SORTING TECHNIQUES

Hanan Samet

Computer Science Department and Center for Automation Research and Institute for Advanced Computer Studies University of Maryland College Park, Maryland 20742 e-mail: hjs@umiacs.umd.edu

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ISSUES

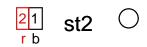
- 1. Nature of storage media
 - fast memory
 - secondary storage
- 2. Random versus sequential access of the data
- 3. Space
 - can we use space in excess of the space occupied by the data?
- 4. Stability
 - is the relative order of duplicate occurrences of a data value preserved?
 - useful as adds a dimension of priority (e.g., time stamps in a scheduling application) for free

Find the smallest element and output it
 113 400 818 612 411

1 b

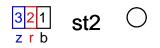
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st2



• Find the smallest element and output it

113 400 818 612 411 400 818 612 411 113 400 113 400 113 400 113 400 113 400



• Find the smallest element and output it

113 400 818 612 411 400 818 612 411 818 612 411 113 400 113 400 411 113 400 411 113 400 411



• Find the smallest element and output it



• Find the smallest element and output it

```
113 400 818 612 411
400 818 612 411
818 612 411
818 612
818
818
400 411
113 400
113 400 411
113 400 411
113 400 411 612
113 400 411 612 818
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654321	st2	\bigcirc
bvgzrb	•	

• Find the smallest element and output it

113	400	818	612	411	~`					
	400	818	612	411		113				
		818	612	411		113	400			
		818	612			113	400	411		
		818				113	400 400	411	612	
						113	400	411	612	818

- $O(n^2)$ time as always $n \cdot (n-1)$ comparisons
- Needs extra space for output
- In-place variant is not stable

• Ex:	1	2	3	4	5	6	7	8
	113	400 ₁	818	4002	411	311	412	420

Step 1 causes no change as 113 is the smallest element

Step 2 causes 311 in position 6 to be exchanged with 400 in position 2 resulting in the first instance of 400 becoming the second instance

1	2	3	4	5	6	7	8
113	311	818	4002	411	400 ₁	412	420

- In-place variant can be made stable:
 - 1. use linked lists
 - only $n \cdot (n-1)/2$ comparisons
 - 2. exchange adjacent elements

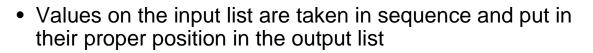
BUBBLE SORT

- Smaller values filter their way to the start of the list while the larger values filter their way to the end of the list
- Data is moved one position at a time and hence method is stable
- In-place

Initially:	113	400	818	612	411
First pass:	113- 113 113 113 113 113	- 400 400- 400 400 400	818 -818 818 <i>←</i> 612 612	612 612 → 612 818← 411	411 411 411 →411 818*
Second pass:	113- 113 113 113 113		612 −612 612 <i>←</i> 411	411 411 + 411 612*	818* 818* 818* 818* 818*

- * denotes final position
- denotes a key comparison
- ↔ denotes a key comparison and a need to swap
- Procedure starts with the values at the right end of the input list and works its way to the left in the sense that larger values are placed in their proper position before (timewise) the smaller value
- $O(n^2)$ comparison and exchange operations





- Previously moved values may have to be moved again
- · Makes only one pass on the input list at cost of move operations

. 113 400 818 612 411 <u>113</u>

1 b

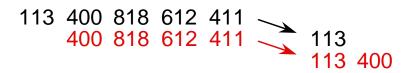
st4

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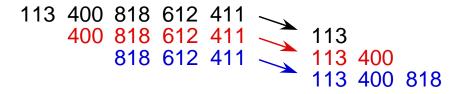
- Values on the input list are taken in sequence and put in their proper position in the output list
- Previously moved values may have to be moved again
- Makes only one pass on the input list at cost of move operations







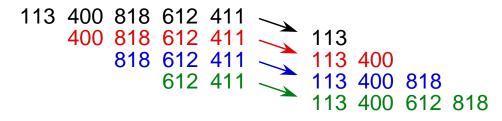
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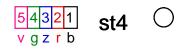




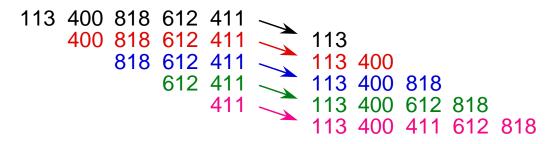
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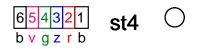
INSERTION SORT



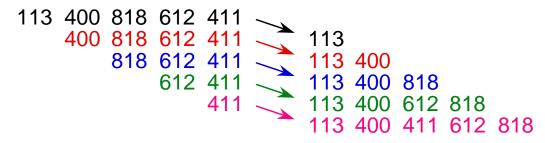
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INSERTION SORT



- Values on the input list are taken in sequence and put in their proper position in the output list
- Previously moved values may have to be moved again
- Makes only one pass on the input list at cost of move operations



- O(n²) but almost always smaller number of operations than selection sort
- Needs extra space for output
- Stable
- In-place variant exists and can also be made stable

MECHANICS OF INSERTION

- Assume inserting *x*, the *i*th element
- Must search for position to make the insertion
- Two methods:
 - 1. search in increasing order
 - Ex: insert 411 in [113 400 612 818]
 - 2. search in decreasing order
 - Ex: insert 411 in [113 400 612 818]

SEARCH IN INCREASING ORDER

- Ex: insert 411 in [113 400 612 818]
- Initialize the content of the output position *i* to ∞ so that we don't have to test if we are at end of current list
- Start at *j*=1 and find first position *j* where *x* belongs i.e., *x* < out[*j*]
- Move all elements at positions k (k ≥ j) one to right (i.e., to k+1)
- *j* comparisons and *i*–*j*+1 moves
- Total of *i*+1 operations for step *i*
- Total of (n+1)(n+2)/2-1 = n(n+3)/2 operations independent of whether the file is initially sorted, not sorted, or sorted in reverse order

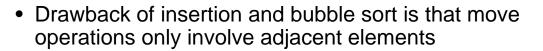
SEARCH IN DECREASING ORDER

- Ex: insert 411 in [113 400 612 818]
- Initialize the contents of the output position 0 to -∞ so that we don't have to test if we are at end (actually the start) of the current list
- Start at *j* =*i* and find first position *j* where *x* belongs i.e., out[*j*-1] ≤ x
- Each time test is false, move the element tested (i.e., at *j*−1) one to the right (i.e., *j*)
- *i*–*j*+1 comparisons and *i*–*j* moves for step *i*
- Total of as many as n(n+1)/2 comparisons and n(n-1)/2 moves when data is sorted in reverse order
- Total of as few as n comparisons and 0 moves when the data is already sorted in increasing order
- Superior to a search increasing order

SORTING BY DISTRIBUTION COUNTING

- Insertion sort must perform move operations because when a value is inserted in the output list, we don't know its final position
- If we know the distribution of the various values, then we can calculate their final position in advance
- If range of values is finite, use an extra array of counters
- Algorithm:
 - 1. count frequency of each value
 - 2. calculate the destination address for each value by making a pass over the array of counters in reverse order and reuse the counter field
 - 3. place the values in the right place in the output list
- O(m+n) time for *n* values in the range $0 \dots m-1$ and stable
- Not in-place because on the final step we can't tell if a value is in its proper location as values are not inserted in the output list in sorted order
- Ex:

input list:	0 3a	1		2 8a	3 2a	4 1a	5		6 2b	7 0b
list.	Ja		a	oa	Za	l la		b	20	
counter:	0	1	2	3	4	5	6	7	/ 8	9
value:	2	2	2	1	0	0	0	C) 1	0
position:	0	2	4	6	7	7	7	7	' 7	8
output	0	1		2	3	4	5	;	6	7
list:				-		· ·		-	<u> </u>	/ 00
list.	0a)	1a	1b	2a	2	D	3a	8a



 If largest element is initially at the start, then by the end of the sort it will have been the subject of n move or exchange operations

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- Can reduce number of move operations by allowing values to make larger jumps
- Sort successively larger sublists
 - 1. e.g., sort every fourth element
 - elements 1, 5, 9, 13, 17 form one sorted list
 - elements 2, 6, 10, 14, 18 form a second sorted list
 - elements 3, 7, 11, 15, 19 form a third sorted list
 - elements 4, 8, 12, 16, 20 form a fourth sorted list
 - 2. apply same technique with successively shorter increments
 - 3. final step uses an increment of size 1
- Usually implement by using insertion sort (that searches for position to make the insertion in decreasing order) at each step
- Ex: with increment sequence of 4, 2, 1

	1	2	3	4	5	6	7	8
start	113	400	818	612	411	311	412	420



- Drawback of insertion and bubble sort is that move operations only involve adjacent elements
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	1	2	3	4	5	6	7	8
start	113	400	818	612	411	311	412	420
h=4	113	311	412	420	411	400	818	612



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start	113	400	818	612	411	311	412	420
h=4	113	311	412	420	411	400	818	612
			112				010	

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			•					
	1	2	3	4	5	6	7	8
start	113	400	818	612	411	311	412	420
h=4	113	311	412	420	411	400	818	612
h=2	113	311	411	400	412	420	818	612
h=1	113	311	400	411	412	420	612	818
	. .							

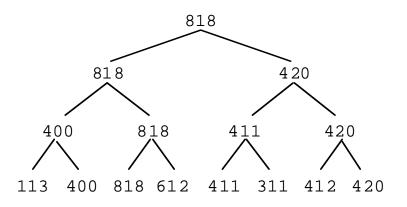
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PROPERTIES OF SHELLSORT

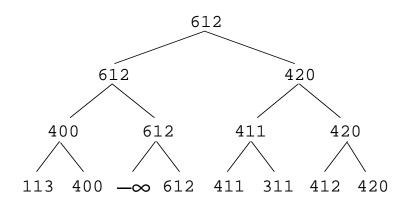
- Difficult to analyze execution time but is good due to being simple, having a fast inner loop, and no bad cases
- Some increment sequences yield $O(n\sqrt{n})$
- Others of form 2^p3^q (e.g., 1, 2, 3, 4, 6, 9, 16, 18, ...) yield O(n log₂n)
- Some increment sequences are better than others
- Not stable but in-place
- 1, 2, 4, 8, ... is not so good as doesn't allow for interaction between values in odd and even positions until final step
- Desirable for log₂*n* increments in order to reduce the number of passes that need to be made over the data
- Not stable as order of equal values is destroyed due to application of sorting to overlapping lists
- In-place

TOURNAMENT SORT

• Like a ladder



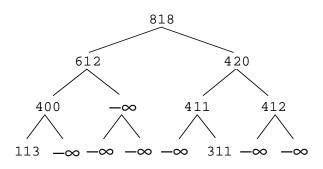
Output value at the root, replace it by -∞, and rebuild the ladder



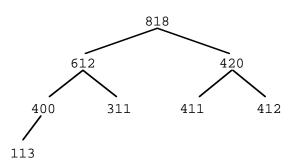
• Sorting takes $O(n \log_2 n)$ once the ladder has been built

HEAPSORT (TREESORT)

- Tournament ladder is wasteful of space as values are repeated
- Need space to store the output of the sort
- Use a modified tournament ladder where only the winners are retained



• Rearrange values so get a reasonably complete binary tree



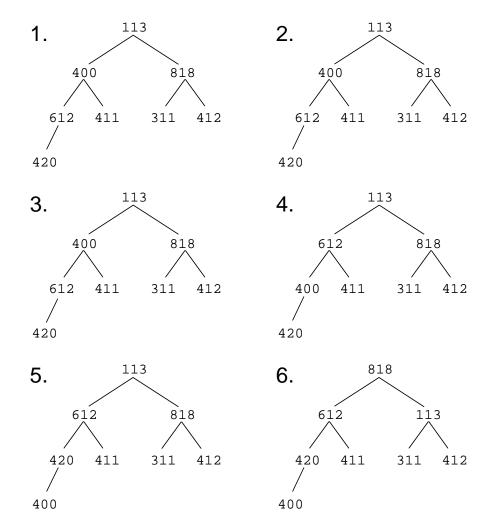
- Result is a heap
 - 1. each value is greater than its two sons
 - 2. use a complete binary tree array representation
 - sons of node at location x are at 2x and 2x+1

1	2	3	4	5	6	7	8
818	612	420	400	311	411	412	113



BUILDING A HEAP

- Start at bottom level of tree
 - 1. compare maximum of each pair of brother values with their father
 - 2. if father < maximum of sons, then exchange father with maximum son and repeat as necessary with two sons
- Repeat process for remaining values on the same level, and the remaining levels while ascending the tree



• Process is not stable

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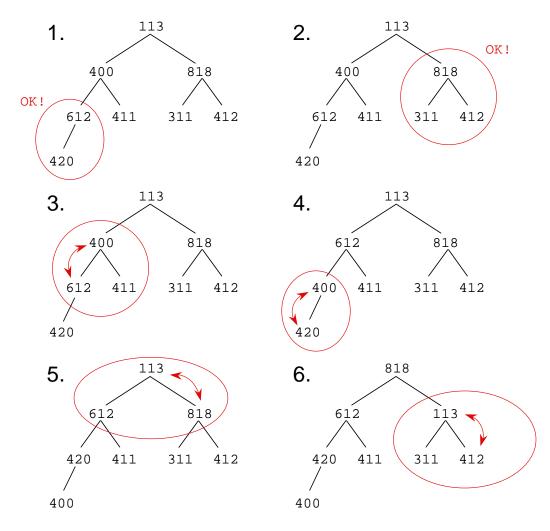




• Start at bottom level of tree

BUILDING A HEAP

- 1. compare maximum of each pair of brother values with their father
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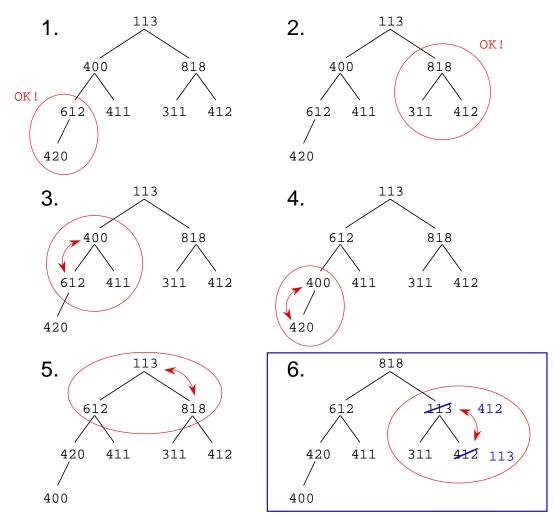
• Process is not stable

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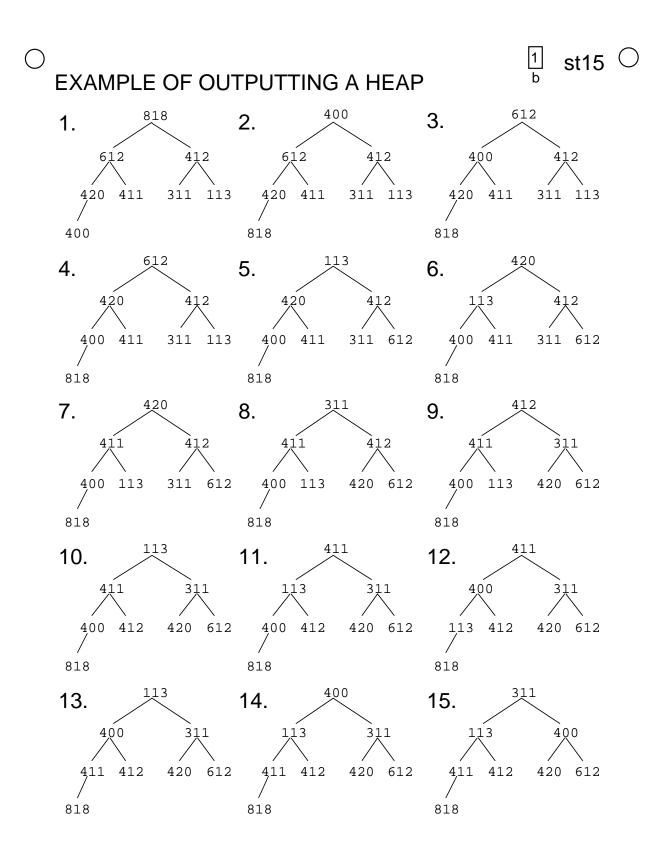
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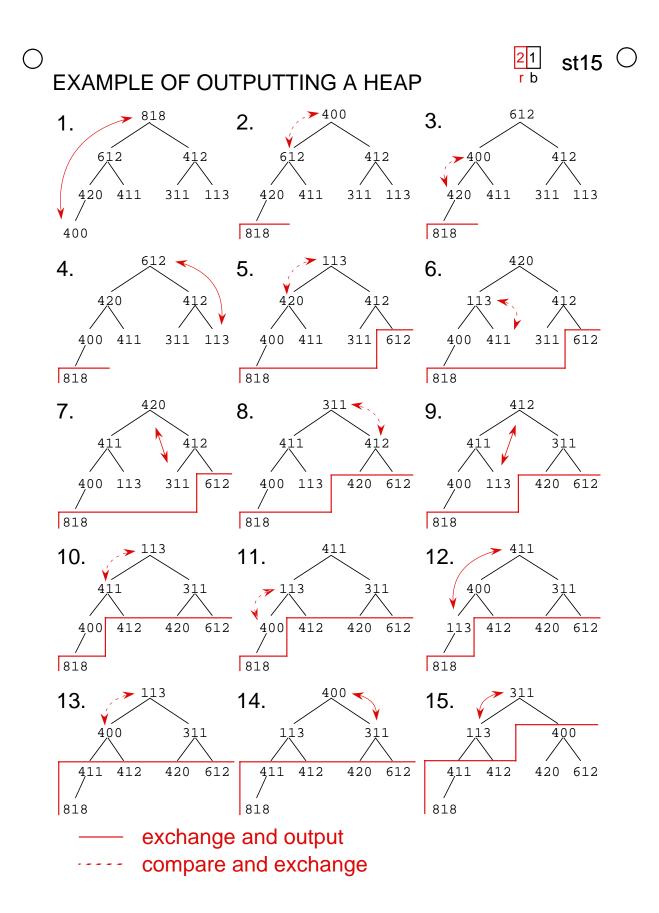
- Process is not stable
- Final result

OUTPUTTING A HEAP

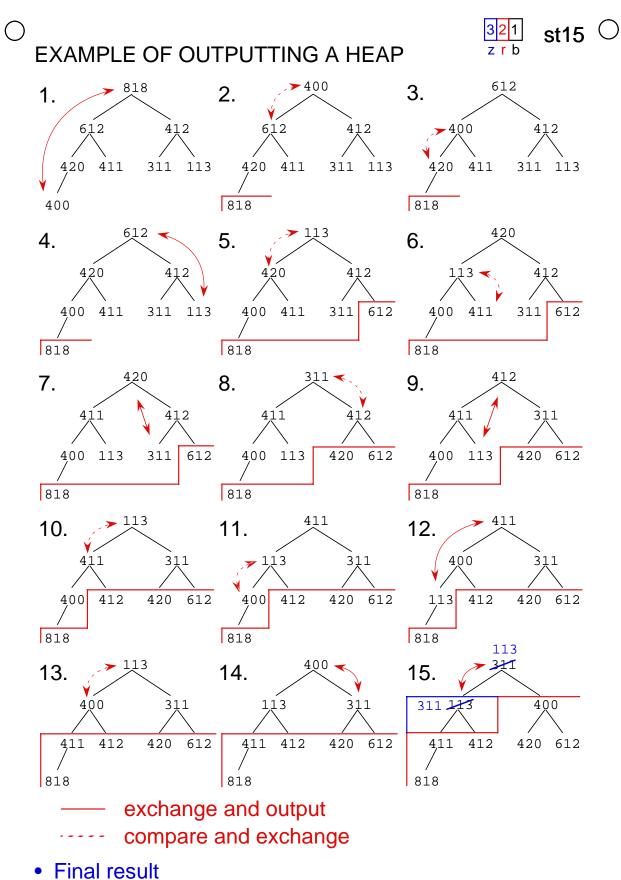
- 1. Exchange root with node at the end of the unsorted set
- 2. Compare root with roots of left and right subtrees
- 3. If root > left and root > right, then done
- If root > max(left,right) and max(left,right)=left, then exchange root with left son and reapply steps 1–5 to left subtree
- 5. Else exchange root with right son and reapply steps 1–5 to right subtree



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ANALYSIS OF HEAPSORT

- 1. Outputting the heap is $O(n \log_2 n)$
- 2. Building the heap
 - based on counting the number of comparisons when each position in the heap serves as the starting point of a comparison process
 - a. root is at level $\lfloor \log_2 n \rfloor$
 - b. between 1 and $\lceil n / 2 \rceil$ nodes at level 0
 - c. root is the start of at most $2 \lfloor \log_2 n \rfloor$ comparison operations
 - d. nodes at level 1 are start of at most 2 comparison operations, and there are at most $\lceil n/4 \rceil$ of them
 - e. nodes at level *i* are the start of at most 2i comparison operations, and there are at most $\left\lceil n/2^{i+1} \right\rceil$ of them

•
$$C = \text{number of comparisons} = \sum_{i=1}^{\lfloor \log_2 n \rfloor} \frac{n \cdot i}{2^i}.$$

$$\sum_{i=1}^{a} \frac{i}{2^i} = \frac{1}{2} \cdot \sum_{i=0}^{a-1} \frac{i+1}{2^i} = \frac{1}{2} \cdot \sum_{i=0}^{a-1} \frac{i}{2^i} + \frac{1}{2} \cdot \sum_{i=0}^{a-1} \frac{1}{2^i}$$

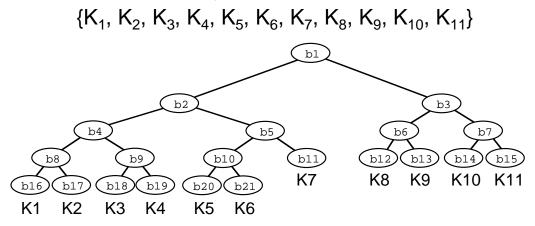
$$= \frac{1}{2} \cdot \sum_{i=1}^{a-1} \frac{i}{2^i} + \frac{1}{2} \cdot \frac{1 - \frac{1}{2^a}}{1 - \frac{1}{2}} = \frac{1}{2} \cdot \sum_{i=1}^{a} \frac{i}{2^i} - \frac{a}{2^{a+1}} + 1 - \frac{1}{2^a}$$
or, $\sum_{i=1}^{a} \frac{i}{2^i} = 2 - \frac{a+2}{2^a}$
Substituting into C yields
$$C = n \cdot \left(2 - \frac{\lfloor \log_2 n \rfloor + 2}{2^{\lfloor \log_2 n \rfloor}}\right) \approx 2 \cdot n$$

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PRIORITY QUEUES

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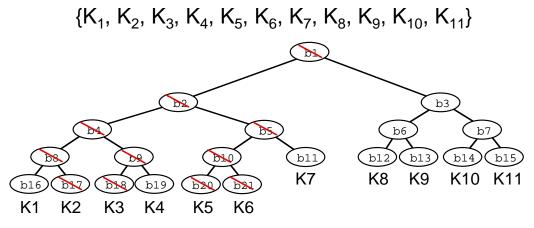
- Properties
 - 1. locate the maximum (minimum) element in O(1) time
 - 2. insert and delete an arbitrary element in $O(\log_2 n)$ time
- Can implement using a heap
- If set of possible elements is known a priori, then can use a bit representation consisting of an array corresponding to a complete binary tree (Abel)
 - 1. all information is stored at the bottom two levels
 - 2. for *n* elements, need just 2n-1 bits
 - 3. node b_i is 1 if one of the elements below it is present
- Ex: set of possible keys



С

PRIORITY QUEUES

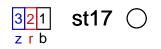
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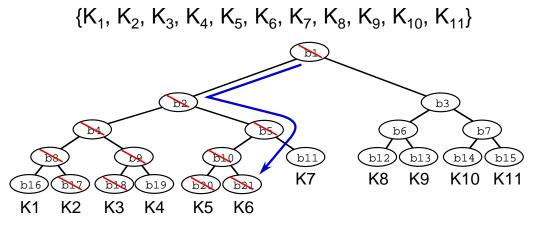
For the set $S = \{K_2, K_3, K_5, K_6\}$ we have $b_1 = b_2 = b_4 = b_5 = b_8 = b_9 = b_{10} = b_{17} = b_{18} = b_{20} = b_{21} = 1$

С

PRIORITY QUEUES



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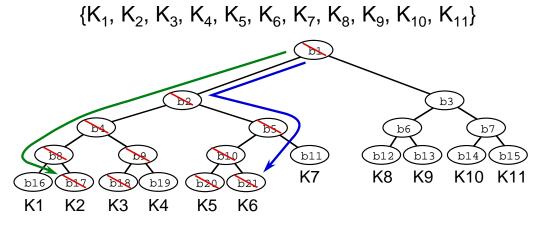
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- To locate the maximum element:
 1. *j*←1
 2. while *j*<*n* do *j*← 2*j* + b_{2*i*+1}

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PRIORITY QUEUES

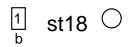


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- For the set $S = \{K_2, K_3, K_5, K_6\}$ we have $b_1 = b_2 = b_4 = b_5 = b_8 = b_9 = b_{10} = b_{17} = b_{18} = b_{20} = b_{21} = 1$
- To locate the maximum element:
 1. *j*←1
 2. while *j*<*n* do *j*← 2*j* + b_{2*i*+1}
- To locate the minimum element:
 1. *j*←1
 2. while *j*<*n* do *j*← 2*j*+1 − b_{2i}

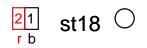




- Key:
 - 1. break file into successive halves such that each half contains all keys greater than a certain value
 - recursive application of this partitioning scheme to halves yields a sorted list once a partition has only one element
- Algorithm:
 - 1. pick an item in the array at random, say x
 - 2. scan the array of keys from the left until $a_i \ge x$ is found
 - 3. scan the array of keys from the right until $a_i \le x$ is found
 - 4. exchange a_i and a_j and continue the scan and swap process until the two scans meet (note that *x* itself may also be moved)

• Ex:	1	2	3	4	5	6	7	8
	113	400	818	612	411	311	412	420





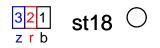
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 - 3. scan the array of keys from the right until $a_i \le x$ is found
 - 4. exchange a_i and a_j and continue the scan and swap process until the two scans meet (note that *x* itself may also be moved)

• Ex:	1	2	3	4	5	▲6	7	8
	113	400	818	612	411	311	412	420

exchange 818 and 311

113	400	311	612	411	818	412	420





- Key:
 - 1. break file into successive halves such that each half contains all keys greater than a certain value
 - recursive application of this partitioning scheme to halves yields a sorted list once a partition has only one element
- Algorithm:
 - 1. pick an item in the array at random, say x
 - 2. scan the array of keys from the left until $a_i \ge x$ is found
 - 3. scan the array of keys from the right until $a_j \le x$ is found
 - 4. exchange a_i and a_j and continue the scan and swap process until the two scans meet (note that *x* itself may also be moved)

• Ex:	1	2	3	4	5	▲6	7	8
	113	400	818	612	411	311	412	420

exchange 818 and 311

113	400	311	612	411	818	412	420
				•			

exchange 612 and 411

113 400 311 411 612 818 412 420

stop with j = 4 and i = 5

now, partition the two subhalves (1, j) and (i, 8)...





- Key:
 - 1. break file into successive halves such that each half contains all keys greater than a certain value
 - recursive application of this partitioning scheme to halves yields a sorted list once a partition has only one element
- Algorithm:
 - 1. pick an item in the array at random, say x
 - 2. scan the array of keys from the left until $a_i \ge x$ is found
 - 3. scan the array of keys from the right until $a_j \le x$ is found
 - 4. exchange a_i and a_j and continue the scan and swap process until the two scans meet (note that *x* itself may also be moved)

• Ex:	1	2	3	4	5	▲6	7	8
	113	400	818	612	411	311	412	420

exchange 818 and 311

113	400	311	612	411	818	412	420
			•	•			

exchange 612 and 411

113 400 311 411 612 818 412 420

stop with j = 4 and i = 5

now, partition the two subhalves (1, j) and (i, 8)...

 Average O(n log₂n): log₂n passes to partition the file into singletons, each pass makes n comparison operations

DRAWBACKS OF QUICKSORT

- 1. Taking random elements may be overkill
 - solution: always work with first or last element in a sublist
 - problem: worst case of the algorithm arises when the file is initially in sorted order
 - solution: take a small subset and use its median as the partition value
- 2. Reduce stack requirements by processing the shortest partition first
- 3. Use insertion sort for small partitions
- 4. Not stable due to scan-and-swap process

COMPUTING MEDIANS

- More generally, find the kth value in increasing order from a set containing n values
- No need to sort the entire list
- Process partition containing entry *a_k*
- Algorithm:
 - 1. Partition set: x = splitting value

$$\begin{array}{l} a_h \leq x \quad \forall h < i \\ a_h \geq x \quad \forall h > j \end{array} i > j$$

- 2. if $k \ge i$, then partition right subhalf if $k \le j$, then partition left subhalf otherwise, k^{th} value is a_k since j < k < i
- Ex: want 6th largest element

1	2	3	4	5	6	7	8
113	400	818	612	411	311	412	420

pick item 5 at random (i.e. 411):

113 400 311 411	612 818	412 420
-----------------	---------	---------

 $k = 6 \ge 5 = i$, so partition right half

use item 8 as the splitting value (i.e., 420):

420 412	818	612
---------	-----	-----

k = 6 = j, so partition left half

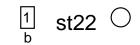
use item 6 as the splitting value (i.e., 412)

420 is the 6th value in increasing order, since $k = 6 \ge i = 6$

ANALYSIS OF MEDIAN COMPUTATION

- 1. Average log₂*n* partitions
- 2. Only process one partition
- 3. *i*th partition has an average of $n/2^i$ elements
 - i.e., $n/2^i$ comparisons
- 4. Total average running time is $\begin{bmatrix} \log_2 n \end{bmatrix} \quad \begin{bmatrix} \log_2 n \end{bmatrix}$

$$n + \sum_{i=1}^{\lceil \log_2 n \rceil} \frac{n}{2^i} = n + n \cdot \sum_{i=1}^{\lceil \log_2 n \rceil} \frac{1}{2^i} = n + n \cdot 1 = 2n$$



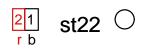
- Quicksort sorts a list on the basis of its values
- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is 	number	binary representation
represented by an <i>M</i> bit	113	0001110001
number $b_{M-1} \dot{b}_{M-2} \dots b_1 b_0$	400	0110010000
	818	1100110010
(i.e., ranging from 0 to $2^M - 1$)	612	1001100100
	411	0110011011
	311	0100110111
	412	0110011100
	420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

oton	partition	element number							
step	values	1	2	3	4	5	6	7	8
start	—	113	400	818	612	411	311	412	420



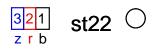


- Quicksort sorts a list on the basis of its values
- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is represented by an <i>M</i> bit number b_{M-1} b_{M-2} b₁ b₀ (i.e., ranging from 0 to 2^M-1 	number 113 400 818) 612 411 311	binary representation 0 0 0 1 1 1 0 0 0 1 0 1 1 0 0 1 0 0 0 0 1 1 0 0 1 1 0 0 1 0 1 0 0 1 1 0 0 1 0 0 0 1 1 0 0 1 1 0 1 1 0 1 0 0 1 1 0 1 1 1
	311 412	
	420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

otop	partition		element number						
step	values	1	2	3	4	5	6	7	8
start	-	113	400	818	612	411	311	412	420
bit 9	512	113	400	420	412	` 411	311 311	612	818

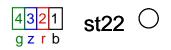


- Quicksort sorts a list on the basis of its values
- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is represented by an <i>M</i> bit number b_{M-1} b_{M-2} b₁ b₀ (i.e., ranging from 0 to 2^M-1) 	400 818 612 411 311	$\begin{array}{c} 0 & 0 & 1 & 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 1 & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 & 0 & 1 & 1 & 1 \\ \end{array}$
	412 420	0100110111 0110011100 01100100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

atan	partition		element number						
step	values	1	2	3	4	5	6	7	8
start	-	113	400	818	612	411	311	412	420
bit 9	512	113	400	420	412	` 411		612	818
bit 8	256,768	113	400	420	412	411	311	612	818



- Quicksort sorts a list on the basis of its values
- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is 	number	binary representation
represented by an <i>M</i> bit	113	0001110001
number $b_{M-1} \ b_{M-2} \dots \ b_1 \ b_0$	400	011001000
	818	1100110010
(i.e., ranging from 0 to $2^M - 1$)	612	1001100100
	411	0110011011
	311	0100110111
	412	0110011100
	420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

aton	partition		element number						
step	values	1	2	3	4	5	6	7	8
start	—	113	400	818	612	411	311	412	420
bit 9	512	113	400	,420	412	<u>`</u> 411	311	612	818
bit 8	256,768	113	4001	420	412	411	311	612	818
bit 7	384		311	420	412	411	400	-	-

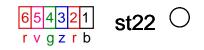


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- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is 	number	binary representation
represented by an <i>M</i> bit	113	0001110001
number $b_{M-1} \dot{b}_{M-2} \dots b_1 b_0$	400	011001000
	818	1100110010
(i.e., ranging from 0 to $2^M - 1$)	612	1001100100
	411	0110011011
	311	0100110111
	412	0110011100
	420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

aton	partition		element number							
step	values	1	2	3	4	5	6	7	8	
start	—	113	400	818	612	411	311	412	420	
bit 9	512	113	400	,420	412	<u>`</u> 411	311	612		
bit 8	256,768	113	4001	420	412	411	311	612	818	
bit 7	384		311	420	412	411	400	-	_	
bit 6	448			420	412	411	400			

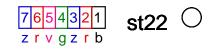


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- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is 	number	binary representation
represented by an <i>M</i> bit	113	0001110001
number b_{M-1} b_{M-2} b_1 b_0	400	011001000
	818	1100110010
(i.e., ranging from 0 to $2^M - 1$)	612	1001100100
	411	0110011011
	311	0100110111
	412	0110011100
	420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

aton	partition		element number							
step	values	1	2	3	4	5	6	7	8	
start	-	113	400	818	612	411	311	412	420	
bit 9	512	113	400	420	412	<u>`</u> 411	311	612	818	
bit 8	256,768	113	4001	420	412	411	311	612	818	
bit 7	384		311	420	,412	411	400	-		
bit 6	448			420	412	411	400			
bit 5	416			400	412	411	420			

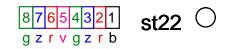


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- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

• Assume each	value is	number	binary representation
represented b	y an <i>M</i> bit	113	0001110001
number b _{M-1} l	b_{μ} b_{μ} b_{μ}	400	011001000
		818	1 1 0 0 1 1 0 0 1 0
(i.e., ranging f	rom 0 to 2 ^M -1)	612	1001100100
		411	0110011011
		311	0100110111
		412	0110011100
		420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

aton	partition			ele	ement	num	ber		
step	values	1	2	3	4	5	6	7	8
start	-	113	400	818	612	411	311	412	420
bit 9	512	113	400	420	412	<u>`</u> 411	311	612	818
bit 8	256,768	113	4001	420	412	411	311	612	818
bit 7	384		311	420		411	400	-	_
bit 6	448			4201	412	411	400		
bit 5	416			400	412	411	420		
bit 4	400			400	412	411			

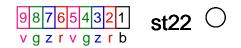


- Quicksort sorts a list on the basis of its values
- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is 	number	binary representation
represented by an <i>M</i> bit	113	00011100001
number $b_{M-1} \dot{b}_{M-2} \dots b_1 b_0$	400	011001000
	818	1100110010
(i.e., ranging from 0 to $2^M - 1$)	612	1001100100
	411	0110011011
	311	0100110111
	412	0110011100
	420	0110100100

- Algorithm:
 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

aton	partition			ele	ement	num	ber		
step	values	1	2	3	4	5	6	7	8
start	—	113	400	818	612	411	311	412	420
bit 9	512	113	400	420	412	<u>`</u> 411	-	-	818
bit 8	256,768	113	4001	420	412	411	311	612	818
bit 7	384		311	420	412		400		
bit 6	448			4201	412	411	400		
bit 5	416			400	412	411	420		
bit 4	400			400	412	411			
bit 3	408			400	412	411			



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- Can also partition on the basis of the bits (more generally the characters or digits) that make up the values

 Assume each value is 	number	binary representation
represented by an <i>M</i> bit	113	0001110001
number $b_{M-1} \dot{b}_{M-2} \dots b_1 b_0$	400	0110010000
···· · ··· — · · •	818	1100110010
(i.e., ranging from 0 to $2^M - 1$)	612	1001100100
	411	0110011011
	311	0100110111
	412	0110011100
	420	0110100100

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 - 1. test most significant bit and partition into two sublists (i.e., $b_{M-1}=0$ and $b_{M-1}=1$)
 - 2. recur on sublists testing successive bit positions
 - 3. terminate when no bits are left to test, or sublist is empty
- Ex:

aton	partition			ele	ement	num	ber		
step	values	1	2	3	4	5	6	7	8
start	—	113	400	818	612	411	311	412	420
bit 9	512	113	400	420	412	<u>`</u> 411	311	612	818
bit 8	256,768	113	4001	420	412	411	311	612	818
bit 7	384		311	420		411	400		
bit 6	448			4201	412	411	400		
bit 5	416			400	412	411	420		
bit 4	400			400	412	411			
bit 3	408			400	412	411			
bit 2	412				411	412			

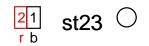
As in quicksort, not stable due to scan-and-swap process



- Radix-exchange sorting does not work too well when leading bits of the items being sorted are identical
- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number *b*_{M−1} *b*_{M−2} ... *b*₁ *b*₀ (i.e., ranging from 0 to 2^M−1)

number	binary representation
113	0001110001
400	0110010000
818	1100110010
612	1001100100
411	0110011011
311	0100110111
412	0110011100
420	0110100100

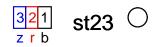
cton	element number										
step	1	2	3	4	5	6	7	8			
start	113	400	818	612	411	311	412	420			



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- Assume each value is represented by an *M* bit number b_{M−1} b_{M−2} ... b₁ b₀ (i.e., ranging from 0 to 2^M−1)

number	binary representation
113	0001110001
400	011001000
818	1100110010
612	1001100100
411	0110011011
311	010011011
412	0110011100
420	0110100100

otop		element number										
step	1	2	3	4	5	6	7	8				
start	(113)	400	818	612	(411)	(311)	412	420				
bit 0	400	818	612	412	420	113	411	311				



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- Assume each value is represented by an *M* bit number b_{M−1} b_{M−2} ... b₁ b₀ (i.e., ranging from 0 to 2^M−1)

number	binary representation
113	0001110001
400	011001000
818	1100110010
612	1001100100
411	0110011011
311	0100110111
412	0110011100
420	0110100100

otop		element number										
step	1	2	3	4	5	6	7	8				
start	(113)	400	818	612	(411)	(311)	412	420				
bit 0	400	(818)	612	412	420	113	(411)	(311)				
bit 1	400	612	412	420	113	818	411	311				

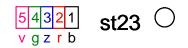


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- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number *b_{M−1} b_{M−2}* ... *b*₁ *b*₀ (i.e., ranging from 0 to 2^{*M*}−1)

number	binary representation
113	0001110001
400	011001000
818	1100110010
612	1001100100
411	0110011011
311	0100110111
412	0110011100
420	0110100100

• Ex: highlight elements where tested bit has value 1

otop		element number							
step	1	2	3	4	5	6	7	8	
start	(113)	400	818	612	(411)	(311)	412	420	
bit 0	400	818	612	412	420	113	(411)	(311)	
bit 1	400	612	(412)	(420)	113	818	411	(311)	
bit 2	400	113	818	411	612	412	420	311	
					-				



- Radix-exchange sorting does not work too well when leading bits of the items being sorted are identical
- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number *b_{M−1} b_{M−2}* ... *b*₁ *b*₀ (i.e., ranging from 0 to 2^{*M*}−1)

number	binary representation
113	0001110001
400	011001000
818	1100110010
612	1001100100
411	0110011011
311	0100110111
412	0110011100
420	0110100100

otop		element number								
step	1	2	3	4	5	6	7	8		
start	(113)	400	818	612	(411)	(311)	412	420		
bit 0	400	818	612	412	420	113	(411)	(311)		
bit 1	400	612	(412)	(420)	113	818	411	(311)		
bit 2	400	113	818	(411)	612	412	420	311		
bit 3	400	113	818	612	420	311	411	412		



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- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number *b_{M−1} b_{M−2}* ... *b*₁ *b*₀ (i.e., ranging from 0 to 2^{*M*}−1)

number	binary representation
113	0001110001
400	011001000
818	1 1 0 0 1 1 0 0 1 0
612	1001100100
411	0 1 1 0 0 1 1 0 1 1
311	0100110111
412	0 1 1 0 0 1 1 1 0 0
420	0110100100

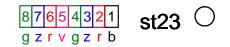
aton		element number								
step	1	2	3	4	5	6	7	8		
start	(113)	400	818	612	(411)	(311)	412	420		
bit 0	400	818	612	412	420	113	(411)	(311)		
bit 1	400	612	(412)	(420)	113	818	411	(311)		
bit 2	400	113	818	(411)	612	412	420	311		
bit 3	(400)	(113)	(818)	612	420	(311)	(411)	(412)		
bit 4	612	420	400	113	818	311	411	412		



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- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number *b_{M−1} b_{M−2}* ... *b*₁ *b*₀ (i.e., ranging from 0 to 2^{*M*}−1)

number	binary representation									
113	0001110001									
400	011001000									
818	1 1 0 0 1 1 0 0 1 0									
612	1001100100									
411	0 1 1 0 0 1 1 0 1 1									
311	0100110111									
412	0 1 1 0 0 1 1 1 0 0									
420	0110100100									

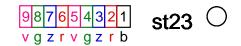
oton	element number								
step	1	2	3	4	5	6	7	8	
start	(113)	400	818	612	(411)	(311)	412	420	
bit 0	400	818	612	412	420	113	(411)	(311)	
bit 1	400	612	(412)	(420)	113	818	411	(311)	
bit 2	400	113	818	411	612	412	420	311	
bit 3	(400)	(113)	818	612	420	(311)	(411)	(412)	
bit 4	612	(420)	400	113	818	311	411	412	
bit 5	400	411	412	612	420	113	818	311	



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- Assume each value is represented by an *M* bit number b_{M−1} b_{M−2} ... b₁ b₀ (i.e., ranging from 0 to 2^M−1)

number	binary representation
113	0001110001
400	011001000
818	1 1 0 0 1 1 0 0 1 0
612	10011000
411	0 1 1 0 0 1 1 0 1 1
311	0 1 0 0 1 1 0 1 1 1
412	0 1 1 0 0 1 1 1 0 0
420	0110100100

otop	element number									
step	1	2	3	4	5	6	7	8		
start	(113)	400	818	612	(411)	(311)	412	420		
bit 0	400	818	612	412	420	113	(411)	(311)		
bit 1	400	612	(412)	(420)	113	818	411	(311)		
bit 2	400	113	818	(411)	612	412	420	311		
bit 3	(400)	(113)	(818)	612	420	(311)	(411)	(412)		
bit 4	612	(420)	400	113	818	311	411	412		
bit 5	400	411	412	612	420	(113)	818	311		
bit 6	400	411	412	420	818	311	612	113		



- Radix-exchange sorting does not work too well when leading bits of the items being sorted are identical
- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number *b_{M−1} b_{M−2}* ... *b*₁ *b*₀ (i.e., ranging from 0 to 2^{*M*}−1)

number	binary representation									
113	0001110001									
400	011001000									
818	1 1 0 0 1 1 0 0 1 0									
612	1001100100									
411	0 1 1 0 0 1 1 0 1 1									
311	0100110111									
412	0 1 1 0 0 1 1 1 0 0									
420	0110100100									

oton	element number									
step	1	2	3	4	5	6	7	8		
start	(113)	400	818	612	(411)	(311)	412	420		
bit 0	400	818	612	412	420	113	(411)	(311)		
bit 1	400	612	(412)	(420)	113	818	411	(311)		
bit 2	400	113	818	(411)	612	(412)	420	311		
bit 3	(400)	(113)	(818)	612	420	(311)	(411)	(412)		
bit 4	612	(420)	400	113	818	311	411	412		
bit 5	400	411	412	<u>612</u>	420	(113)	818	311		
bit 6	400	(411)	412	420	818	311	612	113		
bit 7	818	311	612	113	400	411	412	420		
					-					



- Radix-exchange sorting does not work too well when leading bits of the items being sorted are identical
- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number b_{M−1} b_{M−2} ... b₁ b₀ (i.e., ranging from 0 to 2^M−1)

number	binary representation										n
113	0	0	0	1	1	1	0	0	0	1	
400	0	1	1	0	0	1	0	0	0	0	
818	1	1	0	0	1	1	0	0	1	0	
612	1	0	0	1	1	0	0	1	0	0	
411	0	1	1	0	0	1	1	0	1	1	
311	0	1	0	0	1	1	0	1	1	1	
412	0	1	1	0	0	1	1	1	0	0	
420	0	1	1	0	1	0	0	1	0	0	

otop			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start	(113)	400	818	612	(411)	(311)	412	420
bit 0	400	818	612	412	420	113	(411)	311
bit 1	400	612	(412)	(420)	113	818	411	(311)
bit 2	400	113	818	(411)	612	412	420	311
bit 3	(400)	(113)	(818)	612	420	(311)	(411)	(412)
bit 4	612	(420)	400	113	818	311	411	412
bit 5	400	411	412	<u>612</u>	420	(113)	818	311
bit 6	400	411	412	420	818	311	612	113
bit 7	(818)	(311)	612	113	(400)	(411)	(412)	(420)
bit 8	612	113	818	311	400	411	412	420



- Radix-exchange sorting does not work too well when leading bits of the items being sorted are identical
- Alternative is to sort based on the trailing bits using a stable method such as distribution counting
- Assume each value is represented by an *M* bit number b_{M−1} b_{M−2} ... b₁ b₀ (i.e., ranging from 0 to 2^M−1)

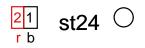
number	binary representation	
113	00011100001	
400	0110010000	
818	1100110010	
612	1001100100	
411	0110011011	
311	0100110111	
412	011001100	
420	0110100100	

cton			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start	(113)	400	818	612	(411)	(311)	412	420
bit 0	400	818	612	412	420	113	(411)	(311)
bit 1	400	612	(412)	(420)	113	818	411	(311)
bit 2	400	113	818	(411)	612	(412)	420	311
bit 3	(400)	(113)	(818)	612	420	(311)	(411)	(412)
bit 4	612	(420)	400	(113)	(818)	(311)	411	412
bit 5	400	411	412	<u>612</u>	420	(113)	818	311
bit 6	(400)	(411)	(412)	(420)	818	311	612	113
bit 7	(818)	(311)	612	113	(400)	(411)	(412)	(420)
bit 8	612	113	(818)	311	400	411	412	420
bit 9	113	311	400	411	412	420	612	818



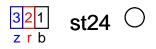
- Slow when the set of numbers being sorted is small while the range of values is large
- Can speed up by using larger groups of bits such as 4 or even the base 10 digits of the numbers
- Ex:

ctop			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start	113	400	818	612	411	311	412	420



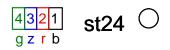
- Slow when the set of numbers being sorted is small while the range of values is large
- Can speed up by using larger groups of bits such as 4 or even the base 10 digits of the numbers
- Ex:

ctop		element number										
step	1	2	3	4	5	6	7	8				
start	113	400	818	612	411	311	412	420				
start digit 0	400	420	411	311	612	412	113	818				
							•	•				



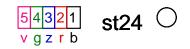
- Slow when the set of numbers being sorted is small while the range of values is large
- Can speed up by using larger groups of bits such as 4 or even the base 10 digits of the numbers
- Ex:

aton			el	ement	numb	er		
step	1			4		6		8
start digit 0 digit 1	113	400	818	612	411	311	412	420
digit 0	400	420	411	311	612	412	113	818
digit 1	400	411	311	612	412	113	818	420
Ŭ		•					·	•



- Slow when the set of numbers being sorted is small while the range of values is large
- Can speed up by using larger groups of bits such as 4 or even the base 10 digits of the numbers
- Ex:

oton			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start								
digit 0	400	420	411	311	612	412	113	818
digit 1								
digit 2								



- Slow when the set of numbers being sorted is small while the range of values is large
- Can speed up by using larger groups of bits such as 4 or even the base 10 digits of the numbers
- Ex:

aton			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start								
digit 0	400	420	411	311	612	412	113	818
digit 1								
digit 2	113	311	400	411	412	420	612	818

- Radix sorting differs from radix-exchange sorting in that we can't use the scan-and-swap process to rearrange the sublist currently being processed since it is not stable
- Need space for the output list and the counters for sorting by distribution counting
- $O(n \log_2 M)$ time
- Analogous to techniques used to sort punched cards in prior times
- *M* is the range of values being sorted





- Bottom-up quicksort
- Small partitions are repeatedly merged to yield larger lists
- Ex:

ctop			el	ement	numb	er	element number										
step	1	2	3	4	5	6	7	8									
start	113	400	818	612	411	311	412	420									



- Bottom-up quicksort
- Small partitions are repeatedly merged to yield larger lists
- Ex:

otop			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start	113	<u>400</u> 400	818	612	411	311	412	420
1	113	400	612	818	311	411	412	420



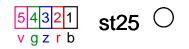
- Bottom-up quicksort
- Small partitions are repeatedly merged to yield larger lists
- Ex:

cton	element number									
step	1	2	3	4	5	6	7	8		
start	113	400	818	612	411	311	412	420		
1	113	400	612	612 818	311	411	412	420		
2	113	400	612	818	311	411	412	420		



- Bottom-up quicksort
- Small partitions are repeatedly merged to yield larger lists
- Ex:

otop			el	ement	numb	er		
step	1	2	3	4	5	6	7	8
start	113	400	818	612	411	311	412	420
1	113	400	612	818	311	411	412	420
2	113	400	612	818	311	411	412	420
3	113	311	400	411	412	420	612	818



- Bottom-up quicksort
- Small partitions are repeatedly merged to yield larger lists
- Ex:

aton	element number									
step	1	2	3	4	5	6	7	8		
start	113	400	818	612	411	311	412	420		
1	113	400	612	818	311	411	412	420		
2	113	400	612	818	311	411	412	420		
3	113	311	400	411	412	420	612	818		

• Observations:

- 1. $O(n \log_2 n)$ time as $\log_2 n$ passes and *n* items
- 2. stable as it retains duplicate items and in same order
- 3. not in-place as need room to store the output on each pass but can be reused
- 4. can avoid space for output list by using linked allocation instead of an array for the lists
- 5. similar to Shellsort with increment sequence 2^k , ..., 2, 1
 - must modify merge sorting not to use consecutive items
 - Shellsort usually uses insertion sort while for this increment sequence it can also be implemented with merging
 - a. result is still not stable as the lists being merged are overlapping rather than consecutive
 - b. process is not in-place because of merging
 - yields a version of Shellsort running in O(n log₂n) time but needs extra space
- 6. used in tape sorting
 - number of records is large and can't keep all in memory
 - merge sorting needs little memory as usually comparing one element against an adjacent one

POLYPHASE MERGE

• Merge sorting can be sped up by starting with larger ordered sequences of records (termed *runs* or *suites*)

• Ex: 12 42 44 55	6 18 67 90		
Suite #1	Suite #2	Suite #3	Suite #4

- k–1 tapes with s suites apiece may be merged onto a remaining tape to form s suites on it
- Each tape contains a different number of suites initially:

tape #	1	2	3	4	5	
# of suites	9	13	6	15	0	
After the first merge (onto tape 5):						
	3	7	0	9	6	
Rewinding tapes 3 and 5 and merging onto tape 3 yields:						
	0	4	3	6	3	

• Working backwards leads to an optimal distribution of suites on the tapes:

		Т	ape #			
Pass	1	2	3	4	5	
n	1	0	0	0	0	
<i>n</i> –1	0	1	1	1	1	Because on the next pass the
n–2	1	0	2	2	2 -	→ maximum number of suites on
<i>n</i> –3	3	2	0	4	4	tapes 2, 3, 4 or 5 is 1
<i>n</i> –4	7	6	4	0	8	• • •
<i>n</i> –5	15	14	12	8	0	Pass <i>i</i> –1 must create the largest
<i>n</i> –6	0	29	27	23	15	number of suites on pass <i>i</i> , so pass
n–7	29	0	56	54	44	<i>i</i> –1 must merge onto this tape

- Each of the distribution patterns provides a starting point for polyphase merge i.e., initially require 1, 4, 7, 13, 25, 49, 92, 181, ... suites
- These numbers can be obtained formally using recurrence relations

INITIAL SUITE DISTRIBUTION

- Performance of polyphase merge methods can be improved when the initial suites contain more records (implies less suites!)
 - 1. fill the working store (WS) to capacity
 - 2. when a record is output (R), it is replaced by the next record from the input (N)
 - if N> R, then N will eventually be output in same suite
 - if N < R, then N is part of new suite being formed in WS
- Summary: there are 2 suites in the working store!

•	Ex:	

|WS| = 3 [] = elements of new suite

	memory		output
1	2	3	
44	55	12	12
44	55	42	42
44	55	94	44
[6]	55	94	55
[6]	67	94	67
[6]	[18]	94	94
[6]	[18]	[70]	end of suite
[6] 6	18	70	6
98	18	70	18
98	82	70	70
98	82	[37]	82
	•		
	•		
	•		

 Theorem: the average length of a suite is 2·|WS| (see Knuth)

COMPARISON

- Merge sorting is a bottom-up variant of quicksort
- Can also have top-down merge sorting
 - 1. quicksort is partition-and-divide
 - 2. top-down merge sorting is divide-and-merge at start
 - 3. key to comparison is time at which recursion (*≡divide*) takes place
 - quicksort: at end
 - top-down merge sorting: at start
- Merge sorting is best for external sorting (i.e., on disk or tape)
- Radix methods are generally impractical as the range of values is usually large and thus many counters or many steps are needed (when sorting by distribution counting is used to reduce the number of steps)
- Linked storage lessens the impact of exchange operations
 - 1. in-place selection sort can be made stable
 - 2. quicksort and radix-exchange sorting need doublylinked lists as they process the lists in both directions
 - 3. top-down merge sorting is impractical as need to know how many elements are in each sublist
- Heapsort and Shellsort are in-place (don't require extra space) while quicksort and radix-exchange sorting are also in-place but need space for the stack

SPEED CONSIDERATIONS

- Quicksort is $n \log_2 n$ on the average but can be as bad as $O(n^2)$
- Heapsort and merge sorting are always $O(n \log_2 n)$
- Quicksort has fastest inner loop
- Merge sorting lies somewhere inbetween quicksort and heapsort
- Shellsort is comparable to merge sorting and is not sensitive to the data being in sorted order unlike quicksort
- When data set is small, use one of basic sorting methods
 - 1. insertion sort or selection sort are comparable
 - 2. insertion sort is preferable
 - easy to implement a stable in-place variant
 - selection sort always requires n^2 or $n^2/2$ operations
 - requires between *n* or n(n+1)/2 operations
 - only *n* operations when input is sorted in increasing order