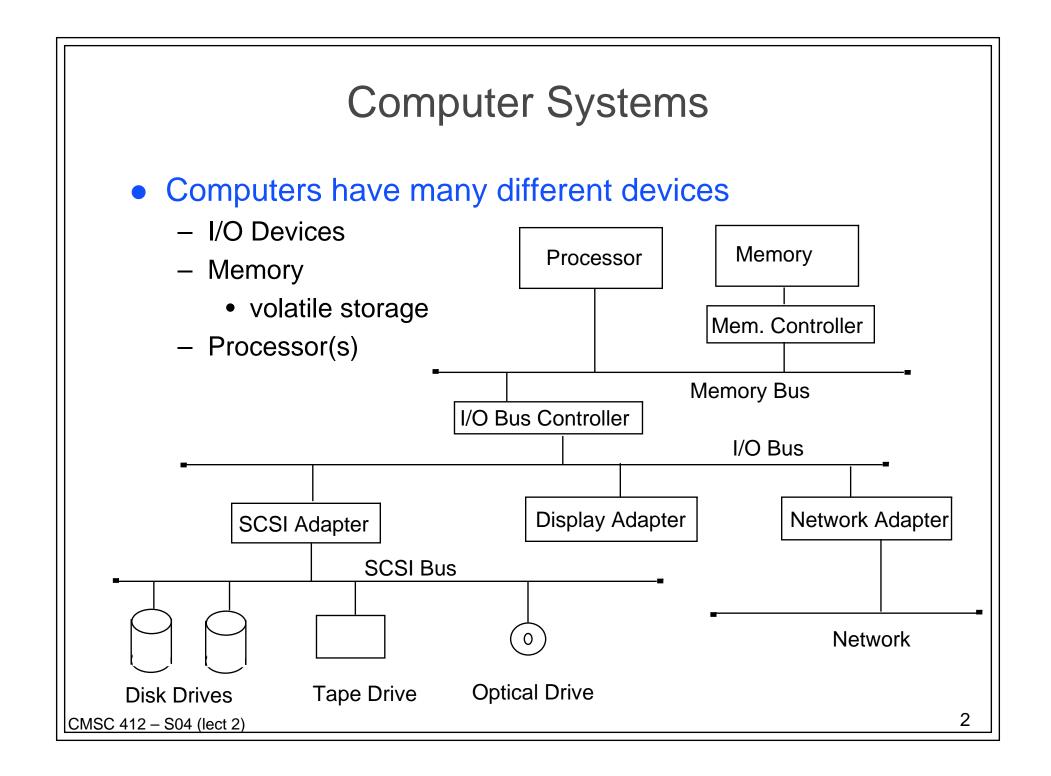
### Announcements

#### • Program #0

- its due Thursday

### • Reading

- Chapter 2
- Chapter 3 (for Tuesday)



## I/O Systems

#### Many different types of devices

- disks
- networks
- displays
- mouse
- keyboard
- tapes
- Each have a different expectation for performance
  - bandwidth
    - rate at which data can be moved
  - latency
    - time from request to first data back

## Different Requirements lead to Multiple Buses

- Processor Bus (on chip)
  - Many Gigabytes/sec
- Memory Bus (on processor board)
  - ~1-2 Gigabyte per second
- I/O Bus (PCI, MCA)
  - ~100 megabytes per second
  - buses are more complex than we saw in class
    - show PCI spec.
- Device Bus (SCSI, USB)
  - tens of megabytes per second

### Issues In Busses

#### • Performance

- increase the data bus width
- have separate address and data busses
- block transfers
  - move multiple words in a single request
- Who controls the bus?
  - one or more bus masters
    - a bus master is a device that can initiate a bus request
  - need to arbitrate who is the bus master
    - assign priority to different devices
    - use a protocol to select the highest priority item
      - daisy chained
      - central control

# Disks

#### • Several types:

- Hard Disks rigid surface with magnetic coating
- Floppy disks flexible surface with magnetic coating
- Optical (CDs and DVDs) read only, write once, multi-write

### • Hard Disk Drives:

- collection of platters
- platters contain concentric rings called tracks
- tracks are divided into fixed sized units called sectors
- a cylinder is a collection of all tracks equal distant from the center of disk
- Current Performance:
  - capacity: megabytes to hundreds of gigabytes
  - throughput: sustained < 10 megabytes/sec
  - latency: mili-seconds

## I/O Interfaces

- Need to adapt Devices to CPU speeds
- Moving the data
  - Programmed I/O
    - Special instructions for I/O
  - Mapped I/O
    - looks like memory only slower
  - DMA (direct memory access)
    - device controller can write to memory
    - processor is not required to be involved
    - can grab bus bandwidth which can slow the processor down

## I/O Interrupts

#### • Interrupt defined

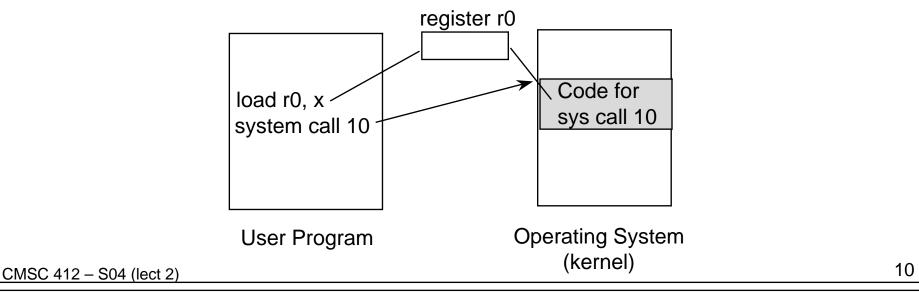
- indication of an event
- can be caused by hardware devices
  - indicates data present or hardware free
- can be caused by software
  - system call (or trap)
- CPU stops what it is doing and executes a handler function
  - saves state about what was happening
  - returns where it left off when the interrupt is done
- Need to know what device interrupted
  - could ask each device (slow!)
  - instead use an interrupt vector
    - array of pointers to functions to handle a specific interrupt

### Hardware Protection

- Need to protect programs from each other
- Processor has modes
  - user mode and supervisor (monitor, privileged)
  - operations permitted in user mode are a subset of supervisor mode
- Memory Protection
  - control access to memory
  - only part of the memory is available
    - can be done with base/bound registers
- I/O Protection
  - I/O devices can only be accessed in supervisor mode
- Processor Protection
  - Periodic timer returns processor to supervisor mode

### System Calls

- Provide the interface between application programs and the kernel
- Are like procedure calls
  - take parameters
  - calling routine waits for response
- Permit application programs to access protected resources



### System Call Mechanism

- Use numbers to indicate what call is made
- Parameters are passed in registers or on the stack
- Why do we use indirection of system call numbers rather than directly calling a kernel subroutine?
  - provides protection since the only routines available are those that are export
  - permits changing the size and location of system call implementations without having to re-link application programs

## Types of System Calls

#### • File Related

- open, create
- read, write
- close, delete
- get or set file attributes
- Information
  - get time
  - set system data (OS parameters)
  - get process information (id, time used)
- Communication
  - establish a connection
  - send, receive messages
  - terminate a connection
- Process control
  - create/terminate a process (including self)

## I/O Operations

#### Synchronous I/O

- program traps into the OS
- request is made to the device
- processor waits for the device
- request is completed
- processor returns to application process
- Asynchronous I/O
  - request is made to the device
  - processor records request
  - processor continues program
    - could be a different one
  - request is completed and device interrupts
  - processor records that request is done
  - program execution continues