
#### Semaphores x,y,z,wsem,rsem are initialized to 1

P(z); P(rsem); P(x); readcount++; if (readcount==1) then P(wsem); V(x); V(rsem); V(z);

readers queue up on semaphore z; this way only a single reader queues on rsem. When a writer signals rsem, only a single reader is allowed through

CMSC 412 - S96 (lect 08)

7



CMSC 412 - S96 (lect 08)

## Formal Deadlocks

#### • 4 *necessary* deadlock conditions:

- Mutual exclusion at least one resource must be held in a non-sharable mode, that is, only a single process at a time can use the resource. If another process requests that resource, the requesting process must be delayed until the resource is released
- Hold and wait There must exist a process that is holding at least one resource and is waiting to acquire additional resources that are currently held by other processors

## Formal Deadlocks

- No preemption: Resources cannot be preempted; a resource can be released only voluntarily by the process holding it, after that process has completed its task
- Circular wait: There must exist a set {P0,...,Pn} of waiting processes such that P0 is waiting for a resource that is held by P1, P1 is waiting for a resource held by P2 etc.
- Note that these are not sufficient conditions

**Deadlock Prevention** 

- Ensure that one (or more) of the necessary conditions for deadlock do not hold
- Hold and wait
  - guarantee that when a process requests a resource, it does not hold any other resources
  - Each process could be allocated all needed resources before beginning execution
  - Alternately, process might only be allowed to wait for a new resource when it is not currently holding any resource

## **Deadlock Prevention**

#### Mutual exclusion

 Sharable resources do not require mutually exclusive access and cannot be involved in a deadlock.

#### Circular wait

 Impose a total ordering on all resource types and make sure that each process claims all resources in increasing order of resource type enumeration

#### No Premption

 virutalize resources and permit them to be prempted. For example, CPU can be prempted.

## Deadlock Avoidance

- Require additional information about how resources are to be requested - decide to approve or disapprove requests on the fly
- Assume that each process lets us know its maximum resource request
- Safe state:
  - system can allocate resources to each process (up to its maximum) in *some order* and still avoid a deadlock
  - A system is in a safe state if there exists a safe sequence

