Concurrent Servers Dec 2, 2009

Topics

- Limitations of iterative servers
- Process-based concurrent servers
- Event-based concurrent servers
- Threads-based concurrent servers

Administrivia

Course Review Web site is open

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Please review grades and let me know any problems

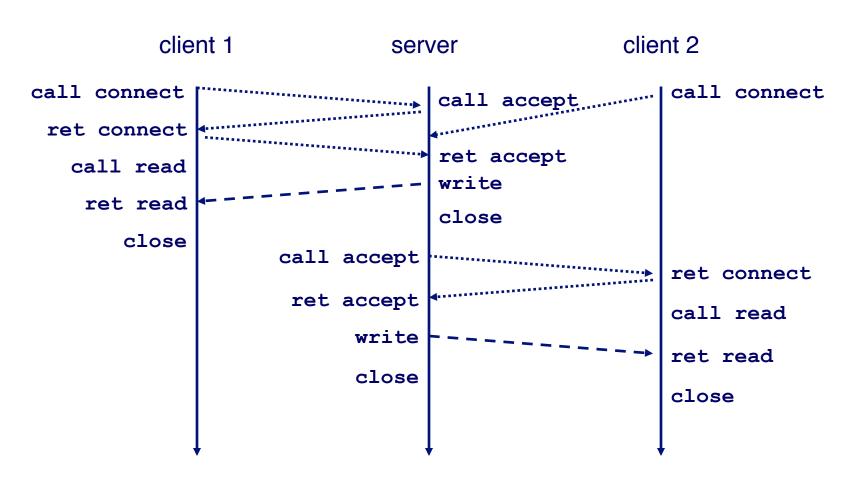
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Final Exam date and time is posted!

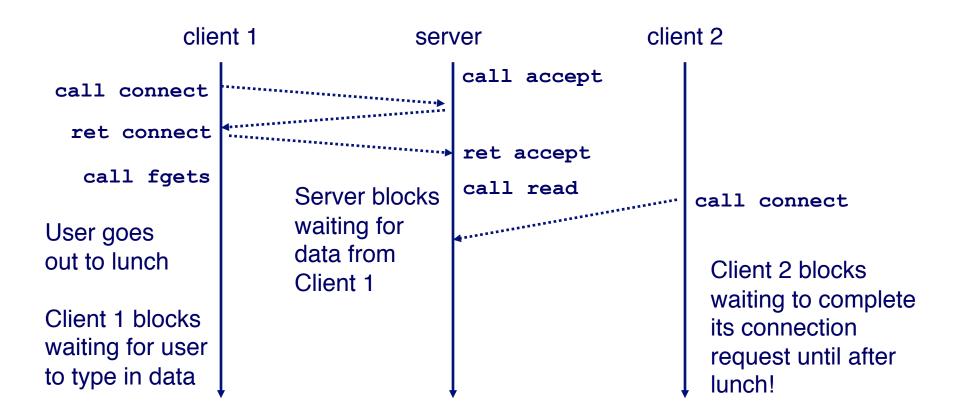
Lab 6 will be submitted via the submit server- details to follow.

Iterative Servers

Iterative servers process one request at a time.



Fundamental Flaw of Iterative Servers

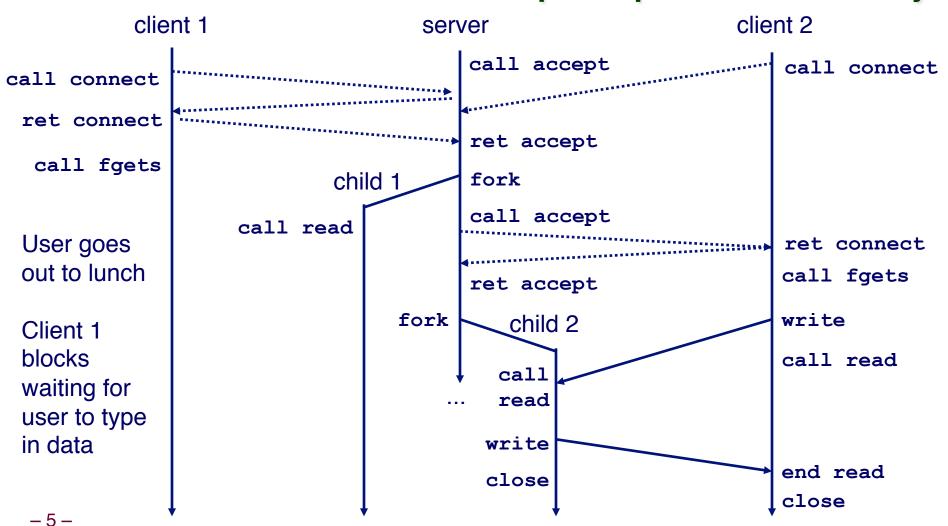


Solution: use concurrent servers instead.

■ Concurrent servers use multiple concurrent flows to serve multiple clients at the same time.

Concurrent Servers

Concurrent servers handle multiple requests concurrently.



Three Basic Mechanisms for Creating Concurrent Flows

1. Processes

- Kernel automatically interleaves multiple logical flows.
- Each flow has its own private address space.

2. I/O multiplexing with select()

- User manually interleaves multiple logical flows.
- Each flow shares the same address space.
- **■** Popular for high-performance server designs.

3. Threads

- Kernel automatically interleaves multiple logical flows.
- **■** Each flow shares the same address space.
- Hybrid of processes and I/O multiplexing!

Process-Based Concurrent Server

```
/*
 * echoserverp.c - A concurrent echo server based on processes
 * Usage: echoserverp <port>
 */
#include <ics.h>
#define BUFSIZE 1024
void echo(int connfd);
void handler(int sig);
int main(int argc, char **argv) {
  int listenfd, connfd;
  int portno;
  struct sockaddr in clientaddr;
  int clientlen = sizeof(struct sockaddr in);
  if (argc != 2) {
    fprintf(stderr, "usage: %s <port>\n", argv[0]);
    exit(0);
  portno = atoi(argv[1]);
  listenfd = open listenfd(portno);
```

Process-Based Concurrent Server (cont)

Process-Based Concurrent Server (cont)

```
/* handler - reaps children as they terminate */
void handler(int sig) {
  pid_t pid;
  int stat;

  while ((pid = waitpid(-1, &stat, WNOHANG)) > 0)
   ;
  return;
}
```

Implementation Issues With Process-Based Designs

Server should restart accept call if it is interrupted by a transfer of control to the SIGCHLD handler

- Not necessary for systems with POSIX signal handling.
 - Our Signal wrapper tells kernel to automatically restart accept
- Required for portability on some older Unix systems.

Server must reap zombie children

to avoid fatal memory leak.

Server must close its copy of connfd.

- Kernel keeps reference for each socket.
- After fork, refcnt(connfd) = 2.
- Connection will not be closed until refcnt (connfd) = 0.

Pros and Cons of Process-Based Designs

- + Handles multiple connections concurrently
- + Clean sharing model
 - descriptors (no)
 - file tables (yes)
 - global variables (no)
- + Simple and straightforward.
- Additional overhead for process control.
- Nontrivial to share data between processes.
 - Requires IPC (interprocess communication) mechanisms
 FIFO's (named pipes), System V shared memory and semaphores

I/O multiplexing provides more control with less ____overhead...

Event-Based Concurrent Servers Using I/O Multiplexing

Maintain a pool of connected descriptors.

Repeat the following forever:

- Use the Unix select function to block until:
 - (a) New connection request arrives on the listening descriptor.
 - (b) New data arrives on an existing connected descriptor.
- If (a), add the new connection to the pool of connections.
- If (b), read any available data from the connection
 - Close connection on EOF and remove it from the pool.

The select Function

select() sleeps until one or more file descriptors in the set readset are ready for reading.

```
#include <sys/select.h>
int select(int maxfdp1, fd_set *readset, NULL, NULL, NULL);
```

readset

- Opaque bit vector (max FD_SETSIZE bits) that indicates membership in a descriptor set.
- If bit k is 1, then descriptor k is a member of the descriptor set.

maxfdp1

- Maximum descriptor in descriptor set plus 1.
- Tests descriptors 0, 1, 2, ..., maxfdp1 1 for set membership.

select() returns the number of ready descriptors and sets each bit of readset to indicate the ready status of its corresponding descriptor.

Macros for Manipulating Set Descriptors

```
void FD_ZERO(fd_set *fdset);
    ■ Turn off all bits in fdset.
void FD_SET(int fd, fd_set *fdset);
    ■ Turn on bit fd in fdset.
void FD CLR(int fd, fd set *fdset);
    ■ Turn off bit fd in fdset.
int FD ISSET(int fd, *fdset);
    Is bit fd in fdset turned on?
```

select Example

```
/*
* main loop: wait for connection request or stdin command.
* If connection request, then echo input line
* and close connection. If stdin command, then process.
*/
printf("server> ");
fflush(stdout);
while (notdone) {
   /*
    * select: check if the user typed something to stdin or
    * if a connection request arrived.
    */
   FD SET(listenfd, &readfds); /* add socket fd */
   FD SET(0, &readfds); /* add stdin fd (0) */
   Select(listenfd+1, &readfds, NULL, NULL, NULL);
```

select Example (cont)

First we check for a pending event on stdin.

```
/* if the user has typed a command, process it */
if (FD ISSET(0, &readfds)) {
   fgets(buf, BUFSIZE, stdin);
   switch (buf[0]) {
   case 'c': /* print the connection count */
      printf("Received %d conn. requests so far.\n", connectcnt);
     printf("server> ");
      fflush(stdout);
     break:
   case 'q': /* terminate the server */
      notdone = 0;
     break:
   default: /* bad input */
      printf("ERROR: unknown command\n");
     printf("server> ");
      fflush(stdout);
```

select Example (cont)

Next we check for a pending connection request.

Event-based Concurrent Echo Server

```
* echoservers.c - A concurrent echo server based on select
*/
#include "csapp.h"
typedef struct { /* represents a pool of connected descriptors */
  fd set read set; /* set of all active descriptors */
  fd set ready set; /* subset of descriptors ready for reading */
  int clientfd[FD SETSIZE]; /* set of active descriptors */
  rio t clientrio[FD SETSIZE]; /* set of active read buffers */
} pool;
int byte cnt = 0; /* counts total bytes received by server */
```

```
int main(int argc, char **argv)
    int listenfd, connfd, clientlen = sizeof(struct sockaddr in);
    struct sockaddr in clientaddr;
    static pool pool;
    listenfd = Open listenfd(argv[1]);
    init pool(listenfd, &pool);
   while (1) {
        pool.ready set = pool.read set;
        pool.nready = Select(pool.maxfd+1, &pool.ready set,
                             NULL, NULL, NULL);
        if (FD ISSET(listenfd, &pool.ready set)) {
            connfd = Accept(listenfd, (SA *)&clientaddr,&clientlen);
            add client(connfd, &pool);
        check clients(&pool);
```

```
void add client(int connfd, pool *p) /* add connfd to pool p */
   int i;
   p->nready--;
   for (i = 0; i < FD SETSIZE; i++) /* Find available slot */
        if (p->clientfd[i] < 0) {</pre>
           p->clientfd[i] = connfd;
            Rio readinitb(&p->clientrio[i], connfd);
            FD SET(connfd, &p->read set); /* Add desc to read set */
            if (connfd > p->maxfd) /* Update max descriptor num */
               p->maxfd = connfd;
            if (i > p->maxi) /* Update pool high water mark */
                p->maxi = i;
            break:
    if (i == FD SETSIZE) /* Couldn't find an empty slot */
        app error("add client error: Too many clients");
```

```
void check clients(pool *p) { /* echo line from ready descs in pool p */
    int i, connfd, n;
    char buf[MAXLINE];
    rio t rio;
    for (i = 0; (i \le p-)maxi) && (p-)nready > 0); i++) {
        connfd = p->clientfd[i];
        rio = p->clientrio[i];
        /* If the descriptor is ready, echo a text line from it */
        if ((connfd > 0) && (FD ISSET(connfd, &p->ready set))) {
            p->nready--;
            if ((n = Rio readlineb(&rio, buf, MAXLINE)) != 0) {
                byte cnt += n;
                Rio writen(connfd, buf, n);
            }
            else {/* EOF detected, remove descriptor from pool */
                Close(connfd);
                FD CLR(connfd, &p->read set);
                p->clientfd[i] = -1;
```

Pro and Cons of Event-Based Designs

- + One logical control flow.
- + Can single-step with a debugger.
- + No process or thread control overhead.
 - Design of choice for high-performance Web servers and search engines.
- Significantly more complex to code than process- or thread-based designs.
- Can be vulnerable to denial of service attack
 - How?

Threads provide a middle ground between processes and I/O multiplexing...

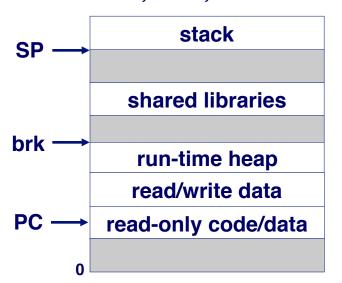
Traditional View of a Process

Process = process context + code, data, and stack

Process context

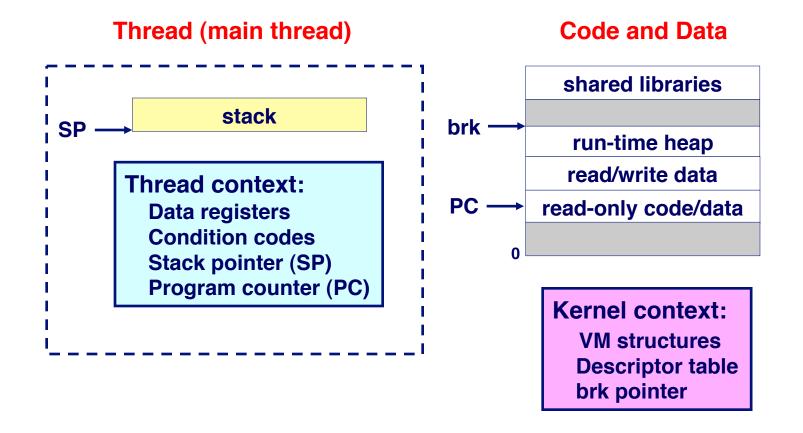
Program context:
Data registers
Condition codes
Stack pointer (SP)
Program counter (PC)
Kernel context:
VM structures
Descriptor table
brk pointer

Code, data, and stack



Alternate View of a Process

Process = thread + code, data, and kernel context



A Process With Multiple Threads

Multiple threads can be associated with a process

- Each thread has its own logical control flow (sequence of PC values)
- Each thread shares the same code, data, and kernel context
- Each thread has its own thread id (TID)

Thread 1 (main thread)

Shared code and data

Thread 2 (peer thread)

stack 1

Thread 1 context:

Data registers

Condition codes

SP1

PC1

run-time heap
read/write data
read-only code/data

Kernel context:
VM structures
Descriptor table
brk pointer

stack 2

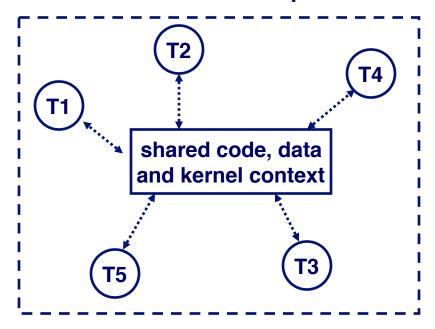
Thread 2 context:
Data registers
Condition codes
SP2
PC2

Logical View of Threads

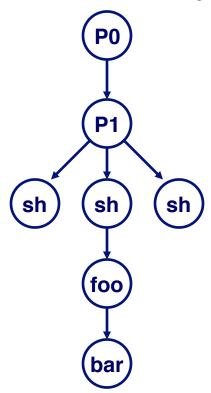
Threads associated with a process form a pool of peers.

Unlike processes which form a tree hierarchy

Threads associated with process foo



Process hierarchy



Concurrent Thread Execution

Two threads run concurrently (are concurrent) if their logical flows overlap in time.

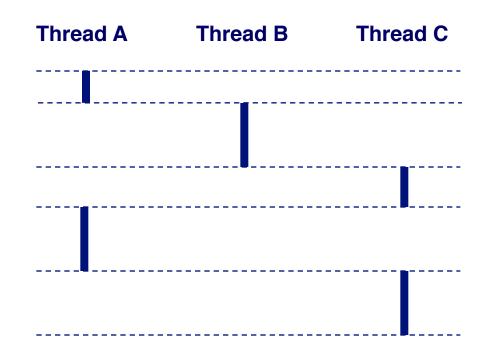
Otherwise, they are sequential.

Examples:

■ Concurrent: A & B, A&C

Sequential: B & C

Time



Threads vs. Processes

How threads and processes are similar

- Each has its own logical control flow.
- Each can run concurrently.
- Each is context switched.

How threads and processes are different

- Threads share code and data, processes (typically) do not.
- Threads are somewhat less expensive than processes.
 - Process control (creating and reaping) is twice as expensive as thread control.
 - Linux/Pentium III numbers:
 - » ~20K cycles to create and reap a process.
 - » ~10K cycles to create and reap a thread.

Posix Threads (Pthreads) Interface

Pthreads: Standard interface for ~60 functions that manipulate threads from C programs.

- Creating and reaping threads.
 - pthread_create
 - pthread join
- Determining your thread ID
 - pthread_self
- Terminating threads
 - pthread_cancel
 - pthread exit
 - exit [terminates all threads], ret [terminates current thread]
- Synchronizing access to shared variables
 - pthread_mutex_init
 - pthread_mutex_[un]lock
 - pthread cond init
 - pthread cond [timed]wait

The Pthreads "hello, world" Program

```
* hello.c - Pthreads "hello, world" program
 */
                                                     Thread attributes
#include "csapp.h"
                                                      (usually NULL)
void *thread(void *varqp);
                                                     Thread arguments
int main() {
                                                         (void *p)
  pthread t tid;
  Pthread create(&tid, NULL, thread, NULL);
  Pthread join(tid, NULL);
  exit(0);
                                                     return value
                                                      (void **p)
/* thread routine */
void *thread(void *varqp) {
  printf("Hello, world!\n");
  return NULL;
```

Execution of Threaded"hello, world"

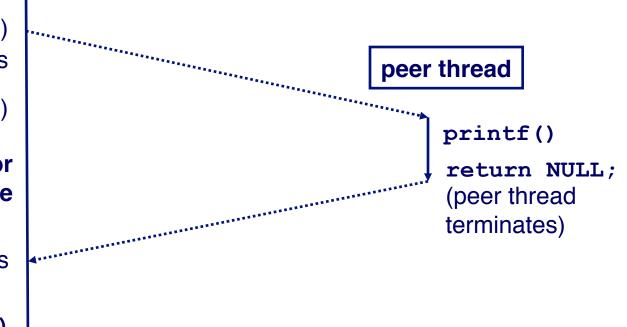
main thread

call Pthread_create()
Pthread_create() returns
call Pthread_join()

main thread waits for peer thread to terminate

Pthread_join() returns

exit()
terminates
main thread and
any peer threads



Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv)
    int listenfd, *connfdp, port, clientlen;
    struct sockaddr in clientaddr;
   pthread t tid;
    if (argc != 2) {
        fprintf(stderr, "usage: %s <port>\n", argv[0]);
        exit(0);
    port = atoi(argv[1]);
    listenfd = open listenfd(port);
    while (1) {
        clientlen = sizeof(clientaddr);
        connfdp = Malloc(sizeof(int));
        *connfdp = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        Pthread create(&tid, NULL, thread, connfdp);
```

Thread-Based Concurrent Server (cont)

```
* thread routine */
void *thread(void *vargp)
{
    int connfd = *((int *)vargp);

    Pthread_detach(pthread_self());
    Free(vargp);

    echo_r(connfd); /* reentrant version of echo() */
    Close(connfd);
    return NULL;
}
```

Issues With Thread-Based Servers

Must run "detached" to avoid memory leak.

- At any point in time, a thread is either *joinable* or *detached*.
- Joinable thread can be reaped and killed by other threads.
 - must be reaped (with pthread_join) to free memory resources.
- Detached thread cannot be reaped or killed by other threads.
 - resources are automatically reaped on termination.
- Default state is joinable.
 - use pthread_detach (pthread_self()) to make detached.

Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of connfd to the thread routine?
 - Pthread_create(&tid, NULL, thread, (void *)
 &connfd);

All functions called by a thread must be thread-safe

(next lecture)

Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
 - e.g., logging information, file cache.
- + Threads are more efficient than processes.

- --- Unintentional sharing can introduce subtle and hardto-reproduce errors!
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads.
 - (next lecture)