Announcements

- Midterm is Thursday (3/6/14)
 - Covers up through definition of deadlock (last Th lecture)
 - Summary of reading assignments on web
- Project #2 is due today at 5:00 PM
- Project #1grades are now posted in grades
 - Re-grade request deadline is 3/11/14

Detecting Deadlock Algorithm

• Variables:

n is the number of processes

m is the number of resource types

- Available vector of length m indicating the number of available resources of each type
- Work vector of length m indicating the number of currently available resources of each type
- Allocation n by m matrix defining number of resources of each type currently allocated to each process
- Request is an m x n matrix indicating the number of additional resources requested by each process
- Finish is a vector of length n (processes) indicating if we are finished checking that process

Detecting Deadlock

```
1. Work = Available;
```

```
foreach i in n
```

if any of Allocation[i,*] != 0 Finish[i] = false

else Finish[i] = true;

2. Find an *i* such that Finish[i] = false and Request[I,*] <= Work[i,*] if no such i, go to 4</p>

```
3. Work[i,*] += Allocation[i,*];
```

```
Finish[i] = true;
```

```
goto step 2
```

4. If Finish[i] = false for some i, system is in deadlock

Note: this requires m x n² steps

Recovery from deadlock

- Must free up resources by some means
- Process termination
 - kill all deadlocked processes
 - select one process and kill it
 - must re-run deadlock detection algorithm again to see if it is freed.
- Resource Preemption
 - select a process, resource and de-allocate it
 - rollback the process
 - needs to be reset the process to a safe state
 - this requires additional state
 - starvation
 - what prevents a process from never finishing?

Deadlock Prevention

Ensure that:

one or more of the necessary conditions for deadlock do not hold

Hold and wait

- guarantee that when a process requests a resource, it does not hold any other resources
- Each process could be allocated all needed resources before beginning execution
- Alternately, process might only be allowed to wait for a new resource when it is not currently holding any resource

Deadlock Prevention

• Mutual exclusion

 Sharable resources do not require mutually exclusive access and cannot be involved in a deadlock.

Circular wait

 Impose a total ordering on all resource types and make sure that each process claims all resources in increasing order of resource type enumeration

No Premption

 virutalize resources and permit them to be prempted. For example, CPU can be prempted.

Deadlock Avoidance

- Require additional information about how resources are to be requested - decide to approve or disapprove requests on the fly
- Assume that each process lets us know its maximum resource request
- Safe state:
 - system can allocate resources to each process (up to its maximum) in some order and still avoid a deadlock
 - A system is in a safe state if there exists a safe sequence

Safe Sequence • Sequence of processes $\langle P_1, ..., P_n \rangle$ is a safe sequence if for each P_i, the resources that P_i can request can be satisfied by the currently available resources plus the resources held by all P_i, j<i • If the necessary resources are not immediately available, P_i can always wait until all P_i, j<i have completed

Banker's Algorithm

- Each process must declare the maximum number of instances of each resource type it may need
- Maximum can't exceed resources available to system
- Variables:
 - n is the number of processes
 - m is the number of resource types
 - Available vector of length m indicating the number of available resources of each type
 - Max n by m matrix defining the maximum demand of each process
 - Allocation n by m matrix defining number of resources of each type currently allocated to each process
 - Need: n by m matrix indicating remaining resource needs of each process
 - Work: a vector of length m (resources)
 - Finish: a vector of length n (processes)

Safe State Predicate

Work = Available; Finish[*] = false all elements in the vector are <= and Need[i,*] <= Vork[i,*] if no such i, go to 4
Work[i,*] += Allocation[i,*]; Finish[i] = true; goto step 2
If Finish[i] = true for all i, system is in a safe state

Note this requires m x n² steps

	Safe State			
Three	resources: A, B	, C (10, 5, 7 ir	nstances eacl	h)
Consic	ler the snapsho	t of the syster	n at this time	Max - alloc
	Alloc	Max	Avail	Need
	ABC	ABC	ABC	ABC
P0	010	753	332	743
P1	200	322		122
P2	302	902		600
P3	211	222		011
P4	002	433		431

System is in a safe state, since the sequence <P1, P3, P4, P2, P0> satisfy the safety criteria.

CMSC 412 – S14 (lect 10)

Resource Request Algorithm

- (1) If $Request_i \le Need_i$ then goto 3
 - otherwise the process has exceeded its maximum claim
- (2) If Request_i \leq Available then goto 3
 - otherwise process must wait since resources are not available
- (3) Check request by having the system pretend that it has allocated the resources by modifying the state as follows:
 - Available = Available Request_i
 - Allocation = Allocation + Request_i
 - Need_i = Need_i Request_i
- Find out if resulting resource allocation state is safe, otherwise the request must wait.