## Some bounds and approaches useful for (randomized) algorithms

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## 1 A basic review of continuous distributions

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Discrete
\(X=x\)
\(\operatorname{Pr}[X=x]\)
\(X \in[x, x+d x)\)
\(\operatorname{Pr}[X \in[x, x+d x)]=f(x) d x\), where \(f(x)\) is the "density function" of \(X\)
\(\operatorname{Pr}[a \leq X \leq b] \quad \int_{a}^{b} f(x) d x\)
\(E[X]=\sum_{x} x \cdot \operatorname{Pr}[X=x] \quad E[X]=\int_{-\infty}^{\infty} x f(x) d x\)
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If follows that if $X$ is always between $l, u$, then $f(x) \geq 0$ and $\int_{l}^{u} f(x) d x=1$
Note that $\operatorname{Pr}[X=x]$ is $f(x) d x=0 \cdot f(x)$. Therefore the probability of any variable being exactly some value is 0 . From this it follows that the probability that two continuous random variables have the same value is 0 .

One important continuous distribution is the normal or Gaussian distribution. If the mean is $\mu$ and standard deviation is $\sigma$, then

$$
f(x)=\frac{1}{\sqrt{2 \pi} \sigma} e^{\frac{-(x-\mu)^{2}}{2 \sigma^{2}}}
$$

here.
Another frequently used distribution is the uniform distribution over a bounded range, such as $[0,1]$. (If this range is $[a, b]$, then the density function $f(x)$ is the constant $1 /(b-a)$.) The idealized version allows us to pick a real number uniformly at random from a bounded range. In practice we approximate this by a discretization of the space.

## 2 Convexity and some of its consequences

Recall that a function $f$ is convex in the interval $[a, b]$ if for any $[u, v] \subseteq[a, b]$, the graph of $f$ lies below the line segment that joins the points $(u, f(u))$ and $(v, f(v))$ : that is,

$$
\forall(u, v) \text { such that } a \leq u \leq v \leq b, \forall p \in[0,1], \quad f(u p+v(1-p)) \leq p \cdot f(u)+(1-p) \cdot f(v)
$$

And, $f$ is called concave in $[a, b]$ if the final inequality gets reversed in direction. In case the second derivative $f^{\prime \prime}$ exists for $x \in[a, b]$, then $f$ can be shown to be convex in $[a, b]$ iff $f^{\prime \prime}(x) \geq 0$, and concave in $[a, b]$ iff $f^{\prime \prime}(x) \leq 0$. Using this, or pictorially, one can verify that:

- $f(x)=x^{2 k}$ is convex over the entire real line, for all positive integers $k$;
- $f(x)=e^{a x}$ is convex over the entire real line, for all reals $a$;
- $f(x)=\ln x$ and $f(x)=\sqrt{x}$ are concave for the entire range $(0, \infty)$;
- $f(x)=x^{3}, f(x)=x^{5}$ etc. are concave for $x<0$, and convex for $x>0$;
- a linear function is both concave and convex.

The following fact is often useful. Suppose a function $f$ is convex in some domain $D=[a, b]$ and $x_{1}, \ldots, x_{n}$ are variables such that $x_{i} \in D$ and $\sum x_{i}=c$, then $\sum_{i} f\left(x_{i}\right)$ is minimized when all $x_{i}$ are the same (i.e., $c / n$ ). Therefore,

$$
\begin{equation*}
\sum_{i} f\left(x_{i}\right) \geq n \cdot f(c / n) \tag{1}
\end{equation*}
$$

Conversely, to maximize $\sum_{i} f\left(x_{i}\right)$ subject to the given constraints, we must push the $x_{i}$ 's as much as possible to their "extreme values" (the definition of this varies from one context to another, but the intuitive meaning remains: "do the opposite of pushing the $x_{i}$ toward each other".) As can be expected, the situation is exactly reversed for concave functions $f$ : make the $x_{i}$ equal if we aim to maximize $\sum_{i} f\left(x_{i}\right)$, and do a sort of opposite if the goal is to minimize $\sum_{i} f\left(x_{i}\right)$
Jensen's Inequality: This is an easy consequence of convexity, and says the following. If $f$ is a convex function in the interval $[a, b]$, then for any random variable $X$ taking values in $[a, b]$,

$$
\mathrm{E}[f(X)] \geq f(\mathrm{E}[X])
$$

and, $f$ is a concave function in the interval $[a, b]$, then for any random variable $X$ taking values in $[a, b]$,

$$
\mathrm{E}[f(X)] \leq f(\mathrm{E}[X])
$$

We finally note that all the above discussion was focused on uni-variate functions $f$, but quite a bit of the above also extends to real-valued multi-variate functions $f\left(x_{1}, x_{2}, \ldots, x_{n}\right)$.

## 3 Additional inequalities and some information theory

We begin by examining some additional useful bounds.

- $1+x \leq e^{x} \forall x$; also, $\left(1-\frac{1}{n}\right)^{n-1} \geq \frac{1}{e}$ for $n \geq 2$. In particular, the bound $(1-x)^{t} \leq e^{-t x}$ for $x \leq 1$ and $t>0$ that follows from the first inequality here, is used routinely.
- Stirling's approximation: $F(n)=\sqrt{2 \pi n}\left(\frac{n}{e}\right)^{n}$, and Robbins' formula for the error of the approximation: $e^{1 /(12 n+1)} \leq \frac{n!}{F(n)} \leq e^{1 /(12 n)}$. Note that both $e^{1 /(12 n+1)}$ and $e^{1 /(12 n)}$ are very close to 1 even for moderately large $n$; e.g., $n \geq 5$. Thus, Stirling's formula is a very good approximation for $n$ ! if $n \geq 5$, say.
- $\left(\frac{n}{r}\right)^{r} \leq\binom{ n}{r} \leq\left(\frac{n e}{r}\right)^{r}$; in fact, $\sum_{i=0}^{r}\binom{n}{i} \leq\left(\frac{n e}{r}\right)^{r}$.
- An alternative bound is as follows. Let $H(\alpha)=-\alpha \log _{2} \alpha-(1-\alpha) \log _{2}(1-\alpha)$ be the "binary entropy function" for $0 \leq \alpha \leq 1$; if $\alpha$ is 0 or 1 , we define $H(\alpha)=0$. Then, for $\alpha \leq \frac{1}{2}$,

$$
\begin{equation*}
\sum_{i=0}^{\alpha n}\binom{n}{i} \leq 2^{n H(\alpha)} \tag{2}
\end{equation*}
$$

This last statement, (2), is of particular interest, so we introduce basic information theory next to look at it more closely.

### 3.1 Basic Information Theory

We first consider the following definitions and observations from information theory. Let $X$ be a random variable which takes on the value $a_{i}$ with probability $p_{i}$ for $i=1 \ldots n$. We loosely define the entropy of $X$ as the "amount of randomness in $X$ ", given by the function:

$$
H(X)=-\sum_{i=1, p_{i} \neq 0}^{n} p_{i} \log _{2} p_{i}
$$

From this we have the following facts:

- $H(X) \geq 0$, and $H(X)=0$ iff $X$ is deterministic (one of the $p_{i}$ equals 1 ).
- For $n$-valued $X, H(X)$ is maximized when $X$ uses the uniform distribution, that is,

$$
p_{1}=p_{2}=\ldots=p_{n}=\frac{1}{n} ; \text { in this case, } H(X)=-\log _{2}\left(\frac{1}{n}\right)=\log _{2} n
$$

In particular, $H(X) \leq \log _{2} n$; we will see this in the proof of Claim 1 .

- For joint distributions, $H\left(X_{1}, X_{2}, \ldots, X_{m}\right) \leq \sum_{i=1}^{m} H\left(X_{i}\right)$.

We now consider the following example, which will be useful in proving (2).
Example: $X=\left\{\begin{array}{l}1 \text { with probability } p \\ 0 \text { with probability } 1-p\end{array}\right.$
From this we have that $H(X)=-p \log _{2} p-(1-p) \log _{2}(1-p)$, which we will call $H(p)$ for simplicity (though it is an abuse of notation since $p$ is a value while $X$ is a random variable). It is easy to see that $H(p)$ is a concave function either by viewing the graph of the function or by taking its second derivative. With this, we can prove (2), which we state next in more generality.

Claim 1 Let $\alpha \leq \frac{1}{2}$, and let $S$ be any set of n-bit strings such that the average number of 1 's in a string in $S$ is $\leq \alpha n$. (That is, the average taken over all strings $s \in S$ of the number of ones in $s$, is at most $\alpha n$.) Then $|S| \leq 2^{n H(\alpha)}$.
Proof Let $X=\left(X_{1}, X_{2}, \ldots, X_{n}\right)$ chosen uniformly at random from $S$. Then $H(X)=\log _{2}|S|$. In fact,

$$
\log _{2}|S|=H(X) \leq \sum_{i=1}^{n} H\left(X_{i}\right)
$$

Suppose $\forall i, X_{i}=\left\{\begin{array}{l}1 \text { with probability } p_{i} \\ 0 \text { with probability } 1-p_{i}\end{array}\right.$; then $H\left(X_{i}\right)=H\left(p_{i}\right)$ as in the example.
Thus $\sum_{i=1}^{n} H\left(X_{i}\right)=\sum_{i=1}^{n} H\left(p_{i}\right)$.
Now notice that we know something about the sum of these $p_{i}$ 's, in particular:

$$
\sum_{i=1}^{n} p_{i}=\sum_{i=1}^{n} E\left[X_{i}\right]=E\left[\sum_{i=1}^{n} X_{i}\right] \leq \alpha n
$$

We now use the fact that if we have a sum of concave functions which is equal to a fixed value, that sum is maximized when the functions are equal. Therefore, if $\sum_{i=1}^{n} p_{i}=t$,

$$
\sum_{i=1}^{n} H\left(p_{i}\right) \leq n \cdot H\left(\frac{t}{n}\right) \leq n H(\alpha) \text { since } \alpha \leq \frac{1}{2}
$$

Therefore $|S| \leq 2^{n H(\alpha)}$.

