

Announcements

- Reading chapter 6 (6.4 and 6.5)
- Midterm #1 is March 5 in class
- Late Policy for programs
 - no late work will be accepted
 - illness and family emergency will be considered on a case by case basis

Critical Section (cont)

- May assume that some instructions are atomic
 - typically load, store, and test word instructions
- Algorithm #1 for two processes
 - use a shared variable that is either 0 or 1
 - when $P_k = k$ a process may enter the region

```
repeat
  (while turn != 0);
  // critical section
  turn = 1;
  // non-critical section
until false;
```

```
repeat
  (while turn != 1);
  // critical section
  turn = 0;
  // non-critical section
until false;
```

- this fails the progress requirement since process 0 not being in the critical section stops process 1.

Critical Section (Algorithm 2)

- Keep an array of flags indicating which processes want to enter the section

Both processes
could be here at
the same time



```
bool flag[2];

repeat
  flag[i] = true;
  while (flag[j]);

  // critical section

  flag[i] = false;

  // non-critical section
until false;
```

- This does **NOT** work either!
 - possible to have both flags set to 1

Critical Section (Algorithm 3)

- Combine 1 & 2

```
bool flag[2];
int turn;

repeat
  flag[i] = true;
  turn = j;
  while (flag[j]&& turn ==j);

  // critical section

  flag[i] = false;

  // non-critical section
until false;
```

- This one does work! Why?

Critical Section (many processes)

- What if we have several processes?
- One option is the Bakery algorithm

```
bool choosing[n];  
integer number[n];
```

```
choosing[i] = true;  
number[i] = max(number[0],..number[n-1])+1;  
choosing[i] = false;  
for j = 0 to n-1  
    while choosing[j];  
        while number[j] != 0 and ((number[j], j) < number[i],i);  
end  
// critical section  
number[i] = 0
```

Bakery Algorithm - explained

- When a process wants to enter critical section, it takes a number
 - however, assigning a unique number to each process is not possible
 - it requires a critical section!
 - however, to break ties we can use the lowest numbered process id
- Each process waits until its number is the highest one
 - it can then enter the critical section
- provides fairness since each process is served in the order they requested the critical section

Synchronization Hardware

- If it's hard to do synchronization in software, why not do it in hardware?
- Disable Interrupts
 - works, but is not a great idea since important events may be lost.
 - doesn't generalize to multi-processors
- test-and-set instruction
 - one atomic operation
 - executes without being interrupted
 - operates on one bit of memory
 - returns the previous value and sets the bit to one
- swap instruction
 - one atomic operation
 - swap(a,b) puts the old value of b into a and of a into b

Using Test and Test for Mutual Exclusion

repeat

```
while test-and-set(lock); ← Note: no priority based on wait time
// critical section
lock = false;
// non-critical section
```

until false;

● bounded waiting time version

repeat

```
waiting[i] = true;
key = true;
while waiting[i] and key ← wait until released or no one busy
    key = test-and-set(lock);
waiting[i] = false;
// critical section
j = (i + 1) % n
while (j != i) and (!waiting[j]) ← look for a waiting process
    j = (j + 1) % n;
if (j == i)
    lock = false; ← no process waiting
else
    waiting[j] = false; ← release process j
// non-critical section
```

until false;

Semaphores

- getting critical section problem correct is difficult
 - harder to generalize to other synchronization problems
 - Alternative is semaphores
- semaphores
 - integer variable
 - only access is through atomic operations
- P (or wait)
 - while $s \leq 0$;
 - $s = s - 1$;
- V (or signal)
 - $s = s + 1$

Using Semaphores

- critical section

```
repeat
    P(mutex);
    // critical section
    V(mutex);
    // non-critical section
until false;
```

- Require that Process 2 begin statement S2 after Process 1 has completed statement S1:

Process 2

S1

V(synch)

Process 1

P(synch)

S2

Implementing semaphores

- Busy waiting implementations
- Instead of busy waiting, process can block itself
 - place process into queue associated with semaphore
 - state of process switched to waiting state
 - transfer control to CPU scheduler
 - process gets restarted when some other process executes a signal operations