#### GRAPHS

Hanan Samet

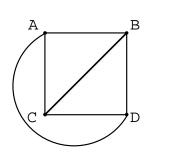
Computer Science Department and Center for Automation Research and Institute for Advanced Computer Studies University of Maryland College Park, Maryland 20742 e-mail: hjs@umiacs.umd.edu

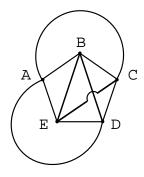
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### GRAPH (G)

- Generalization of a tree
  - 1. no longer a distinguished node called the root
    - implies no need to distinguish between leaf and nonleaf nodes
  - 2. two nodes can be linked by more than one sequence of edges
- Formally: set of vertices (V) and edges (E) joining them, with at most one edge joining any pair of vertices
- $(V_0, V_1, ..., V_n)$ : path of length *n* from  $V_0$  to  $V_n$  (chain)
- Simple Path: distinct vertices (elementary chain)
- Connected: path between any two vertices of G
- Cycle: simple path of length  $\ge$  3 from V<sub>0</sub> to V<sub>0</sub> (length in terms of edges)
- Planar: curves intersect only at points of graph
- Degree: number of edges intersecting at the node
- Isomorphic: if there is a one-to-one correspondence between nodes and edges of two graphs



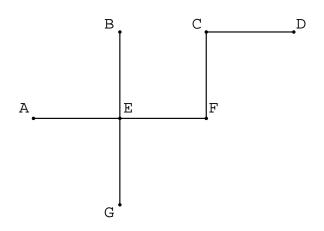


#### SAMPLE GRAPH PROBLEM

- Given *n* people at a party who shake hands, show that at the party's end, an even number of people have shaken hands with an odd number of people
- Theorem: For any graph G an even number of nodes have an odd degree
- Proof:
  - 1. each edge joins 2 nodes
  - 2. each edge contributes 2 to the sum of degrees
  - 3. sum of degrees is even
  - 4. thus an even number of nodes with odd degree

### FREE TREES

- Connected graph with no cycles
- Given G as a free tree with n vertices
  - 1. Connected, but not so if any edge is removed
  - 2. One simple path from V to V' (  $V \neq V'$ )
  - 3. No cycles and n-1 edges
  - 4. G is connected with n-1 edges

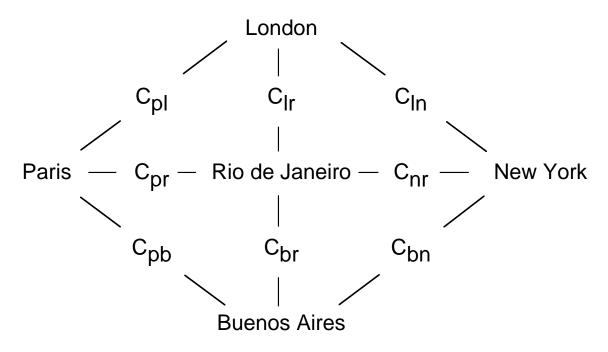


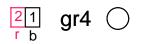
- Differences from regular trees:
  - 1. No identification of root
  - 2. No distinction between terminal and branch nodes

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### FREE SUBTREES

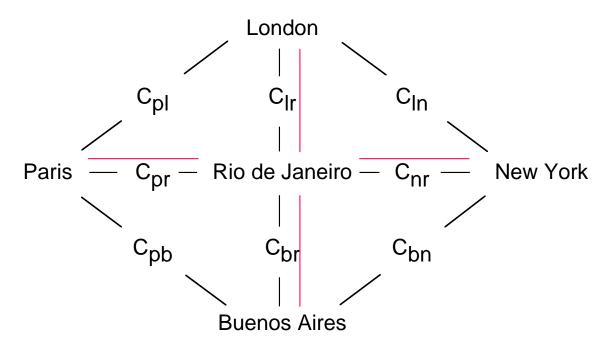
- Definition: set of edges such that all the vertices of the graph are connected to form a free tree
- Ex: distribution of telephone networks



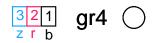


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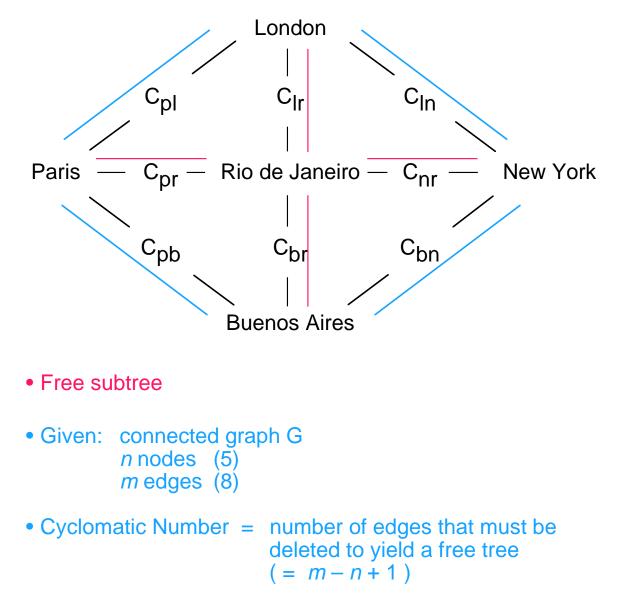


• Free subtree



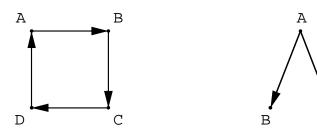
### FREE SUBTREES

- Definition: set of edges such that all the vertices of the graph are connected to form a free tree
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#### DIRECTED GRAPH

- Definition: graph with direction attached to the edges
- $(V_0, V_1, ..., V_n)$ : path of length *n* from  $V_0$  to  $V_n$
- Elementary path: all vertices are distinct
- Circuit: cycle (but can have length 1 or 2)
- Elementary Circuit: all vertices are distinct
- Indegree:
- Outdegree:
- Strongly Connected: path from any V to any V'
- Rooted: at least one V with paths to all  $V' \neq V$
- Note: strongly connected implies rooted but not vice versa



### DATA STRUCTURES FOR GRAPHS

- Must decide what information is to be accessible and with what ease
- Most important information conveyed by a graph is connectivity which is indicated by its edges
- Two choices
  - 1. vertex-based
    - keeps track of nodes connected to each node
    - can implement as array A of lists
      - a. one entry for each vertex p
      - b. A[p] is a list of all vertices P that are connected to p by virtue of the existence of an edge between p and q where  $q \in P$ (also known as an *adjacency list*)
  - 2. edge-based
    - keeps track of edges
    - usually represented as a list of pairs of form (p q) where there is an edge between vertices p and q
    - drawback: need to search entire set to determine edges connected to a particular vertex

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### ADJACENCY MATRIX

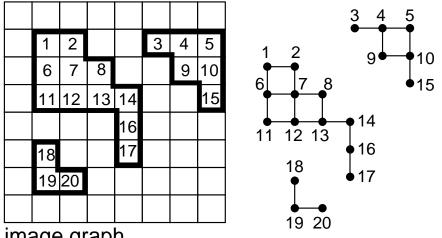
- Hybrid approach
- Good for representing a directed graph

- Somewhat wasteful of space as there is an entry for every possible edge even though the array is usually sparse
  - 1. in such cases, a vertex-based representation such as an adjacency list is more economical
  - 2. adjacency matrix is useful if want to detect if an edge exists between two vertices
    - cumbersome when using a list as need to search
- Useful if want to keep track of all vertices reachable from every vertex

• Ev·	Leftmost derivations		A	В	С	b	С	d
			0	1	0	1	0	0
	$A \rightarrow bC$	В	0	0	0	0	1	0
	$A \rightarrow Bd$	С	0	0	0	0	0	0
	A / Du	b	0	0	0	0	0	0
	$B \rightarrow c$	С	0	0	0	0	0	0
• Boolean matrices		0	0	0	0	0	0	
Dook								
1 + 1 1 + 0 0 + 0	$= 1   1 \cdot 0 =$	1 0	• 1	=	0 ·	• 0	=	0
• Cycle of length n $A_{ii}^n = 1$								

### CONNECTED GRAPH

- Def: there exists path between any two vertices of the graph
- Ex: binary image



- 1. image graph
  - image elements are vertices
  - horizontal and vertical adjacencies between image elements are edges
- 2. connected component labeling: determine separate regions of binary image
  - image graph is stored implicitly
  - easy to access adjacent vertices given location of a vertex
  - neither a vertex-based or edge-based representation; instead algorithms are based on them
    - 1. vertex-based implies need to follow connectivity
      - depth-first or seed-filling approach
      - many page faults if disk-resident data
    - 2. edge-based determines edges by examining image row-by-row
      - only need to access two rows simultaneously
      - good for disk-resident data
    - 3. both take  $\approx O(\text{number of image elements})$  time

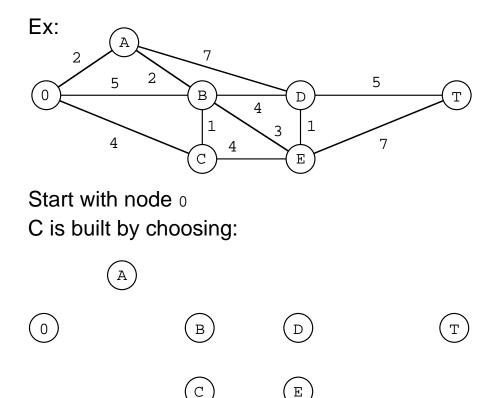


#### MINIMUM SPANNING TREE

- $\bullet$  Cost C<sub>ij</sub> associated with each edge from i to j
- Find the free subtree of G with minimum cost
- Solution:

C = connected nodes: initially { } U = unconnected nodes: initially { all nodes }

- 1. choose arbitrary node and place it in C
- select node in U that is closest to a node in C and add edge; move node from U to C; repeat until U is empty





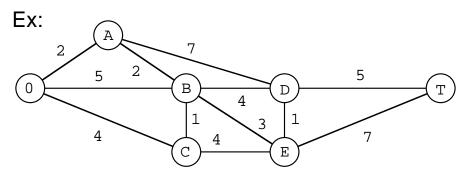
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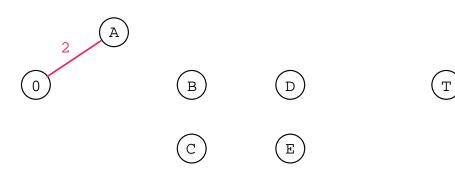
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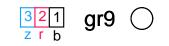
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Start with node 0 C is built by choosing: A



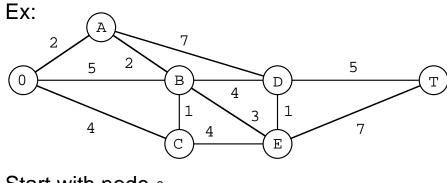


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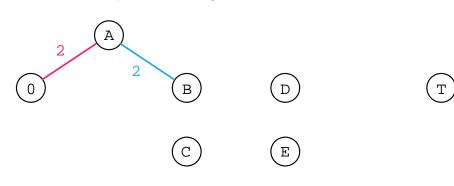
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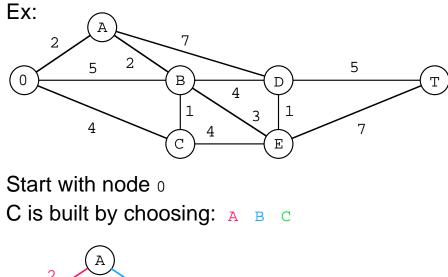
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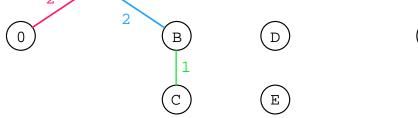
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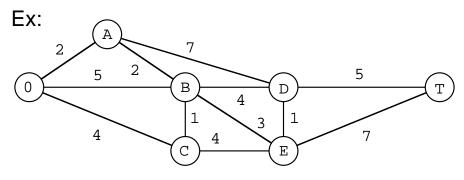
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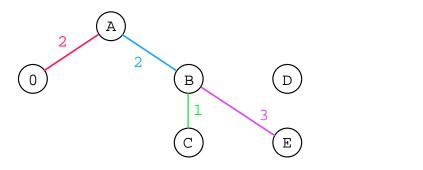
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Start with node o

C is built by choosing: A B C E





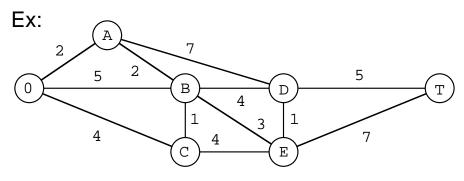
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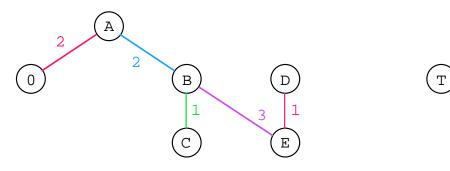
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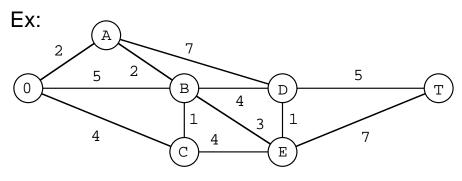
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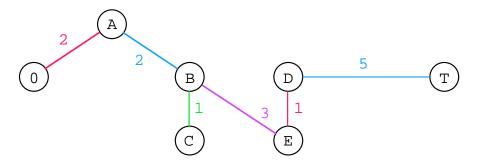
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C is built by choosing: A B C E D T



 Given node X0 in G find the shortest (cheapest) chain joining X0 with all the nodes of G

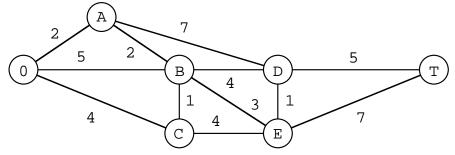
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- Solution:
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Ex: start at node o

А



Result:

good for designing flight schedules

0 B D T C E

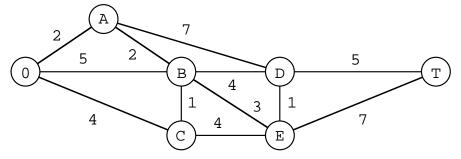
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21 r b

gr10 ( )

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Result: 0 (0,A)

Α good for designing flight schedules В D С Ε

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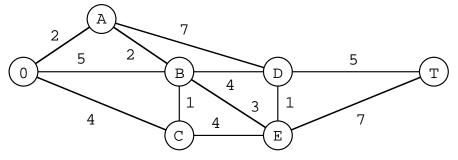
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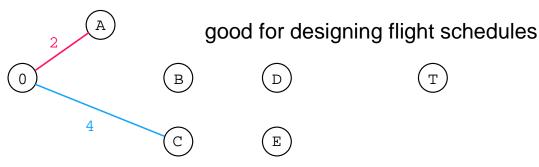


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Ex: start at node o



Result: 0 (0,A) A (0,C) or (A,B)



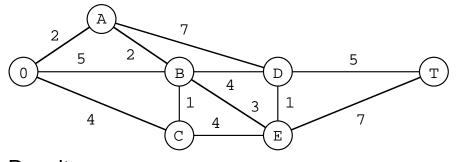
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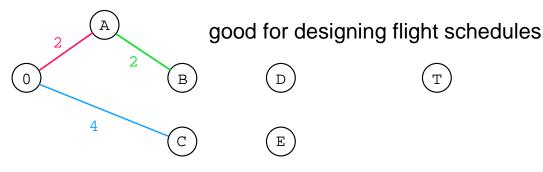
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Ex: start at node o



Result:  $O_{(0,A)} = A_{(0,C)} \text{ or } (A,B) = C_{(A,B)}$ 



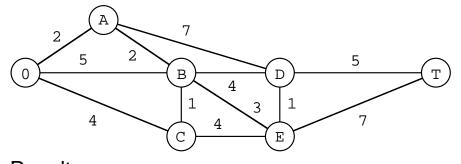
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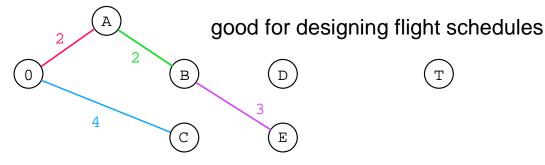
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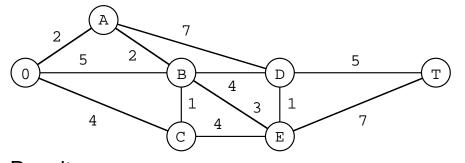


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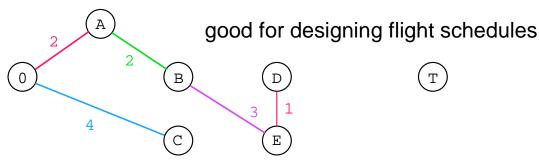
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Ex: start at node o



Result:  $O_{(0,A)} \xrightarrow{A_{(0,C)} \text{ or } (A,B)} C_{(A,B)} \xrightarrow{B_{(B,E)}} \underbrace{E_{(D,E)} \text{ or } (B,D)}$ 

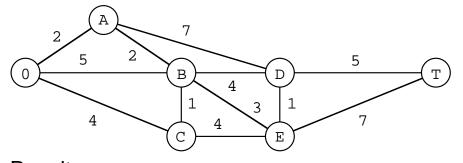


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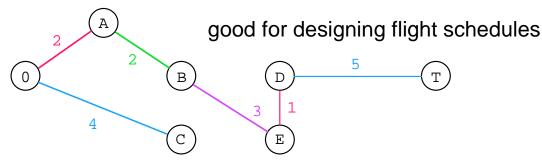
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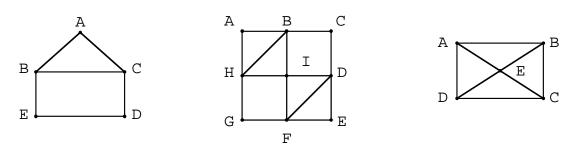


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### EULERIAN CHAINS AND CYCLES

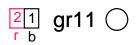
• When is it possible to trace a planar graph without tracing any edge more than once so that the pencil is never removed from the paper?



- Eulerian cycle = edges are all the edges of G (end up at point where started)
- Theorem: an Eulerian cycle exists for a connected graph G whenever all nodes have an even degree and vice versa
- Proof: one direction: if an Eulerian cycle exists, then each time we enter a node by one edge we leave by another edge

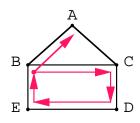
other direction: more complex

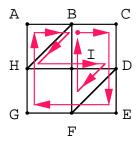
- Eulerian chain = joins nodes X and Y such that its edges are all the edges of G (end up at point different from starting point)
- Theorem: an Eulerian chain between nodes X and Y for a connected graph G exists if and only if nodes X and Y have odd degree and the remaining nodes have even degree



### EULERIAN CHAINS AND CYCLES

• When is it possible to trace a planar graph without tracing any edge more than once so that the pencil is never removed from the paper?







Eulerian chain

**Eulerian cycle** 

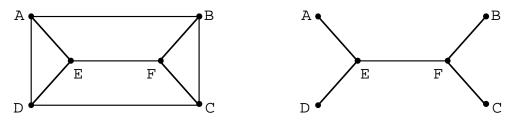
- Neither
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other direction: more complex

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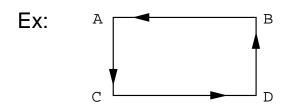
### HAMILTONIAN CHAINS AND CYCLES

• When is it possible for a salesman based in city X to cover his territory in such a way that he never visits a city more than once, where not every city is connected directly to another city?



Hamiltonian cycle = cycle where each vertex appears once (salesman ends up at home!) Hamiltonian chain = chain where each vertex appears once (salesman need not end up at home!)

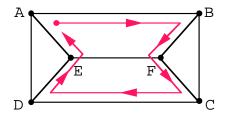
- Unlike Eulerian chains and cycles, no necessary and sufficient conditions exist for a graph G to have a Hamiltonian chain or cycle
- Sufficient condition:
  - Theorem: A simple graph with  $n \ge 3$  nodes such that for any distinct nodes X and Y not joined by an edge and degree (X) + degree (Y)  $\ge n$ , then G has a Hamiltonian cycle

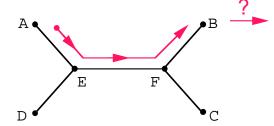


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Hamiltonian cycle existsNo HaHamiltonian chain exists(onlyHamiltonian cycle = A B F C D E A

No Hamiltonian chain or cycle (only one way from ADE to BCF) D E A

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- Unlike Eulerian chains and cycles, no necessary and sufficient conditions exist for a graph G to have a Hamiltonian chain or cycle
- Sufficient condition:
  - Theorem: A simple graph with  $n \ge 3$  nodes such that for any distinct nodes X and Y not joined by an edge and degree (X) + degree (Y)  $\ge n$ , then G has a Hamiltonian cycle

